



Intel® Open Source HD Graphics and Intel Iris™ Plus Graphics

Programmer's Reference Manual

For the 2016 - 2017 Intel Core™ Processors, Celeron™ Processors,
and Pentium™ Processors based on the "Kaby Lake" Platform

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Introduction

The hardware supports three engines:

- The Render command streamer interfaces to 3D/IE and display streams.
- The Media command streamer interfaces to the fixed function media.
- The Blitter command streamer interfaces to the blit commands.

Software interfaces of all three engines are very similar and should only differ on engine-specific functionality.

Memory Views Glossary

Term	Definition
IOMMU	I/O Memory Mapping unit
SVM	Shared Virtual Memory, implies the same virtual memory view between the IA cores and processor graphics.
Page Walker (GAM)	GFX page walker which handles page level translations between GFX virtual memory to physical memory domain.

GPU Memory Interface

GPU memory interface functions are divided into 4 different major sections:

- Global Arbitration
- Memory Interface Functions
- Page Translations (GFX Page Walker)
- Ring Interface Functions (GTI)

GT Interface functions are covered at a different chapter/HAS and not part of this documentation. The following documentation is meant for GFX arbitration paths in accessing to memory/cache interfaces and page translations and page walker functions.



Global Arbitration

The global memory arbitration fabric is meant to be a hierarchal memory fabric where memory accesses from different stages of the pipeline are consolidated to a single interface towards GT's connection to CPU's ring interface.

The arbitration on the fabric is programmable via a simple per pipeline stage priority levels.

Programming Note	
Context:	Global Memory Arbitration
Arbitration allows 4 levels of arbitration where each pipeline level can be put into these 4 levels. Each consolidation stage simply follows the 4-level arbitration with grace periods to allow ahead of the pipeline to get a higher share of the memory bandwidth.	

The final arbitration takes places in GAM between parallel compute engines. Each engine (in some cases major pipeline stages are also separated, i.e. Z vs Color vs L3 vs Fixed Functions) gets a count in a grace period where its accesses are counted against a global pool. If a particular engine (or pipeline stage) exhausts its max allowed, it is dropped to a lower priority and goes to fixed pipeline based prioritization. Once all counts are expired, the grace period completes and resets.

The count values are programmable via MMIO (i.e. *_MAX_REQ_COUNT) registers with defaults favoring the pipeline order.

GFX MMIO – MCHBAR Aperture

Address: 140000h – 147FFFh

Default Value: Same as MCHBAR

Access: Aligned Word, Dword, or Qword Read/Write

This range defined in the graphics MMIO range is an alias with which graphics driver can read and write registers defined in the MCHBAR MMIO space claimed through Device #0. Attributes for registers defined within the MCHBAR space are preserved when the same registers are accessed via this space. Registers that the graphics driver requires access to are Rank Throttling, GMCH Throttling, Thermal Sensor, etc.

The Alias functions work for MMIO access from the CPU only. A command stream load register immediate will drop the data, and the store register immediate will return all Zeroes.

Graphics MMIO registers can be accessed through MMIO BARs in function #0 and function #1 in Device #2. The aliasing mechanism is turned off if memory access to the corresponding function is turned off via software or in certain power states.

Please refer to applicable EDS documentation of offset 140000h – 147FFFh for details of this register's format and behavior.



Graphics Memory Interface Functions

The major role of an integrated graphics device's Memory Interface (MI) function is to provide various client functions access to "graphics" memory used to store commands, surfaces, and other information used by the graphics device. This chapter describes the basic mechanisms and paths by which graphics memory is accessed.

Information not presented in this chapter includes:

- Microarchitectural and implementation-dependent features (e.g., internal buffering, caching, and arbitration policies).
- MI functions and paths specific to the operation of external (discrete) devices attached via external connections.
- MI functions essentially unrelated to the operation of the internal graphics devices, .e.g., traditional "chipset functions"
- GFX Page Walker and GT interface functions are covered in different chapters.

Graphics Memory Clients

The MI function provides memory access functionality to a number of external and internal graphics memory *clients*, as described in the table below.

Graphics Memory Clients

MI Client	Access Modes
Host Processor	Read/Write of Graphics Operands located in Main Memory. Graphics Memory is accessed using Device 2 Graphics Memory Range Addresses
External PEG Graphics Device	Write-Only of Graphics Operands located in Main Memory via the Graphics Aperture. (This client is not described in this chapter).
Peer PCI Device	Write-Only of Graphics Operands located in Main Memory. Graphics Memory is accessed using Device 2 Graphics Memory Range Addresses (i.e., mapped by GTT). <i>Note that DMI access to Graphics registers is not supported.</i>
Coherent Read/Write (internal)	Internally-generated snooped reads/writes.
Command Stream (internal)	DMA Read of graphics commands and related graphics data.
Vertex Stream (internal)	DMA Read of indexed vertex data from Vertex Buffers by the 3D Vertex Fetch (VF) Fixed Function.
Instruction/State Cache (internal)	Read of pipelined 3D rendering state used by the 3D/Media Functions and instructions executed by the EUs.
Render Cache (internal)	Read/Write of graphics data operated upon by the graphics rendering engines (Blit, 3D, MPEG, etc.) Read of render surface state.
Sampler Cache (internal)	Read of texture (and other sampled surface) data stored in graphics memory.



MI Client	Access Modes
Display/Overlay Engines (internal)	Read of display, overlay, cursor and VGA data.
Media Engines	Read and write of media content and media processing.
uController	Read/Write (DMA) functions for u-controller and scheduler.

Graphics Memory Addressing Overview

The Memory Interface function provides access to graphics memory (GM) clients. It accepts memory addresses of various types, performs a number of optional operations along *address paths*, and eventually performs reads and writes of graphics memory data using the resultant addresses. The remainder of this subsection will provide an overview of the graphics memory clients and address operations.

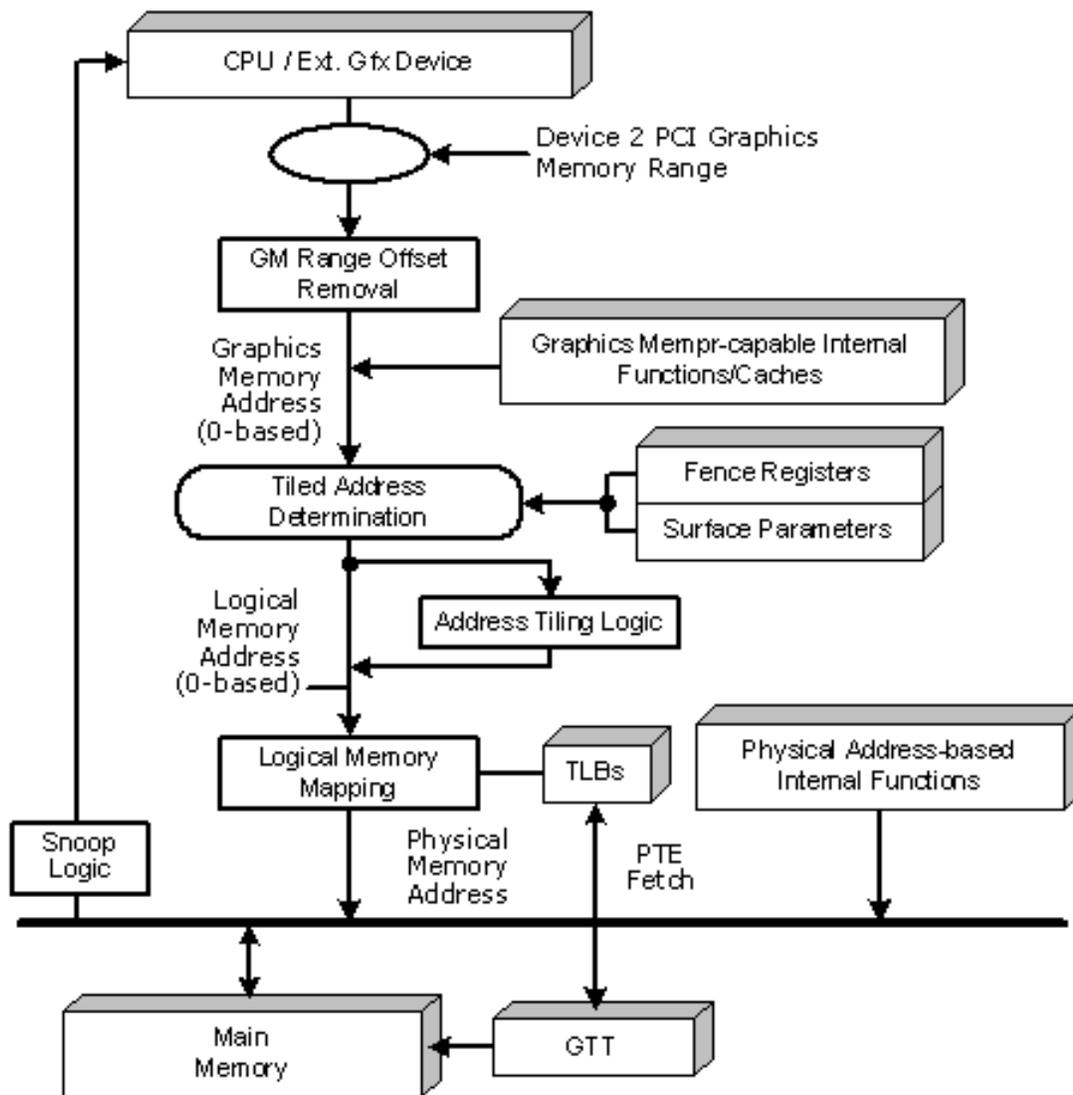
Graphics Address Path

Graphics Address Path shows the internal graphics memory address path, connection points, and optional operations performed on addresses. Externally-supplied addresses are normalized to zero-based *Graphics Memory (GM) addresses* (GM_Address). If the GM address is determined to be a tiled address (based on inclusion in a fenced region or via explicit surface parameters), *address tiling* is performed. At this point the address is considered a *Logical Memory address*, and is translated into a *Physical Memory address* via the GTT and associated TLBs. The physical memory location is then accessed.

CPU accesses to graphics memory are sent back on the ring to snoop. Hence pages that are mapped cacheable in the GTT will be coherent with the CPU cache if accessed through graphics memory aperture.



Graphics Memory Paths



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The remainder of this chapter describes the basic features of the graphics memory address pipeline, namely Address Tiling, Logical Address Mapping, and Physical Memory types and allocation considerations.



Graphics Memory Address Spaces

The *Graphics Memory Address Spaces* table lists the five supported Graphics Memory Address Spaces. Note that the Graphics Memory Range Removal function is automatically performed to transform system addresses to internal, zero-based Graphics Addresses.

Graphics Memory Address Types

Address Type	Description	Range	Gen9
GMADR	Address range allocated via the Device 2 (integrated graphics device) GMADR register. The processor and other peer (DMI) devices utilize this address space to read/write graphics data that resides in Main Memory. This address is internally converted to a GM_Address.	This is a 4 GB BAR above physical memory.	128 MB, 256 MB, 512 MB, 1GB, 2GB, 4GB
GTTMMADR	The combined Graphics Translation Table Modification Range and Memory Mapped Range. The range requires 16 MB combined for MMIO and Global GTT aperture, with 8MB of that used by MMIO and 8MB used by GTT. GTTADR will begin at GTTMMADR + 8MB while the MMIO base address will be the same as GTTMMADR. For the Global GTT, this range is defined as a memory BAR in graphics device config space. It is an alias into which software is required to write Page Table Entry values PTEs. Software may read PTE values from the global Graphics Translation Table GTT. PTEs cannot be written directly into the global GTT memory area.	This is a 16MB BAR above physical memory.	16 MB (2 MB MMIO + 6 MB reserved + 8 MB GGTT)
GSM	GTT Stolen Memory. It is an 8 MB (max) region taken out of physical memory to store the Global GTT entries for page translations specific to GFX driver use. It is accessible via GTTMMADR from the CPU path however GPU/DE can access the same region directly.	This is an 8 MB region in physical memory not visible to OS.	1 MB, 2 MB, 4 MB, 8 MB
DSM	Data stolen memory, the size is determined with GMS filed (8 bits) with MAX size of 4 GB. This is a stolen memory which can be accessed via GMADR for CPU and directly for GPU/DE. Size is programmable with 32 MB multiplier. First 4KB of DSM has to be reserved for GFX hardware use.	This is a max of 4 GB stolen physical memory for GFX data structures.	0 MB, 32 MB, 64 MB, 96 MB, ...4096MB

Next level breakdown for GTTMMADR is given below.

Software is allowed to use range x17_0000 to x17_FFFF as the Null range.



Address Tiling Function Introduction

When dealing with memory operands (e.g., graphics surfaces) that are inherently rectangular in nature, certain functions within the graphics device support the storage/access of the operands using alternative (tiled) memory formats to increase performance. This section describes these memory storage formats, why and when they should be used, and the behavioral mechanisms within the device to support them.

Legacy Tiling Modes:

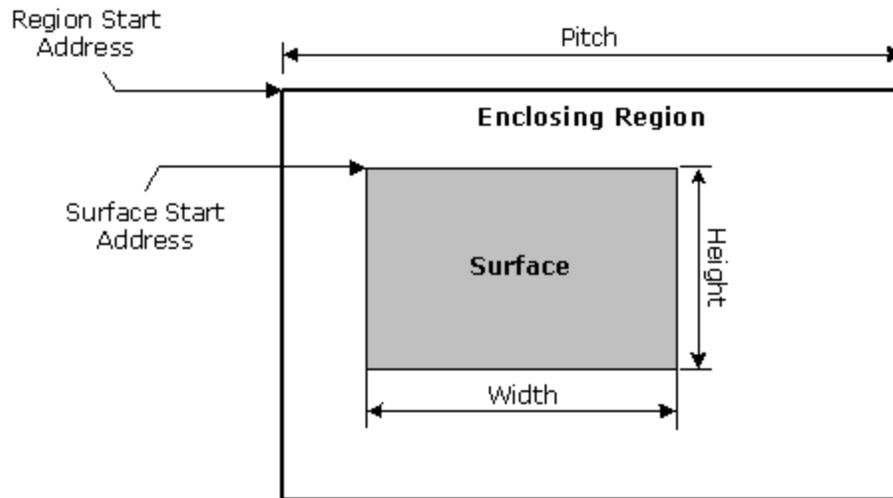
- **TileY**: Used for most tiled surfaces when **TR_MODE**=TR_NONE.
- **TileX** : Used primarily for display surfaces.
- **TileW**: Used for Stencil surfaces.

Programming Note	
Context:	Address Tiling Function
<p>Tiled Resource Tiling Modes</p> <ul style="list-style-type: none"> • TileYF: 4KB tiling mode based on TileY • TileYS: 64KB tiling mode based on TileY <p>These modes are based on 4KB and 64KB tiles. The 64KB tile is made up of a 4x4 matrix of 4KB tiles. The 4KB tiles in general have a different layout as compared to the legacy modes, with the sub-mode defining the layout within the 4KB tile. The sub-modes are determined by the bits per element of the surface format. The Tiled Resource Mode field in SURFACE_STATE is used to select the new modes.</p> <p>Tiled surface base addresses must be tile aligned (64KB aligned for TileYS, 4KB aligned for all other tile modes). For 1D surfaces, the base address must be 64KB aligned if Tiled Resource Mode is TRMODE_64KB, and 4KB aligned if Tiled Resource Mode is TRMODE_4KB. An exception to this tile alignment is when a SURFACE_STATE describes a single MIP within the MIP Tail of another surface, using a 64-bit or 128-bit Surface Format—then Surface Base Address can refer directly to the given MIP (e.g. to write to a non-renderable Surface Format by re-describing as an alternative surface).</p>	

Linear vs Tiled Storage

Regardless of the memory storage format, “rectangular” memory operands have a specific *width* and *height*, and are considered as residing within an enclosing rectangular region whose width is considered the *pitch* of the region and surfaces contained within. Surfaces stored within an enclosing region must have widths less than or equal to the region pitch (indeed the enclosing region may coincide exactly with the surface). *Rectangular Memory Operand Parameters* shows these parameters.

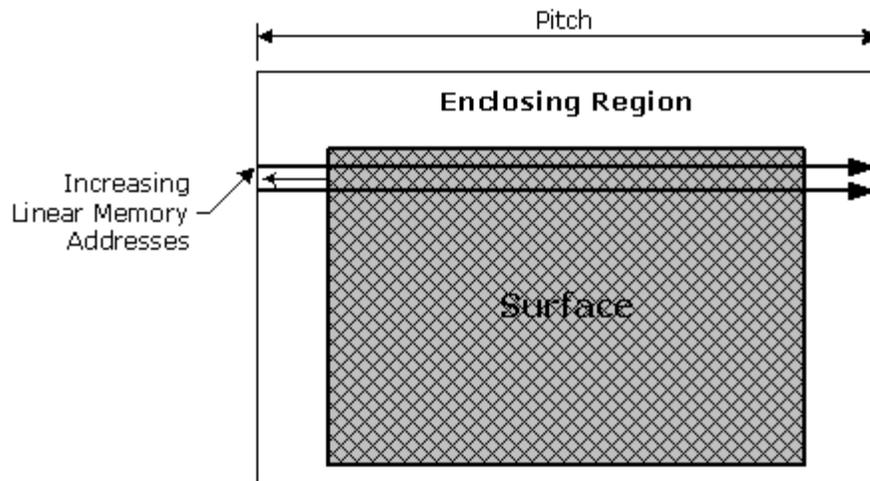
Rectangular Memory Operand Parameters



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The simplest storage format is the *linear* format (see *Linear Surface Layout*), where each row of the operand is stored in sequentially increasing memory locations. If the surface width is less than the enclosing region’s pitch, there will be additional memory storage between rows to accommodate the region’s pitch. The pitch of the enclosing region determines the distance (in the memory address space) between vertically-adjacent operand elements (e.g., pixels, texels).

Linear Surface Layout



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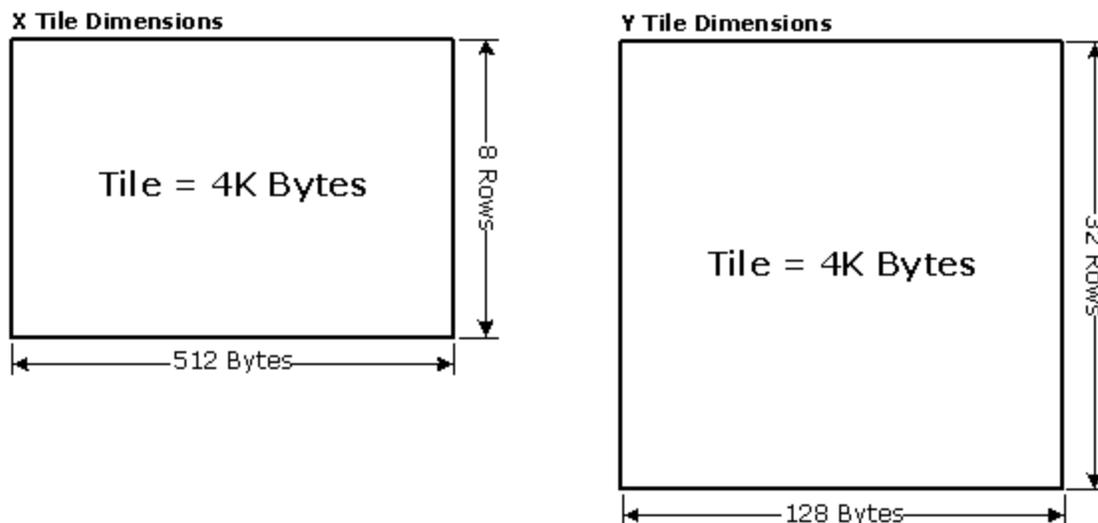
The linear format is best suited for 1-dimensional row-sequential access patterns (e.g., a display surface where each scanline is read sequentially). Here the fact that one object element may reside in a different memory page than its vertically-adjacent neighbors is not significant; all that matters is that horizontally-adjacent elements are stored contiguously. However, when a device function needs to access a 2D subregion within an operand (e.g., a read or write of a 4x4 pixel span by the 3D renderer, a read of a 2x2 texel block for bilinear filtering), having vertically-adjacent elements fall within different memory pages is to be avoided, as the page crossings required to complete the access typically incur increased memory latencies (and therefore lower performance).

One solution to this problem is to divide the enclosing region into an array of smaller rectangular regions, called memory *tiles*. Surface elements falling within a given tile will all be stored in the same physical memory page, thus eliminating page-crossing penalties for 2D subregion accesses within a tile and thereby increasing performance.

Tiles have a fixed 4KB size and are aligned to physical DRAM page boundaries. They are either 8 rows high by 512 bytes wide or 32 rows high by 128 bytes wide (see *Memory Tile Dimensions*). Note that the dimensions of tiles are irrespective of the data contained within – e.g., a tile can hold twice as many 16-bit pixels (256 pixels/row x 8 rows = 2K pixels) than 32-bit pixels (128 pixels/row x 8 rows = 1K pixels).



Memory Tile Dimensions

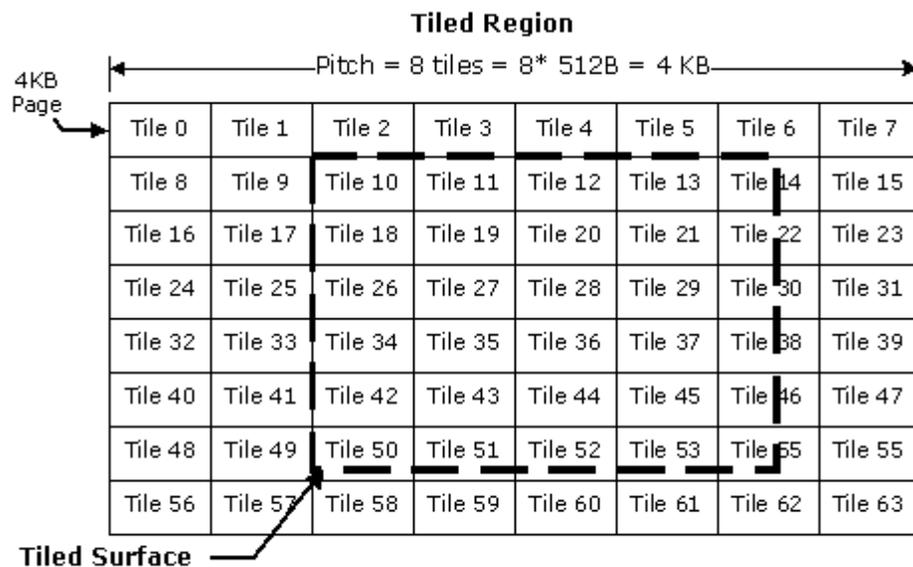


B6692-01

The pitch of a tiled enclosing region must be an integral number of tile widths. The 4KB tiles within a tiled region are stored sequentially in memory in row-major order.

The *Tiled Surface Layout* figure shows an example of a tiled surface located within a tiled region with a pitch of 8 tile widths (512 bytes * 8 = 4KB). Note that it is the *enclosing region* that is divided into tiles – the surface is not necessarily aligned or dimensioned to tile boundaries.

Tiled Surface Layout



B6693-01



Auxiliary Surfaces For Sampled Tiled Resources

For surfaces which are defined as Tiled Resources (TileYs or TileYf format), there may be auxiliary surfaces which are associated with the surface (e.g. HiZ, CCS or MCS). These auxiliary surfaces, while actually not defined as TileYs or TileYf will behave like tiled resources from the hardware perspective. It is possible for software to map and unmap tiles of auxiliary surfaces as tiles of the associated surface are mapped and unmapped. Below is a description how sampling to the mapped/unmapped tile resources is handled for the associated auxiliary surface. Normally, sampling unmapped tiles will return a NULL response to the requesting agent.

HiZ

A tile of HiZ data must be mapped to memory whenever any depth surface (Z) pixels associated with the HiZ tile are mapped. When all Z pixels associated with a HiZ tile are unmapped, the HiZ tile may be mapped or unmapped. Below is a table showing the responses for sampling to mapped and unmapped depth surfaces.

Responses for Sampling to A Depth-Surface Tiled Resource

Depth Surface Mapping	HiZ Surface Mapping	Sample Response
Mapped	Mapped	Normal Sample Response
Mapped	Unmapped	Undefined
Unmapped	Mapped	NULL Response
Unmapped	Unmapped	NULL Response

A "NULL Response" means that the sample returned will be all 0's and the **Null Pixel Mask** (if requested) will indicate the depth pixel is Null.

CCS

A tile of CCS (Color Control Surface) must be mapped to memory whenever color surface pixels associated with the CCS tile are mapped. When all color pixels associated with a CCS tile are unmapped, the CCS may be mapped or unmapped. CCS is used to indicate that the color surface is losslessly compressed. Below is a table showing the responses for sampling to mapped and unmapped.

Responses for Sampling to a Losslessly Compressed Color Surface That is a Tiled Resource

Color Surface Mapping	CCS Surface Mapping	Sample Response
Mapped	Mapped	Normal Response
Mapped	Unmapped	Undefined
Unmapped	Mapped	NULL Response
Unmapped	Unmapped	NULL Response

A "NULL Response" means that the sample returned will be all 0's and the **Null Pixel Mask** (if requested) will indicate the depth pixel is Null.



MCS

A tile of MCS(Multi-Sample Control Surface) must be mapped to memory whenever MSAA surface pixels associated with the CCS tile are mapped. When all MSAA pixels associated with a MCS tile are unmapped, the MCS may be mapped or unmapped. Below is a table showing the responses for sampling to mapped and unmapped.

Responses for Sampling to MSAA Tiled Resources

MSAA Surface Mapping	MCS Mapping	Sample Response
Mapped	Mapped	Normal Response
Mapped	Unmapped	Undefined Response
Unmapped	Mapped	NULL Response
Unmapped	Unmapped	NULL Response

A "NULL Response" means that the sample returned will be all 0's and the **Null Pixel Mask** (if requested) will indicate the depth pixel is Null.

Tile Formats

Multiple tile formats are supported by the Gen Core. The following sections define and describe these formats.

Tiling formats are controlled by programming the fields `Tile_Mode` and `Tiled_Resource_Mode` in the `RENDER_SURFACE_STATE`.

Tile-X Legacy Format

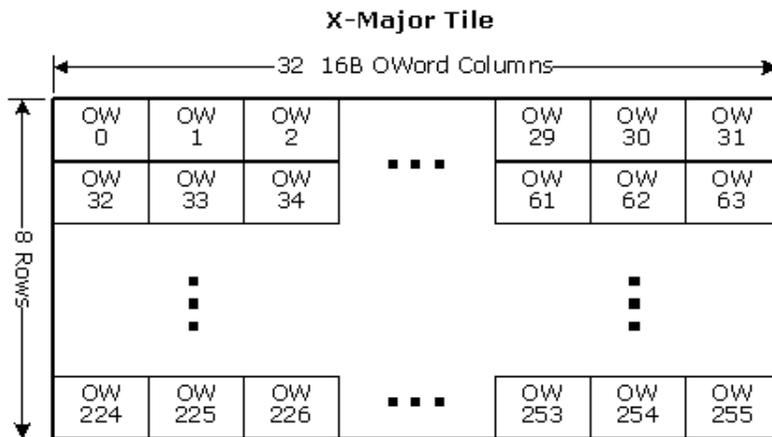
The legacy format Tile-X is a *X-Major* (row-major) storage of tile data units, as shown in the following figure. It is a 4KB tile which is subdivided into an 8-high by 32-wide array of 16-byte OWords . The selection of tile direction only impacts the internal organization of tile data, and does not affect how surfaces map onto tiles. Note that an X-major tiled region with a tile pitch of 1 tile is actually stored in a linear fashion.

Tile-X format is selected for a surface by programming the `Tiled_Mode` field in `RENDER_SURFACE_STATE` to `XMAJOR`.

For 3D sampling operation, a surface using Tile-X layout is generally lower performance the organization of texels in memory.



Tile X-Tile (X-Major) Layout



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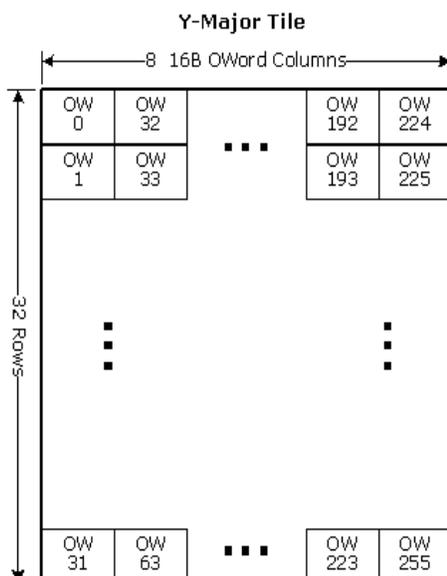
Tile-Y Legacy Format

The device supports Tile-Y legacy format which is *Y-Major* (column major) storage of tile data units, as shown in the following figure. A 4KB tile is subdivided 32-high by 8-wide array of OWords. The selection of tile direction only impacts the internal organization of tile data, and does not affect how surfaces map onto tiles.

Tile-Y surface format is selected by programming the `Tile_Mode` field in `RENDER_SURFACE_STATE` to `YMAJOR`.

Note that 3D sampling of a surface in Tile-Y format is usually has higher performance due to the layout of pixels.

Y-Major Tile Layout



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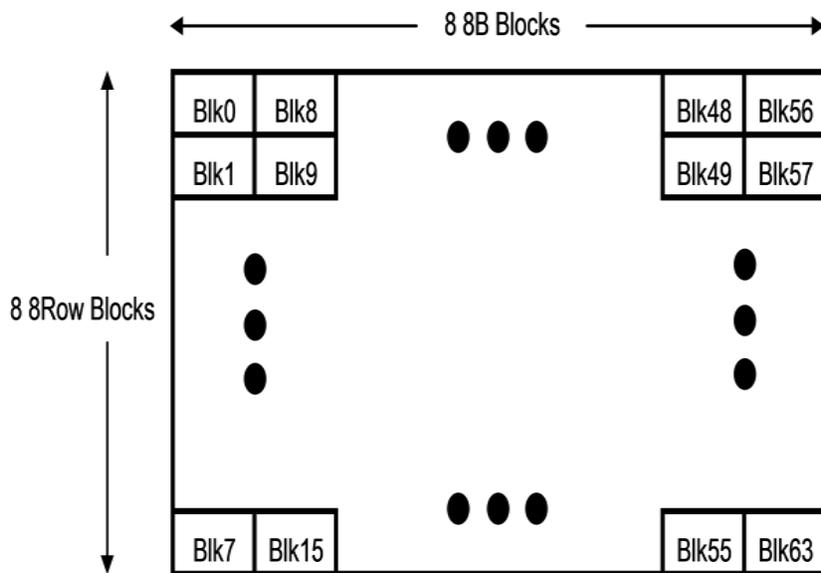


W-Major Tile Format

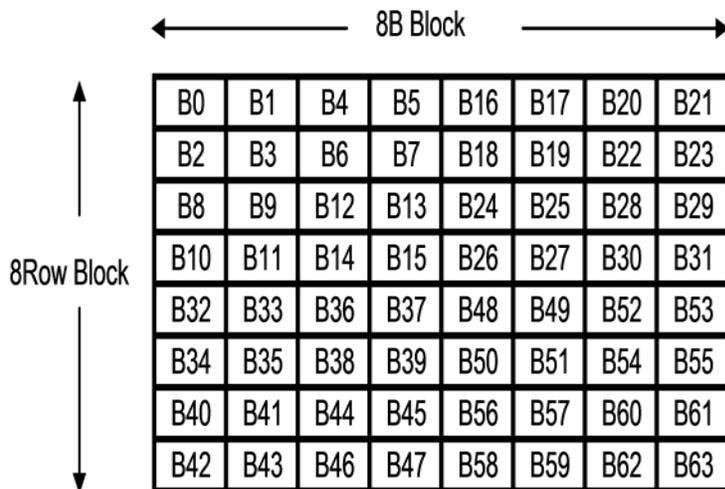
The device supports additional format *W-Major* storage of tile data units, as shown in the following figures. A 4KB tile is subdivided into 8-high by 8-wide array of Blocks for W-Major Tiles (W Tiles). Each Block is 8 rows by 8 bytes. The selection of tile direction only impacts the internal organization of tile data, and does not affect how surfaces map onto tiles. W-Major Tile Format is used for separate stencil.

Tile-W surface format is selected by programming the Tile_Mode field in the RENDER_SURFACE_STATE to WMAJOR.

W-Major Tile Layout



W-Major Block Layout

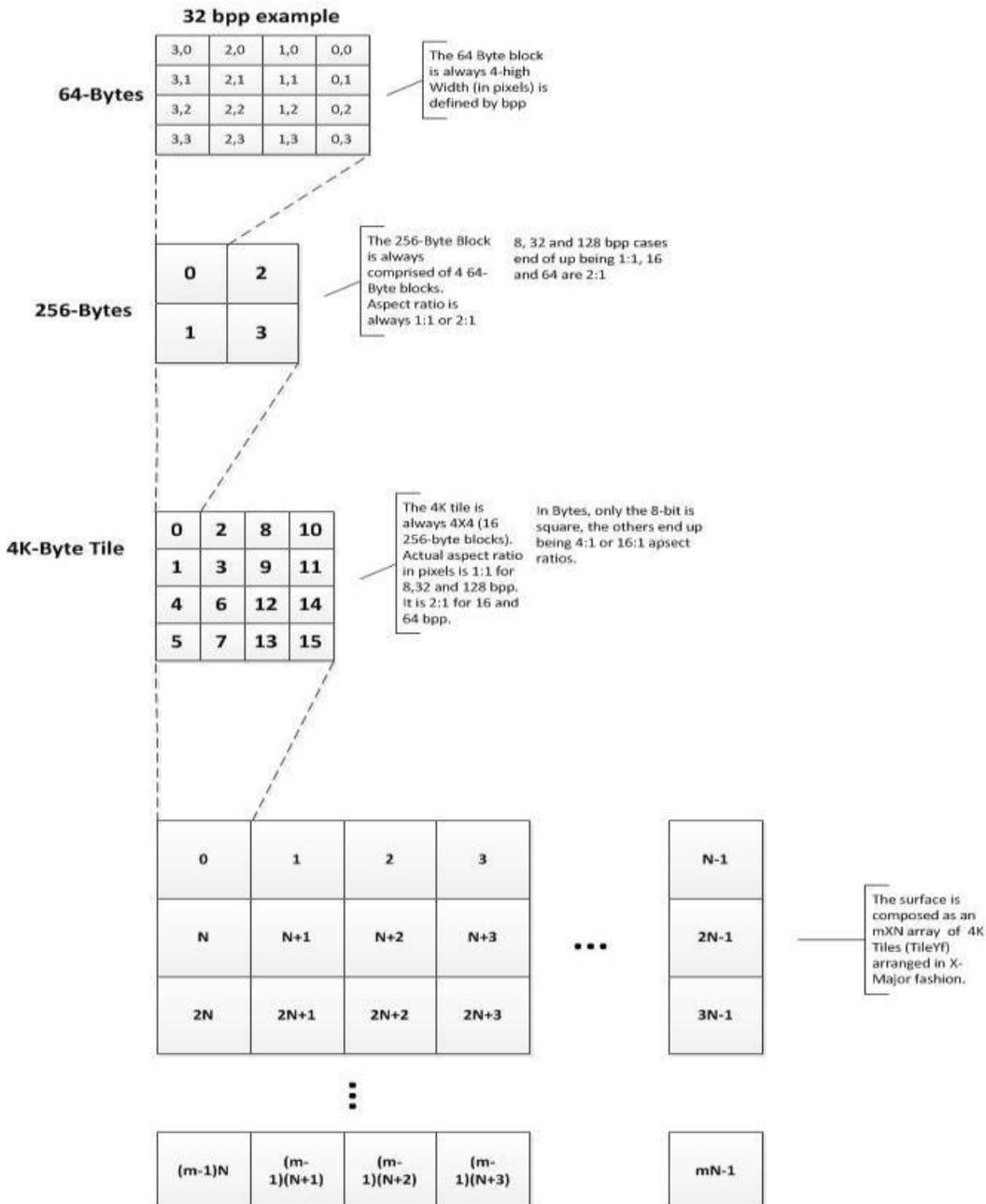




Tile-Yf Format

Tile-Yf is a 4K-Byte tile format (similar to Tile-Y), but organized in a different manner. Tile-Yf is selected by programming the Tile_Mode field in the RENDER_SURFACE_STATE to YMAJOR and the Tiled_Resource_Mode to TILEYF. The diagram below shows how pixels are mapped into the TileYf format for 2D surfaces, and it uses 32Bpp (bits per pixel) surface format as an example on a 2D surface which is N tiles wide and m tiles high. The exact aspect ratio will be dependent on the Bpp of the surface. Note that the TileYf format is identical to the TileYs up to the 4K-Byte tile size.

2D Tile Layout for TileYf

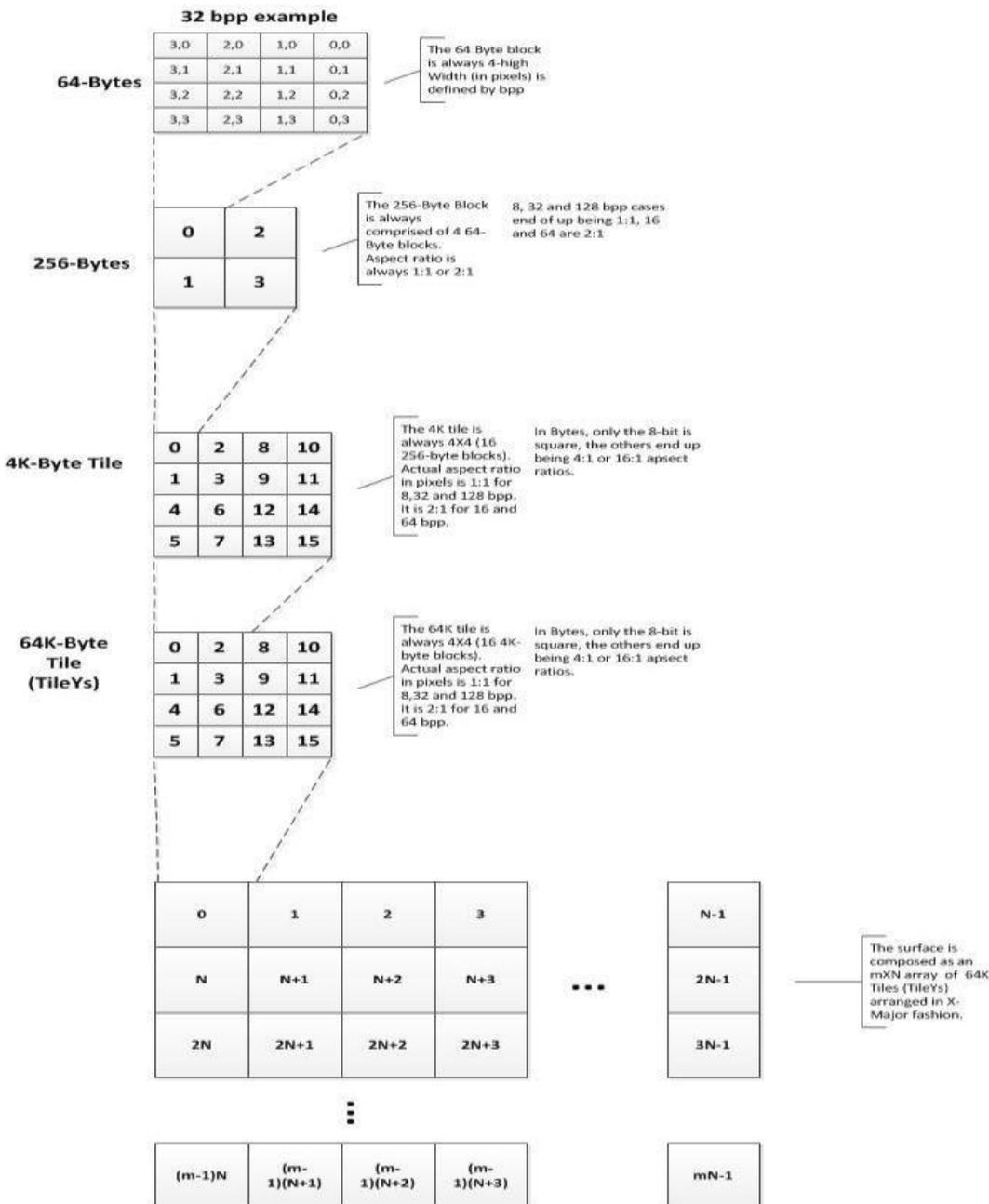




Tile-Ys Format

TileYs is a 64K-Byte tile size. It is enabled by programming the Tile_Mode field (in RENDER_SURFACE_STATE) to YMAJOR, and programming the Tiled_Resource_Mode to TILEYS. It is organized as shown below, and is composed of 4KByte blocks which have identical layout to the TileYf format. The diagram below shows how pixels are mapped into the TileYs format, and it uses 32Bpp (bits per pixel) surface format as an example on a 2D surface which is N tiles wide and m tiles high. The exact aspect ratio will be dependent on the Bpp of the surface.

Tile-Ys Layout





Tiling Algorithm

The following pseudo-code describes the algorithm for translating a tiled memory surface in graphics memory to an address in logical space.

The following new modes are supported for Tiled Resources (**TR_MODE** != TR_NONE) defined to enable tiled resources.

For more details about Mip Tails, see Surface Layout and Tiling in the Common Surface Formats section.

- **TileYF:** 4KB tiling mode based on TileY
- **TileYS:** 64KB tiling mode based on TileY

Inputs:

```

LinearAddress(offset into regular or LT aperture in terms of bytes),
Pitch(in terms of tiles),
    WalkY (1 for Y and 0 for X)
    WalkW (1 for W and 0 for the rest)

```

Static Parameters:

```

TileH (Height of tile, 8 for X, 32 for Y and 64 for W),
TileW (Width of Tile in bytes, 512 for X, 128 for Y and 64 for W)
TileSize = TileH * TileW;
RowSize = Pitch * TileSize;

```

If (Fenced) {

```

LinearAddress = LinearAddress - FenceBaseAddress
LinearAddrInTileW = LinearAddress div TileW;
Xoffset_inTile = LinearAddress mod TileW;
    Y = LinearAddrInTileW div Pitch;
    X = LinearAddrInTileW mod Pitch + Xoffset_inTile;

```

}

```

// Internal graphics clients that access tiled memory already have the X, Y
// coordinates and can start here
YOff_Within_Tile = Y mod TileH;
XOff_Within_Tile = X mod TileW;
TileNumber_InY = Y div TileH;
TileNumber_InX = X div TileW;

```

```

    TiledOffsetY = RowSize * TileNumber_InY + TileSize * TileNumber_InX + TileH * 16 *
(XOff_Within_Tile div 16) +
    YOff_Within_Tile * 16 +
    (XOff_Within_Tile mod 16);

```

```

    TiledOffsetW = RowSize * TileNumber_InY +
    TileSize * TileNumber_InX +
    TileH * 8 * (XOff_Within_Tile div 8) +
    64 * (YOff_Within_Tile div 8) +
    32 * ((YOff_Within_Tile div 4) mod 2) +
    16 * ((XOff_Within_Tile div 4) mod 2) +
    8 * ((YOff_Within_Tile div 2) mod 2) +
    4 * ((XOff_Within_Tile div 2) mod 2) +
    2 * (YOff_Within_Tile mod 2) +
    (XOff_Within_Tile mod 2);

```

```

    TiledOffsetX = RowSize * TileNumber_InY + TileSize * TileNumber_InX + TileW *
YOff_Within_Tile + XOff_Within_Tile;

```



```
TiledOffset = WalkW? TiledOffsetW : (WalkY? TiledOffsetY : TiledOffsetX);

TiledAddress = Tiled? (BaseAddress + TiledOffset): (BaseAddress + Y*LinearPitch +
X);TiledAddress = (Tiled &&
    (Address Swizzling for Tiled-Surfaces == 01)) ?
    (WalkW || WalkY) ?
    (TiledAddress div 128) * 128 +
    (((TiledAddress div 64) mod 2) ^
    ((TiledAddress div 512) mod 2)) +
    (TiledAddress mod 32)
    :
    (TiledAddress div 128) * 128 +
    (((TiledAddress div 64) mod 2) ^
    ((TiledAddress div 512) mod 2)
    ((TiledAddress Div 1024) mod 2)) +
    (TiledAddress mod 32)
    :
    TiledAddress;
}
```

Address Swizzling for Tiled-Surfaces is no longer used because the main memory controller has a more effective address swizzling algorithm.

For Address Swizzling for Tiled-Surfaces see ARB_MODE – Arbiter Mode Control register, ARB_CTL—Display Arbitration Control 1 and TILECTL - Tile Control register

The Y-Major tile formats have the characteristic that a surface element in an even row is located in the same aligned 64-byte cacheline as the surface element immediately below it (in the odd row). This spatial locality can be exploited to increase performance when reading 2x2 texel squares for bilinear texture filtering, or reading and writing aligned 4x4 pixel spans from the 3D Render pipeline.

On the other hand, the X-Major tile format has the characteristic that horizontally-adjacent elements are stored in sequential memory addresses. This spatial locality is advantageous when the surface is scanned in row-major order for operations like display refresh. For this reason, the Display and Overlay memory streams only support linear or X-Major tiled surfaces (Y-Major tiling is not supported by these functions). This has the side effect that 2D- or 3D-rendered surfaces must be stored in linear or X-Major tiled formats if they are to be displayed. Non-displayed surfaces, e.g., “rendered textures”, can also be stored in Y-Major order.

The following Psuedo Code Describes the algorithm for mapping TileYs and TileYf Tile Address to Byte Offset within a Tile. It describes the support for 2D for both TileYs and TileYf as well as MSAA 2D For TileYs.



```
        ((BIT7 & x) << 4) |
        ((BIT6 & x) << 3) |
        ((xMaskBits5_4 & x) << 2) | // shift to bit positions 7..6
        (xMaskBits3_0 & x);

    ySwizzle = ((BIT5 & y) << 9) |
               ((BIT4 & y) << 8) |
               ((BIT3 & y) << 7) |
               ((BIT2 & y) << 6) |
               ((yMaskBits1_0 & y) << 4); // shift to bit positions 5..4

    // OR the swizzled bit positions for final offset within a tile
    return xSwizzle | ySwizzle;
}

UINT16 TileYS2dElementOffset16_32bpe(UINT16 x, UINT16 y)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;

    // shift bits in x and y to their respective TileYS swizzled bit locations
    xSwizzle = ((BIT8 & x) << 7) |
               ((BIT7 & x) << 6) |
               ((BIT6 & x) << 5) |
               ((BIT5 & x) << 4) |
               ((BIT4 & x) << 3) |
               (xMaskBits3_0 & x);

    ySwizzle = ((BIT6 & y) << 8) |
               ((BIT5 & y) << 7) |
               ((BIT4 & y) << 6) |
               ((BIT3 & y) << 5) |
               ((yMaskBits2_0 & y) << 4); // shift to bit positions 6..4

    // OR the swizzled bit positions for final offset within a tile
    return xSwizzle | ySwizzle;
}

UINT16 TileYS2dElementOffset8bpe(UINT16 x, UINT16 y)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;

    // shift bits in x and y to their respective TileYS swizzled bit locations
    xSwizzle = ((BIT7 & x) << 8) |
               ((BIT6 & x) << 7) |
               ((BIT5 & x) << 6) |
               ((BIT4 & x) << 5) |
               (xMaskBits3_0 & x);

    ySwizzle = ((BIT7 & y) << 7) |
               ((BIT6 & y) << 6) |
               ((BIT5 & y) << 5) |
               ((yMaskBits4_0 & y) << 4); // shift to bit positions 8..4

    // OR the swizzled bit positions for final offset within a tile
    return xSwizzle | ySwizzle;
}

/*****\
    TileYS 2D MSAA Tile address swizzling functions w/o _pdep32
    \*****/
```



```

/*
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Num    | Bits per element | Tiled element offset bits |
| Samples |                   | 15|14|13|12|11|10| 9| 8| 7| 6| 5| 4| 3| 2| 1| 0|
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| 2x     | 64 & 128         | ss0|y5|x8|y4|x7|y3|x6|y2|x5|x4|y1|y0|x3|x2|x1|x0|
|         | 16 & 32          | ss0|y6|x7|y5|x6|y4|x5|y3|x4|y2|y1|y0|x3|x2|x1|x0|
|         | 8                | ss0|y7|x6|y6|x5|y5|x4|y4|y3|y2|y1|y0|x3|x2|x1|x0|
*/
UINT16 TileYS2xMsaaElementOffset64_128bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;
    UINT16 SampleSwizzle;

    // shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
    xSwizzle = ((BIT8 & x) << 5) | // shift to bit position 13
               ((BIT7 & x) << 4) | // shift to bit position 11
               ((BIT6 & x) << 3) | // shift to bit position 9
               ((xMaskBits5_4 & x) << 2) | // shift to bit positions 7..6
               (xMaskBits3_0 & x); // leave in bits 3..0

    ySwizzle = ((BIT5 & y) << 9) | // shift to bit position 14
               ((BIT4 & y) << 8) | // shift to bit position 12
               ((BIT3 & y) << 7) | // shift to bit position 10
               ((BIT2 & y) << 6) | // shift to bit position 8
               ((yMaskBits1_0 & y) << 4); // shift to bit positions 5..4

    SampleSwizzle = (sample && SampleMask0) << 15; // shift to bit position 15

    // OR the swizzled bit positions for final offset within a tile
    return SampleSwizzle | xSwizzle | ySwizzle;
}

UINT16 TileYS2xMsaaElementOffset16_32bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;
    UINT16 SampleSwizzle;

    // shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
    xSwizzle = ((BIT7 & x) << 6) | // shift to bit position 13
               ((BIT6 & x) << 7) | // shift to bit position 11
               ((BIT5 & x) << 6) | // shift to bit position 9
               ((BIT4 & x) << 5) | // shift to bit position 7
               (xMaskBits3_0 & x); // leave in bits 3..0

    ySwizzle = ((BIT6 & y) << 8) | // shift to bit position 14
               ((BIT5 & y) << 7) | // shift to bit position 12
               ((BIT4 & y) << 6) | // shift to bit position 10
               ((BIT3 & y) << 5) | // shift to bit position 8
               ((yMaskBits2_0 & y) << 4); // shift to bit positions 6..4

    SampleSwizzle = (sample && SampleMask0) << 15; // shift to bit position 15

    // OR the swizzled bit positions for final offset within a tile
    return SampleSwizzle | xSwizzle | ySwizzle;
}

UINT16 TileYS2xMsaaElementOffset8bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;

```



```

UINT16 ySwizzle;
UINT16 SampleSwizzle;

// shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
xSwizzle = ((BIT6 & x) << 7) | // shift to bit position 13
            ((BIT5 & x) << 6) | // shift to bit position 11
            ((BIT4 & x) << 5) | // shift to bit position 9
            (xMaskBits3_0 & x); // leave in bits 3..0

ySwizzle = ((BIT7 & y) << 7) | // shift to bit position 14
            ((BIT6 & y) << 6) | // shift to bit position 12
            ((BIT5 & y) << 5) | // shift to bit position 10
            ((yMaskBits4_0 & y) << 4); // shift to bit positions 8..4

SampleSwizzle = (sample && SampleMask0) << 15; // shift to bit position 15

// OR the swizzled bit positions for final offset within a tile
return SampleSwizzle | xSwizzle | ySwizzle;
}

/*
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Num    | Bits per element | Tiled element offset bits |
| Samples |                  | 15|14|13|12|11|10|9|8|7|6|5|4|3|2|1|0|
|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| 4x     | 64 & 128         | ss1|ss0|x8|y4|x7|y3|x6|y2|x5|x4|y1|y0|x3|x2|x1|x0|
|        | 16 & 32          | ss1|ss0|x7|y5|x6|y4|x5|y3|x4|y2|y1|y0|x3|x2|x1|x0|
|        | 8                | ss1|ss0|x6|y6|x5|y5|x4|y4|y3|y2|y1|y0|x3|x2|x1|x0|
*/
UINT16 TileYS4xMsaaElementOffset64_128bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;
    UINT16 SampleSwizzle;

    // shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
    xSwizzle = ((BIT8 & x) << 5) | // shift to bit position 13
                ((BIT7 & x) << 4) | // shift to bit position 11
                ((BIT6 & x) << 3) | // shift to bit position 9
                ((xMaskBits5_4 & x) << 2) | // shift to bit positions 7..6
                (xMaskBits3_0 & x); // leave in bits 3..0

    ySwizzle = ((BIT4 & y) << 8) | // shift to bit position 12
                ((BIT3 & y) << 7) | // shift to bit position 10
                ((BIT2 & y) << 6) | // shift to bit position 8
                ((yMaskBits1_0 & y) << 4); // shift to bit positions 5..4

    SampleSwizzle = (sample && SampleMask1_0) << 14; // shift to bit positions 15..14

    // OR the swizzled bit positions for final offset within a tile
    return SampleSwizzle | xSwizzle | ySwizzle;
}

UINT16 TileYS4xMsaaElementOffset16_32bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;
    UINT16 SampleSwizzle;

    // shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
    xSwizzle = ((BIT7 & x) << 6) | // shift to bit position 13
                ((BIT6 & x) << 7) | // shift to bit position 11

```



```

        ((BIT5 & x) << 6) | // shift to bit position 9
        ((BIT4 & x) << 5) | // shift to bit position 7
        (xMaskBits3_0 & x); // leave in bits 3..0

ySwizzle = ((BIT5 & y) << 7) | // shift to bit position 12
            ((BIT4 & y) << 6) | // shift to bit position 10
            ((BIT3 & y) << 5) | // shift to bit position 8
            ((yMaskBits2_0 & y) << 4); // shift to bit positions 6..4

SampleSwizzle = (sample && SampleMask1_0) << 14; // shift to bit positions 15..14

// OR the swizzled bit positions for final offset within a tile
return SampleSwizzle | xSwizzle | ySwizzle;
}

UINT16 TileYS4xMsaaElementOffset8bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;
    UINT16 SampleSwizzle;

    // shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
    xSwizzle = ((BIT6 & x) << 7) | // shift to bit position 13
                ((BIT5 & x) << 6) | // shift to bit position 11
                ((BIT4 & x) << 5) | // shift to bit position 9
                (xMaskBits3_0 & x); // leave in bits 3..0

    ySwizzle = ((BIT6 & y) << 6) | // shift to bit position 12
                ((BIT5 & y) << 5) | // shift to bit position 10
                ((yMaskBits4_0 & y) << 4); // shift to bit positions 8..4

    SampleSwizzle = (sample && SampleMask1_0) << 14; // shift to bit positions 15..14

    // OR the swizzled bit positions for final offset within a tile
    return SampleSwizzle | xSwizzle | ySwizzle;
}

/*


| Num     | Bits per element | Tiled element offset bits |     |     |    |    |    |    |    |    |    |    |    |    |    |    |    |
|---------|------------------|---------------------------|-----|-----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| Samples |                  | 15                        | 14  | 13  | 12 | 11 | 10 | 9  | 8  | 7  | 6  | 5  | 4  | 3  | 2  | 1  | 0  |
| 8x      | 64 & 128         | ss2                       | ss1 | ss0 | y4 | x7 | y3 | x6 | y2 | x5 | x4 | y1 | y0 | x3 | x2 | x1 | x0 |
|         | 16 & 32          | ss2                       | ss1 | ss0 | y5 | x6 | y4 | x5 | y3 | x4 | y2 | y1 | y0 | x3 | x2 | x1 | x0 |
|         | 8                | ss2                       | ss1 | ss0 | y6 | x5 | y5 | x4 | y4 | y3 | y2 | y1 | y0 | x3 | x2 | x1 | x0 |


*/
UINT16 TileYS8xMsaaElementOffset64_128bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;
    UINT16 SampleSwizzle;

    // shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
    xSwizzle = ((BIT7 & x) << 4) | // shift to bit position 11
                ((BIT6 & x) << 3) | // shift to bit position 9
                ((xMaskBits5_4 & x) << 2) | // shift to bit positions 7..6
                (xMaskBits3_0 & x); // leave in bits 3..0

    ySwizzle = ((BIT4 & y) << 8) | // shift to bit position 12
                ((BIT3 & y) << 7) | // shift to bit position 10
                ((BIT2 & y) << 6) | // shift to bit position 8
                ((yMaskBits1_0 & y) << 4); // shift to bit positions 5..4

```



```

SampleSwizzle = (sample && SampleMask2_0) << 13; // shift to bit positions 15..13

// OR the swizzled bit positions for final offset within a tile
return SampleSwizzle | xSwizzle | ySwizzle;
}

UINT16 TileYS8xMsaaElementOffset16_32bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;
    UINT16 SampleSwizzle;

    // shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
    xSwizzle = ((BIT6 & x) << 7) | // shift to bit position 11
               ((BIT5 & x) << 6) | // shift to bit position 9
               ((BIT4 & x) << 5) | // shift to bit position 7
               (xMaskBits3_0 & x); // leave in bits 3..0

    ySwizzle = ((BIT5 & y) << 7) | // shift to bit position 12
               ((BIT4 & y) << 6) | // shift to bit position 10
               ((BIT3 & y) << 5) | // shift to bit position 8
               ((yMaskBits2_0 & y) << 4); // shift to bit positions 6..4

    SampleSwizzle = (sample && SampleMask2_0) << 13; // shift to bit positions 15..13

    // OR the swizzled bit positions for final offset within a tile
    return SampleSwizzle | xSwizzle | ySwizzle;
}

UINT16 TileYS8xMsaaElementOffset8bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;
    UINT16 SampleSwizzle;

    // shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
    xSwizzle = ((BIT5 & x) << 6) | // shift to bit position 11
               ((BIT4 & x) << 5) | // shift to bit position 9
               (xMaskBits3_0 & x); // leave in bits 3..0

    ySwizzle = ((BIT6 & y) << 6) | // shift to bit position 12
               ((BIT5 & y) << 5) | // shift to bit position 10
               ((yMaskBits4_0 & y) << 4); // shift to bit positions 8..4

    SampleSwizzle = (sample && SampleMask2_0) << 13; // shift to bit positions 15..13

    // OR the swizzled bit positions for final offset within a tile
    return SampleSwizzle | xSwizzle | ySwizzle;
}

/*


| Num Samples | Bits per element | Tiled element offset bits                           |
|-------------|------------------|-----------------------------------------------------|
| 16x         | 64 & 128         | ss3 ss2 ss1 ss0 x7 y3 x6 y2 x5 x4 y1 y0 x3 x2 x1 x0 |
|             | 16 & 32          | ss3 ss2 ss1 ss0 x6 y4 x5 y3 x4 y2 y1 y0 x3 x2 x1 x0 |
|             | 8                | ss3 ss2 ss1 ss0 x5 y5 x4 y4 y3 y2 y1 y0 x3 x2 x1 x0 |


*/
UINT16 TileYS16xMsaaElementOffset64_128bpe(UINT16 x, UINT16 y, UINT16 sample)
{

```



```

UINT16 xSwizzle;
UINT16 ySwizzle;
UINT16 SampleSwizzle;

// shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
xSwizzle = ((BIT7 & x) << 4) | // shift to bit position 11
            ((BIT6 & x) << 3) | // shift to bit position 9
            ((xMaskBits5_4 & x) << 2) | // shift to bit positions 7..6
            (xMaskBits3_0 & x); // leave in bits 3..0

ySwizzle = ((BIT3 & y) << 7) | // shift to bit position 10
            ((BIT2 & y) << 6) | // shift to bit position 8
            ((yMaskBits1_0 & y) << 4); // shift to bit positions 5..4

SampleSwizzle = (sample && SampleMask3_0) << 12; // shift to bit positions 15..12

// OR the swizzled bit positions for final offset within a tile
return SampleSwizzle | xSwizzle | ySwizzle;
}

UINT16 TileYS16xMsaaElementOffset16_32bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;
    UINT16 SampleSwizzle;

    // shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
    xSwizzle = ((BIT6 & x) << 7) | // shift to bit position 11
                ((BIT5 & x) << 6) | // shift to bit position 9
                ((BIT4 & x) << 5) | // shift to bit position 7
                (xMaskBits3_0 & x); // leave in bits 3..0

    ySwizzle = ((BIT4 & y) << 6) | // shift to bit position 10
                ((BIT3 & y) << 5) | // shift to bit position 8
                ((yMaskBits2_0 & y) << 4); // shift to bit positions 6..4

    SampleSwizzle = (sample && SampleMask3_0) << 12; // shift to bit positions 15..12

    // OR the swizzled bit positions for final offset within a tile
    return SampleSwizzle | xSwizzle | ySwizzle;
}

UINT16 TileYS16xMsaaElementOffset8bpe(UINT16 x, UINT16 y, UINT16 sample)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;
    UINT16 SampleSwizzle;

    // shift bits in x, y, and sample to their respective TileYS MSAA swizzled bit locations
    xSwizzle = ((BIT5 & x) << 6) | // shift to bit position 11
                ((BIT4 & x) << 5) | // shift to bit position 9
                (xMaskBits3_0 & x); // leave in bits 3..0

    ySwizzle = ((BIT5 & y) << 5) | // shift to bit position 10
                ((yMaskBits4_0 & y) << 4); // shift to bit positions 8..4

    SampleSwizzle = (sample && SampleMask3_0) << 12; // shift to bit positions 15..12

    // OR the swizzled bit positions for final offset within a tile
    return SampleSwizzle | xSwizzle | ySwizzle;
}

```



```

/*****\
TileYF 2D Tile address swizzling functions w/o _pdep32
\*****/
/*

```

Num Samples	Bits per element	Tiled element offset bits															
		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1x	64 & 128																
	16 & 32																
	8																

```

*/
UINT16 TileYF2dElementOffset64_128bpe(UINT16 x, UINT16 y)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;

    // shift bits in x and y to their respective TileYF swizzled bit locations
    xSwizzle = ((BIT7 & x) << 4) |
                ((BIT6 & x) << 3) |
                ((xMaskBits5_4 & x) << 2) | // shift to bit positions 7..6
                (xMaskBits3_0 & x);

    ySwizzle = ((BIT3 & y) << 7) |
                ((BIT2 & y) << 6) |
                ((yMaskBits1_0 & y) << 4); // shift to bit positions 5..4

    // OR the swizzled bit positions for final offset within a tile
    return xSwizzle | ySwizzle;
}

```

```

UINT16 TileYF2dElementOffset16_32bpe(UINT16 x, UINT16 y)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;

    // shift bits in x and y to their respective TileYF swizzled bit locations
    xSwizzle = ((BIT6 & x) << 5) |
                ((BIT5 & x) << 4) |
                ((BIT4 & x) << 3) |
                (xMaskBits3_0 & x);

    ySwizzle = ((BIT4 & y) << 6) |
                ((BIT3 & y) << 5) |
                ((yMaskBits2_0 & y) << 4); // shift to bit positions 6..4

    // OR the swizzled bit positions for final offset within a tile
    return xSwizzle | ySwizzle;
}

```

```

UINT16 TileYF2dElementOffset8bpe(UINT16 x, UINT16 y)
{
    UINT16 xSwizzle;
    UINT16 ySwizzle;

    // shift bits in x and y to their respective TileYF swizzled bit locations
    xSwizzle = ((BIT5 & x) << 6) |
                ((BIT4 & x) << 5) |
                (xMaskBits3_0 & x);

    ySwizzle = ((BIT5 & y) << 5) |

```



```

        ((yMaskBits4_0 & y) « 4); // shift to bit positions 8..4

    // OR the swizzled bit positions for final offset within a tile
    return xSwizzle | ySwizzle;
}

```

Tiled Channel Select Decision

There was a historical configuration control field to swizzle address bit[6] for in X/Y tiling modes. This was set in three different places: TILECTL[1:0], ARB_MODE[5:4], and DISP_ARB_CTL[14:13].

The swizzle fields are all reserved, and the CPU's memory controller performs all address swizzling modifications.

Tiling Support

The rearrangement of the surface elements in memory must be accounted for in device functions operating upon tiled surfaces. (Note that not all device functions that access memory support tiled formats). This requires either the modification of an element's linear memory address or an alternate formula to convert an element's X,Y coordinates into a tiled memory address.

However, before tiled-address generation can take place, some mechanism must be used to determine whether the surface elements accessed fall in a linear or tiled region of memory, and if tiled, what the tile region pitch is, and whether the tiled region uses X-Major or Y-Major format. There are two mechanisms by which this detection takes place: (a) an implicit method by detecting that the pre-tiled (linear) address falls within a "fenced" tiled region, or (b) by an explicit specification of tiling parameters for surface operands (i.e., parameters included in surface-defining instructions).

The following table identifies the tiling-detection mechanisms that are supported by the various memory streams.

Access Path	Tiling-Detection Mechanisms Supported
Processor access through the Graphics Memory Aperture	Fenced Regions
3D Render (Color/Depth Buffer access)	Explicit Surface Parameters
Sampled Surfaces	Explicit Surface Parameters
Blit operands	Explicit Surface Parameters
Display and Overlay Surfaces	Explicit Surface Parameters



Tiled (Fenced) Regions

The only mechanism to support the access of surfaces in tiled format by the host or external graphics client is to place them within “fenced” tiled regions within Graphics Memory. A fenced region is a block of Graphics Memory specified using one of the sixteen FENCE device registers. (See *Memory Interface Registers* for details). Surfaces contained within a fenced region are considered tiled from an external access point of view. Note that fences cannot be used to untile surfaces in the PGM_Address space since external devices cannot access PGM_Address space. Even if these surfaces (or any surfaces accessed by an internal graphics client) fall within a region covered by an enabled fence register, that enable will be effectively masked during the internal graphics client access. Only the explicit surface parameters described in the next section can be used to tile surfaces being accessed by the internal graphics clients.

Tiled Surface Parameters

Internal device functions require explicit specification of surface tiling parameters via information passed in commands and state. This capability is provided to limit the reliance on the fixed number of fence regions.

The following table lists the surface tiling parameters that can be specified for 3D Render surfaces (Color Buffer, Depth Buffer, Textures, etc.) via SURFACE_STATE.

Surface Parameter	Description
Tiled Surface	If ENABLED, the surface is stored in a tiled format. If DISABLED, the surface is stored in a linear format.
Tile Walk	If Tiled Surface is ENABLED, this parameter specifies whether the tiled surface is stored in Y-Major or X-Major tile format.
Base Address	Additional restrictions apply to the base address of a Tiled Surface vs. that of a linear surface.
Pitch	Pitch of the surface. Note that, if the surface is tiled, this pitch must be a multiple of the tile width.



Tiled Surface Restrictions

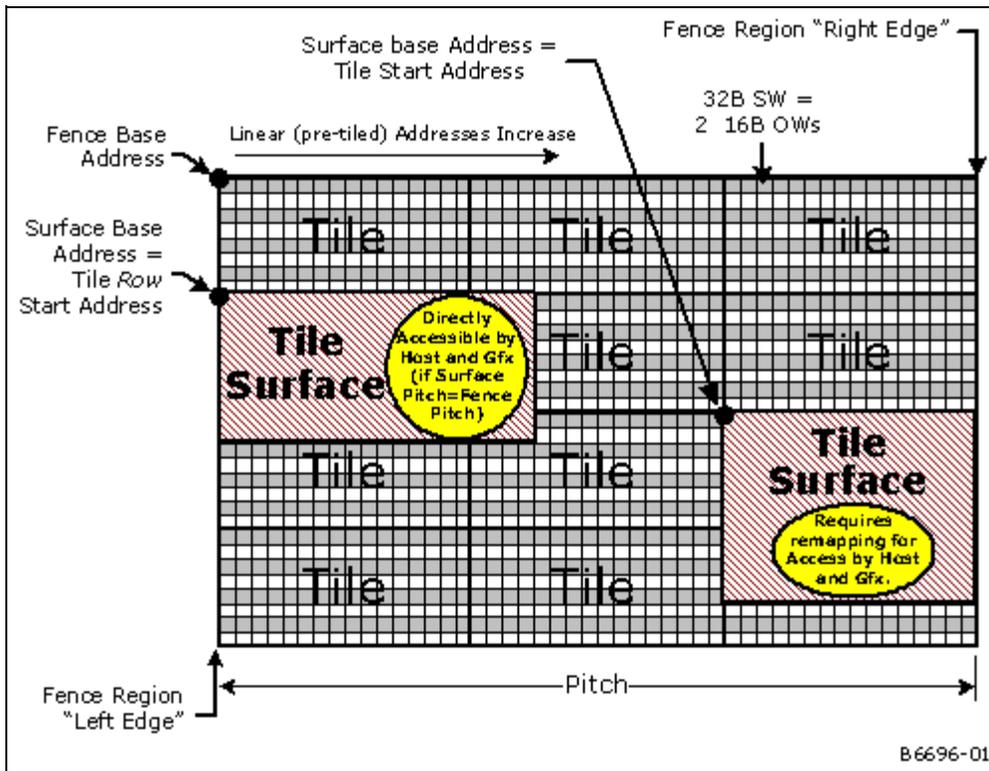
Additional restrictions apply to the Base Address and Pitch of a surface that is tiled. In addition, restrictions for tiling via SURFACE_STATE are subtly different from those for tiling via fence regions. The most restricted surfaces are those that will be accessed both by the host (via fence) and by internal device functions. An example of such a surface is a tiled texture that is initialized by the CPU and then sampled by the device.

The tiling algorithm for internal device functions is different from that of fence regions. Internal device functions always specify tiling in terms of a surface. The surface must have a base address, and this base address is not subject to the tiling algorithm. Only *offsets* from the base address (as calculated by X, Y addressing within the surface) are transformed through tiling. The base address of the surface must therefore be 4KB-aligned. This forces the 4KB tiles of the tiling algorithm to exactly align with 4KB device pages once the tiling algorithm has been applied to the offset. The width of a surface must be less than or equal to the surface pitch. There are additional considerations for surfaces that are also accessed by the host (via a fence region).

Fence regions have no base address per se. Host linear addresses that fall in a fence region are translated in their entirety by the tiling algorithm. It is as if the surface being tiled by the fence region has a base address in graphics memory equal to the fence base address, and all accesses of the surfaces are (possibly quite large) offsets from the fence base address. Fence regions have a virtual "left edge" aligned with the fence base address, and a "right edge" that results from adding the fence pitch to the "left edge". Surfaces in the fence region must not straddle these boundaries.

Base addresses of surfaces that are to be accessed both by an internal graphics client and by the host have the tightest restrictions. In order for the surface to be accessed without GTT re-mapping, the surface base address (as set in SURFACE_STATE) must be a "Tile Row Start Address" (TRSA). The first address in each tile row of the fence region is a Tile Row Start Address. The first TRSA is the fence base address. Each TRSA can be generated by adding an integral multiple of the row size to the fence base address. The row size is simply the fence pitch in tiles multiplied by 4KB (the size of a tile.)

Tiled Surface Placement



The pitch in SURFACE_STATE must be set equal to the pitch of the fence that will be used by the host to access the surface if the same GTT mapping will be used for each access. If the pitches differ, a different GTT mapping must be used to eliminate the "extra" tiles (4KB memory pages) that exist in the excess rows at the right side of the larger pitch. Obviously no part of the surface that will be accessed can lie in pages that exist only in one mapping but not the other. The new GTT mapping can be done manually by SW between the time the host writes the surface and the device reads it, or it can be accomplished by arranging for the client to use a different GTT than the host (the PPGTT -- see *Logical Memory Mapping* below).

The width of the surface (as set in SURFACE_STATE) must be less than or equal to both the surface pitch and the fence pitch in any scenario where a surface will be accessed by both the host and an internal graphics client. Changing the GTT mapping will not help if this restriction is violated.



Surface Access	Base Address	Pitch	Width	Tile "Walk"
Host only	No restriction	Integral multiple of tile size <= 256KB	Must be <= Fence Pitch	No restriction
Client only	4KB-aligned	Integral multiple of tile size <= 256KB	Must be <= Surface Pitch	Restrictions imposed by the client (see Per Stream Tile Format Support)
Host and Client, No GTT Remapping	Must be TRSA	Fence Pitch = Surface Pitch = integral multiple of tile size <= 256KB	Width <= Pitch	Surface Walk must meet client restriction, Fence Walk = Surface Walk
Host and Client, GTT Remapping	4KB-aligned for client (will be tile-aligned for host)	Both must be Integral multiple of tile size <= 128KB, but not necessarily the same	Width <= Min(Surface Pitch, Fence Pitch)	Surface Walk must meet client restriction, Fence Walk = Surface Walk

Per-Stream Tile Format Support

MI Client	Tile Formats Supported	
CPU Read/Write	All	
Display/Overlay	Y-Major not supported X-Major required for Async Flips	
Blt	Linear and X-Major only No Y-Major support	
3D Sampler	All Combinations of TileY, TileX and Linear are supported. TileY is the fastest, Linear is the slowest.	
3D Color,Depth	Rendering Mode Color-vs-Depth bpp	Buffer Tiling Supported
	Classical Same Bpp	Both Linear Both TileX Both TileY Linear & TileX Linear & TileY TileX & TileY
	Classical Mixed Bpp	Both Linear Both TileX Both TileY Linear & TileX Linear & TileY TileX & TileY



Main Memory

The integrated graphics device is capable of using 4KB pages of physical main (system) memory for graphics functions. Some of this main memory can be “stolen” from the top of system memory during initialization (e.g., for a VGA buffer). However, most graphics operands are dynamically allocated to satisfy application demands. To this end the graphics driver will frequently need to allocate locked-down (i.e., non-swappable) physical system memory pages – typically from a cacheable non-paged pool. The locked pages required to back large surfaces are typically non-contiguous. Therefore a means to support “logically-contiguous” surfaces backed by discontinuous physical pages is required. The Graphics Translation Table (GTT) that was described in previous sections provides the means.

Optimizing Main Memory Allocation

This section includes information for software developers on how to allocate SDRAM Main Memory (SM) for optimal performance in certain configurations. The general idea is that these memories are divided into some number of page types, and careful arrangement of page types both within and between surfaces (e.g., between color and depth surfaces) will result in fewer page crossings and therefore yield somewhat higher performance.

The algorithm for allocating physical SDRAM Main Memory pages to logical graphics surfaces is somewhat complicated by (1) permutations of memory device technologies (which determine page sizes and therefore the number of pages per device row), (2) memory device row population options, and (3) limitations on the allocation of physical memory (as imposed by the OS).

However, the theory to optimize allocation by limiting page crossing penalties is simple: (a) switching between open pages is optimal (again, the pages do not need to be sequential), (b) switching between memory device rows does not in itself incur a penalty, and (c) switching between pages within a particular bank of a row incurs a page miss and should therefore be avoided.



Application of the Theory (Page Coloring)

This section provides some scenarios for how Main Memory page allocation can be optimized.

3D Color and Depth Buffers

Here we want to minimize the impact of page crossings (a) between corresponding pages (1-4 tiles) in the Color and Depth buffers, and (b) when moving from a page to a neighboring page within a Color or Depth buffer. Therefore corresponding pages in the Color and Depth Buffers, and adjacent pages within a Color or Depth Buffer should be mapped to different page types (where a page's "type" or "color" refers to the row and bank it's in).

Memory Pages Backing Color and Depth Buffers

Color Buffer

Page Type 0	Page Type 1	Page Type 0	Page Type 1	⋮
Page Type 2	Page Type 3	Page Type 2	Page Type 3	⋮
Page Type 0	Page Type 1	Page Type 0	Page Type 1	⋮
Page Type 2	Page Type 3	Page Type 2	Page Type 3	⋮
⋮	⋮	⋮	⋮	⋮

Depth Buffer

Page Type 3	Page Type 2	Page Type 3	Page Type 2	⋮
Page Type 1	Page Type 0	Page Type 1	Page Type 0	⋮
Page Type 3	Page Type 2	Page Type 3	Page Type 2	⋮
Page Type 1	Page Type 0	Page Type 1	Page Type 0	⋮
⋮	⋮	⋮	⋮	⋮

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For higher performance, the Color and Depth Buffers could be allocated from *different* memory device rows.



Media/Video

The Y surfaces can be allocated using 4 page types in a similar fashion to the Color Buffer diagram. The U and V surfaces would split the same 4 page types as used in the Y surface.

Physical Graphics Address Types

The Physical Memory Address Types table lists the various *physical* address types supported by the integrated graphics device. Physical Graphics Addresses are either generated by Logical Memory mappings or are directly specified by graphics device functions. *These physical addresses are not subject to tiling or GTT re-mappings.*

Physical Memory Address Types

Address Type	Description	Range
MM_Address	Main Memory Address. Offset into physical, <i>unsnooped</i> Main Memory.	[0,TopOfMemory-1]
SM_Address	System Memory Address. Accesses are snooped in processor cache, allowing shared graphics/ processor access to (locked) cacheable memory data.	[0,512GB]

Graphics Virtual Memory

The GPU uses a virtual memory address space, where the graphics virtual address is mapped through a Page Table (PPGTT) to a physical memory address. Normally, this mapping is set up by the graphics device driver and is private to the GPU context. However, in some cases the graphics virtual address is shared with the CPU – see Shared Virtual Memory (SVM) for more information.

The range of valid graphics virtual addresses, and the types of page tables supported for address translation, varies with the GPU configuration. See the Configurations section for a summary the ranges and features supported by a specific graphics device.

Although the range of supported graphics virtual addresses varies, most GPU commands and GPU instructions use a common 64 bit definition for a graphics virtual address. Addresses outside of the supported range are reserved for future address space expansion. See the **GraphicsAddress** structure definition for specific details.

Some GPU devices support an extended graphics virtual memory address mapping called Tiled Resources. When enabled, the Tiled Resources Translation Table (TR-TT) pre-processes graphics virtual addresses. TR-TT maps a graphics virtual memory address either to a new graphics virtual memory address or to a Null Tile. Null Tiles return zero on reads and drop writes. For translations that are not Null Tiles, the new graphics virtual memory address is then used for the graphics virtual address and translated through the normal Page Table to generate a physical memory address.



Graphics Translation Tables

GT supports standard virtual memory models as defined by the IA programmer's guide. This section describes the different paging models, their behaviors, and the page table formats.

The Graphics Translation Tables GTT (Graphics Translation Table, sometimes known as the global GTT) and PPGTT (Per-Process Graphics Translation Table) are memory-resident page tables containing an array of DWord Page Translation Entries (PTEs) used in mapping logical Graphics Memory addresses to physical memory addresses, and sometimes snooped system memory "PCI" addresses.

The base address (MM offset) of the GTT and the PPGTT are programmed via the PGTBL_CTL and PGTBL_CTL2 MI registers, respectively. The translation table base addresses must be 4KB aligned. The GTT size can be either 128KB, 256KB, or 512KB (mapping to 128MB, 256MB, and 512MB aperture sizes respectively) and is physically contiguous. The global GTT should only be programmed via the range defined by GTTMMADR. The PPGTT is programmed directly in memory. The per-process GTT (PPGTT) size is controlled by the PGTBL_CTL2 register. The PPGTT can, in addition to the above sizes, also be 64KB in size (corresponding to a 64MB aperture). Refer to the GTT Range chapter for a bit definition of the PTE entries.

GFX Page Tables

GPU supports three page table mechanisms

- IA32e compatible GTT
- PPGTT – private per process GTT (private GFX)
- GGTT – global GTT

All page tables use the same 64-bit PTE format. Differences are in how various bit fields applies (vs reserved) under various usage models.

Tiled Resources Translation Tables

Sparse Tiled Resources can be thought of as a kind of application-controlled virtual memory scheme. The application allocates a resource in a virtual address space. Then the application tells the driver to map specified 64KB tiles within the surface to memory, within resources called Tile Pools. Tiles that are not mapped to a Tile Pool are null tiles.

Tiled Resource Translation Table (TRTT) is constructed as a 3 level tile Table. Each tile is 64KB in size which leaves behind $44-16=28$ address bits. 28bits are partitioned as $9+9+10$ which corresponds to TRVATT L3, L2 and L1 respectively. This is where TRVATT L3 has 512 entries, L2 has 512 entries and L1 has 1024 entries where each level is contained within a 4KB page hence L3 and L2 is composed of 64b entries and L1 is composed of 32b entries.



L3 Entry:

Bits	Field	Description
63:48	Ignored	Ignored (h/w does not care about values behind ignored registers)
47:12	ADDR: Address	GFX virtual address or Guest Physical Address of 4KB base address pointing to TR-TT L2. TR-TT table entries for L2 and L3 can be in GFX virtual address mode or Guest Physical address mode chosen by GFX software.
11:2	Ignored	Ignored (h/w does not care about values behind ignored registers)
1	Null	Null Tile where reads to this tile returns zero with a Null indicator and writes are dropped.
0	Invalid	Invalid Tile where reads to this tile returns zero and writes are dropped. Additional interrupt is generated to GFX software when an invalid tile is accessed.

Programming Note

Context: Tiled ResourceTranslation Tables in Gfx Page Tables

GFX Driver has to disable the TR-TT bypass mode before using tiled resoruces translation tables. Details of the registers are given in "registers for TR-TT management."

Programming Note

Context: Tiled ResourceTranslation Tables in Gfx Page Tables

GFX Driver is not allowed to put TR-TT entries into TR-VA space.

Programming Note

Context: Tiled ResourceTranslation Tables in Gfx Page Tables

Usage model for TR translations are restricted to GFX Render Engine (& POSH pipeline).

Programming Note

Context: Tiled ResourceTranslation Tables in Gfx Page Tables

TRTT is only for PPGTT64 (Advanced or Legacy PPGTT64). Enabling TRTT in Legacy PPGTT32 context or GGTT context is considered as invalid programming.



Registers for TR-TT Management

Following register is a global mechanism to disable the bypass mode which is considered to be default for h/w. GFX driver has to set this bit to disable bypass mode before using TR-TTs.

Following registers shall be part of the h/w context.

Tiled Resources VA Translation Table L3 Pointer						
Register Space:		MMIO: 0/2/0				
DWord	Bit	Description				
1	63:48	Reserved				
		<table border="1"> <tr> <td>Access:</td> <td>RO</td> </tr> </table> <p>Reserved.</p>	Access:	RO		
Access:	RO					
0	47:32	Tiled Resource – VA translation Table L3 Pointer (Upper Address)				
		<table border="1"> <tr> <td>Default Value:</td> <td>0000h</td> </tr> <tr> <td>Access:</td> <td>R/W</td> </tr> </table> <p>Upper address bits for tiled resource VA to virtual address translation L3 table. For physical memory option, address bits [47:39] has to be programmed to "0" as it is defined the limit of physical memory allocation.</p>	Default Value:	0000h	Access:	R/W
		Default Value:	0000h			
Access:	R/W					
<table border="1"> <tr> <td>Default Value:</td> <td>0000h</td> </tr> <tr> <td>Access:</td> <td>R/W</td> </tr> </table> <p>Lower address bits for tiled resource VA to virtual address translation L3 table.</p>	Default Value:	0000h	Access:	R/W		
Default Value:	0000h					
Access:	R/W					
0	15:0	Reserved				
		<table border="1"> <tr> <td>Access:</td> <td>RO</td> </tr> </table> <p>Reserved.</p>	Access:	RO		
Access:	RO					



Tiled Resources Null Tile Detection Register						
Register Space:		MMIO: 0/2/0				
DWord	Bit	Description				
	31:0	<p>Null Tile Detection Value</p> <table border="1"> <tr> <td>Default Value:</td> <td>00000000h</td> </tr> <tr> <td>Access:</td> <td>R/W</td> </tr> </table> <p>A 32bit value programmed to enable h/w to perform a match of TR-VA TT entries to detect Null Tiles. Hardware will flag each entry and space behind it as Null Tile for matched entries.</p>	Default Value:	00000000h	Access:	R/W
Default Value:	00000000h					
Access:	R/W					

Tiled Resources Invalid Tile Detection Register						
Register Space:		MMIO: 0/2/0				
DWord	Bit	Description				
	31:0	<p>Invalid Tile Detection Value</p> <table border="1"> <tr> <td>Default Value:</td> <td>00000000h</td> </tr> <tr> <td>Access:</td> <td>R/W</td> </tr> </table> <p>A 32bit value programmed to enable h/w to perform a match of TR-VA TT entries to detect Invalid Tiles. Hardware will flag each entry and space behind it as Invalid Tile for matched entries.</p>	Default Value:	00000000h	Access:	R/W
Default Value:	00000000h					
Access:	R/W					

Tiled Resources Virtual Address Detection Registers (TRVADR)					
Register Space:		MMIO: 0/2/0			
DWord	Bit	Description			
0	31:8	<p>Reserved</p> <table border="1"> <tr> <td>Access:</td> <td>RO</td> </tr> </table> <p>Reserved.</p>	Access:	RO	
	Access:	RO			
7:4	<p>TRVA Mask Value (TRVAMV)</p> <table border="1"> <tr> <td>Default Value:</td> <td>0000b</td> </tr> <tr> <td>Access:</td> <td>R/W</td> </tr> </table> <p>4bit MASK value that is mapped to incoming address bits[47:44]. MASK bits are used to identify which address bits need to be considered for compare. If particular mask bit is "1", mapping address bit needs to be compared to DATA value provided. If "0", corresponding address bit is masked which</p>	Default Value:	0000b	Access:	R/W
Default Value:	0000b				
Access:	R/W				



Tiled Resources Virtual Address Detection Registers (TRVADR)					
	<p>makes it don't care for compare (<i>this field defaults to "0000" to disable detection</i>)</p> <p><i>Note that h/w supports two possible values for MASK: "0000" which is disabled case and "1111" where 44 bit TR-VA space is carved out.</i></p>				
3:0	<p>TRVA Data Value (TRVADV)</p> <table border="1"> <tr> <td>Default Value:</td> <td>0b</td> </tr> <tr> <td>Access:</td> <td>R/W</td> </tr> </table> <p>4bit DATA value that is mapped to incoming address bits[47:44]. Data bits are used to compare address values that are not filtered by the TRVAMV for match.</p>	Default Value:	0b	Access:	R/W
Default Value:	0b				
Access:	R/W				

Tiled Resources Translation Table Control Register (TRTTE)						
Register Space: MMIO: 0/2/0						
DWord	Bit	Description				
0	31:2	<p>Reserved</p> <table border="1"> <tr> <td>Access:</td> <td>RO</td> </tr> </table> <p>Reserved.</p>	Access:	RO		
Access:	RO					
1		<p>TR-VA Translation Table Memory Location</p> <table border="1"> <tr> <td>Default Value:</td> <td>0b</td> </tr> <tr> <td>Access:</td> <td>R/W</td> </tr> </table> <p>This fields specifies whether the translation tables for TR-VA to VA are in virtual address space vs physical (GPA) address space.</p> <p>0: Tables are in Physical (GPA) Space</p> <p>1: Tables are in Virtual Address Space</p> <p>Tiled Resource Translation Tables in GPA space is not supported in any GEN generations. this mode should never be set as GPA mode (always set to '1'). HW will set TRTT tables in Virtual address space mode only.</p>	Default Value:	0b	Access:	R/W
Default Value:	0b					
Access:	R/W					



Tiled Resources Translation Table Control Register (TRTTE)					
0	<p>TR-TT Enable</p> <table border="1"> <tr> <td>Default Value:</td> <td>0b</td> </tr> <tr> <td>Access:</td> <td>R/W</td> </tr> </table> <p>TR translation tables are disabled as default. This field needs to be enabled via s/w to get TR translation active.</p>	Default Value:	0b	Access:	R/W
Default Value:	0b				
Access:	R/W				

The following register (0x4DFC[0]) has enable and disable control of the bypass path across TR translations. By default, bypass is enabled, and bypass needs to be disabled (by setting 0x4DFC[0] = '1') for TR translations to function. Disabling the bypass should be done before render power gating is enabled.

Detection and Treatment of Null and Invalid Tiles

Two types of definition that need to be extracted from TR-VA walk in addition to reaching the GFX virtual address.

1. **Null Tiles:** Null tiles provide the applications the of capability to preventing OS mapping the entire surface. When a memory access hits a Null tile, the access is terminated and zero's are returned to the originator of the memory access for loads along with a null indicator and for stores the access is dropped at the page walker level.
2. **Invalid Tiles:** This is the case where GFX software did not update the value of the mapping properly for hardware to separate resident vs null tiles. The Invalid Tile treatment is exactly same however additionally a unique interrupt is generated in h/w

Both detections are done by GPU:

- For L2/L3 entries, Null and Invalid tile information is already embedded in the TR-TT entries
- For L1 entries, the contents (32bits) are compared in hardware to pre-programmed values by GFX software (*values are provided in GFX MMIO space*). For the match values, two separate 32b registers are defined, one for Null Tile detection and one for Invalid Tile detection.

Hardware walking matching the value or detecting L2/L3 would terminate the walk (i.e. rest of the tables are not valid) and define the access as either Null or Invalid.

Programming Note	
Context:	Detection and treatment of null and invallide tiles.
The software is not allowed to program both Null and Invalid values to be the same.	



Programming Note	
Context:	TileX Surfaces and Null Tiles
NULL or Invalid Tiles are not supported on TileX surfaces.	

GPU implements a counter mechanism to roll-up the Null tile accesses detected. The counter value is exposed to GFX software via GFX MMIO.

When the TR translation tables are in Gfx virtual address domain, the pages faults encountered while walking the IA32e pages are not reported back to the TR walkers or TLBs. These faults are handled as fault & halt, making these faults transparent to the TR walkers. However, when such a fault is not fixed (unsuccessful fault response) or when a non-recoverable fault encountered, main page walker HW convertes the cycle to an invalid cycle. Thus, in this case, TR walker or TR TLBs will get incorrect read return data without any notification of the non-recoverable fault condition. Thus TR walker/TLBs will continue with the TR-walk with incorrect data. This can lead to spurious cycles being generated. However, a Gfx reset/FLR is expected as a result of the non-recoverable fault.

TR-TT Modes

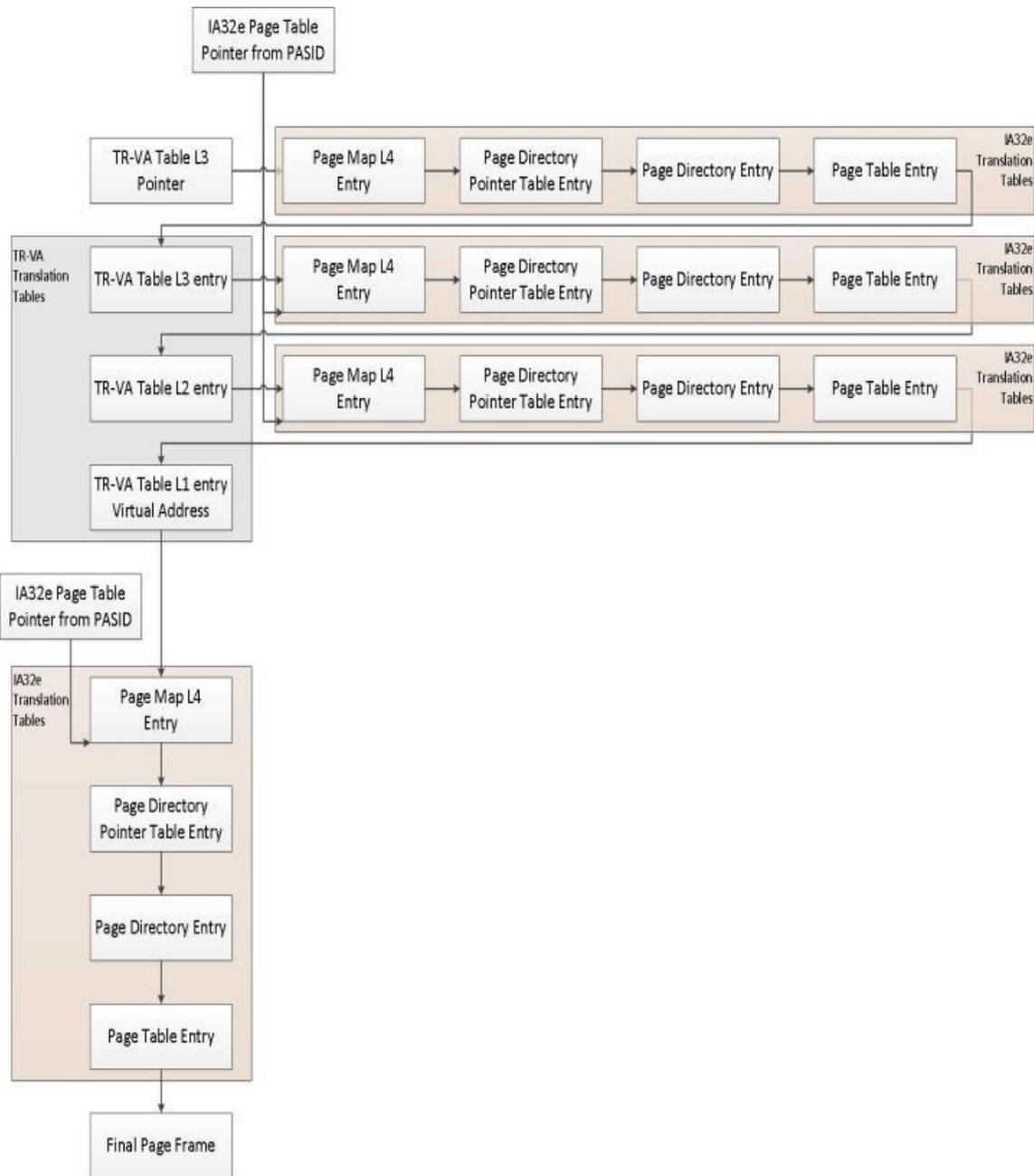
The L3 table pointer along with TRTTL3e/TRTTL2e is projected to support two modes of address space. Original intent was to have the contents to be in Virtual Address space (OS managed) and have them to be translated to GPA to HPA before getting accessed. Such mechanism will incur high latency penalties due to nested page translations. GPU shall have an additional mode where tiled-resources translation tables are in physical address space (GPA) and eliminate the need to have nested translations to reduce the potentially high miss latencies.

TR-TT walker shall have both modes supported. The Mode bit will be part of the same Register that provides TR-VA TT L3 pointer.

Virtual Addressed TR Translation Tables

Having sparse tiled resource translation tables in GFX virtual space requires the h/w TR-TT walker to walk thru the 1st level tile tables for table accesses to reach to Physical address at the L1 TR translation tables.

The following diagrams provide the view of the walk TR-VA translation tables are in physical memory and no 2nd Level (VTd) translations enabled.



Once 2nd level translations are enabled each level of 1st level walk needs to be further walked through VTd page tables.

The level of nested walks does not change the structure of the TR-VA walker; it just defines the recursive nature of the translations.



Page Table Modes

GFX Aperture and Display accesses are mapped thru Global GTT to keep the walk simple (i.e. 1-level) and latency sensitive. GPU accesses to memory can be mapped via Global GTT and/or ppGTT with various addressing modes.

Supported walk modes are listed as following:

1. **Global GTT with 32b virtual addressing:** Global GTT usage is similar to previous generations with extended capability of increasing virtual address (VA) up to 4GB (from 2GB) and use a standard 64b PTE format. The breakdown of the PTE for global GTT is given in later sections and allows 1-level page walk where the 20b index is used to select the 64b PTE from memory.
2. **Legacy 32b VA with ppGTT:** This is a mode where ppGTT page tables are considered private and managed via GFX software (driver) where context is tagged as Legacy 32b VA. Each page walk is managed via 9b of the virtual address and 20b index to address 4GB memory space is broken into 3 parts. In order to optimize the walks and make it look like previous generations, GFX software provides 4 pointers to page tables (called 4 PDP entries) all guest physical address. GPU uses the four pointers and fetches the 4x4KB into h/w (for render and media) before the context execution starts. The optimization limits the dynamic (on demand) page walks to 1-level only.
3. **Legacy 48b VA with ppGTT:** GFX address expansion beyond 4GB is added to address 48b virtual address space. 48b VA requires 36b indexing (4x9b) translating into 4-levels of page walk. To reduce the overhead of 4 level walk, GPU will cache the entire content of PML4 (4kB) to limit the on-demand walks to 3 levels. The caching happens as part of the initial demand where no further replacements required.
4. **Advanced 48b VA with IA32e support via IOMMU:** 48b addressing in advanced mode is managed via IOMMU settings where the base of the page table shall be found after the root / context tables using bus/device/function values. PASID# is used as an index in PASID table to find page table pointer to start the 4-level page walk. Rest of the mechanism is similar to Legacy 48b VA mode, GPU has the capability to cache entire content of PML4 and try to limit the dynamic page walks to 3-level.

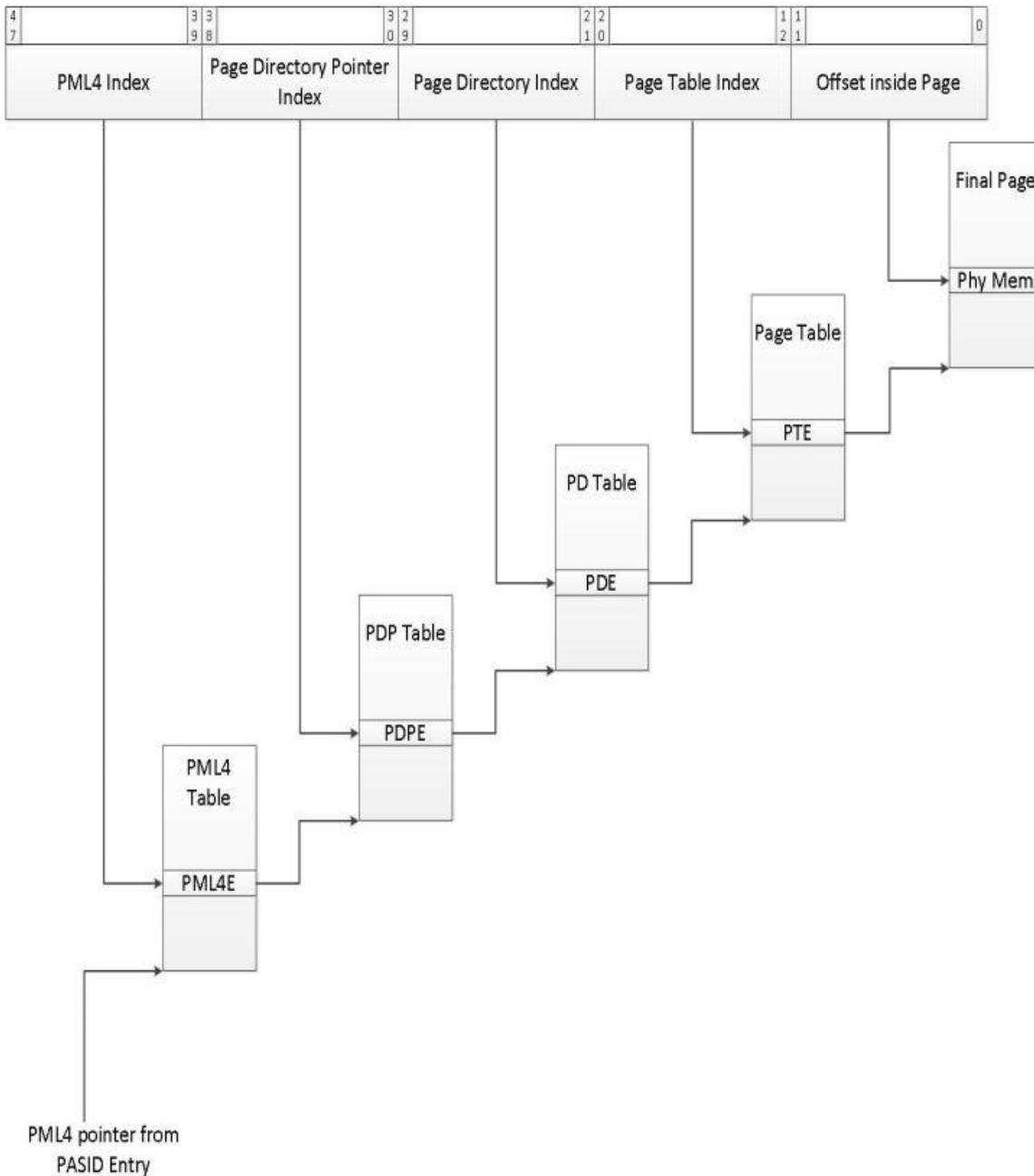
Per Process GTT

GTT mechanism has multiple hooks and mechanisms for s/w to prepare the page walks on hardware. The listed mechanisms here are selectable per-context and descriptors are delivered to hardware as part of context descriptor.

The entry contents are also modified to match the same format as IA32e page tables allowing future expansion for sharable page tables as well as higher order virtual addressing.

Page Tables Entry (PTE) Formats

Page Table Entry (PTE) formats follow the IA32e layout shown below. Note that the Hardware Address Width (HAW) is determined by Uncore: typically 39 for client products and 46 for server products.



A 64 bit (48b canonical) address requires 4 levels of page table format where the context carries a pointer to highest level page table (PML4 pointer) via PASID. The rest of the walk is normal page walk thru various levels.

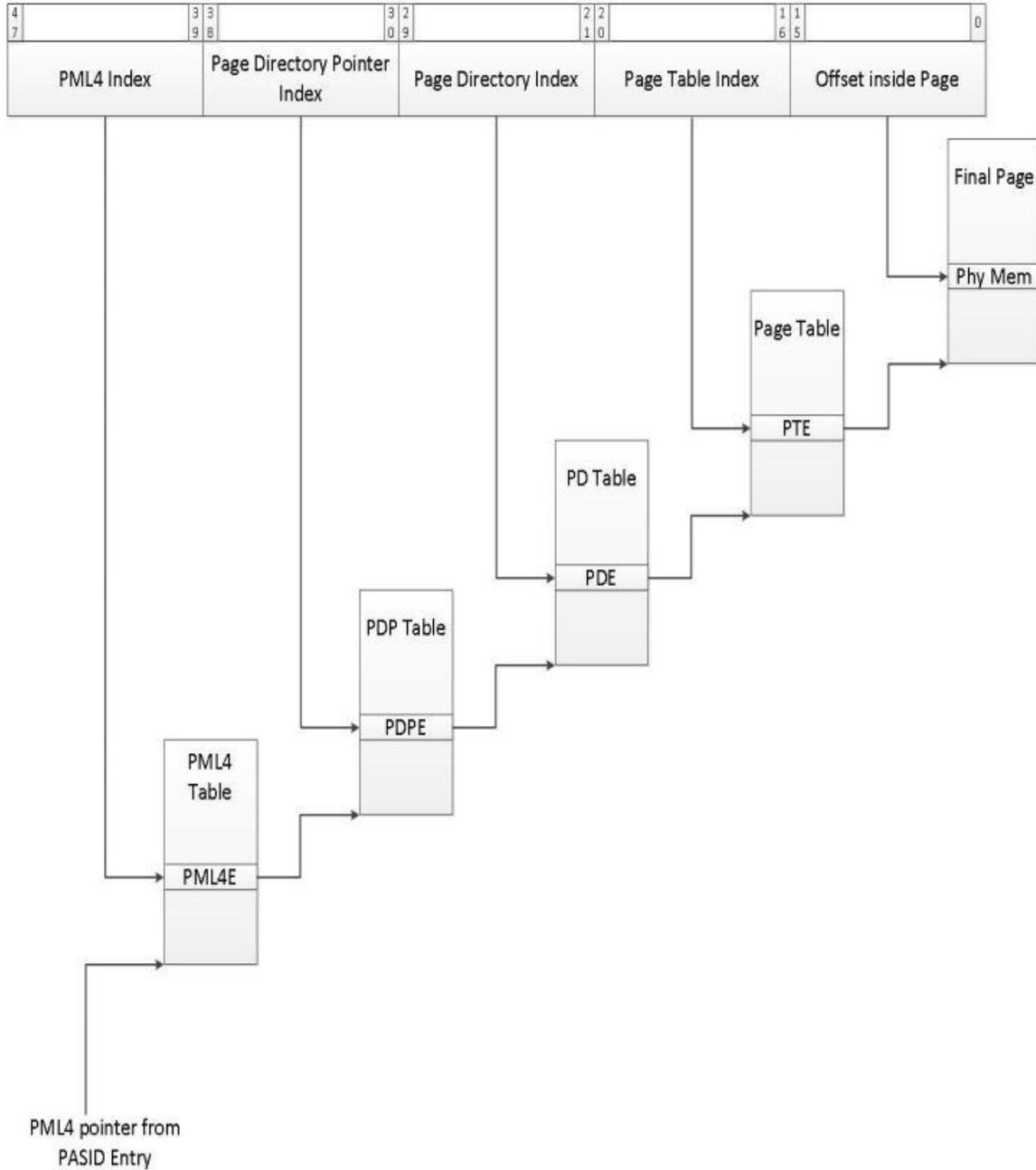
To repurpose the caches the following mechanism is used:

- 3D: 4KB to store PML4, 4KB as PDP cache, 2x4PD cache.
- Media: 4KB to store PML4, 4KB as PDP cache, 2x4PD cache.
- VEBOX, Blitter: each with 4KB acting as PML4, PDP, PD cache.

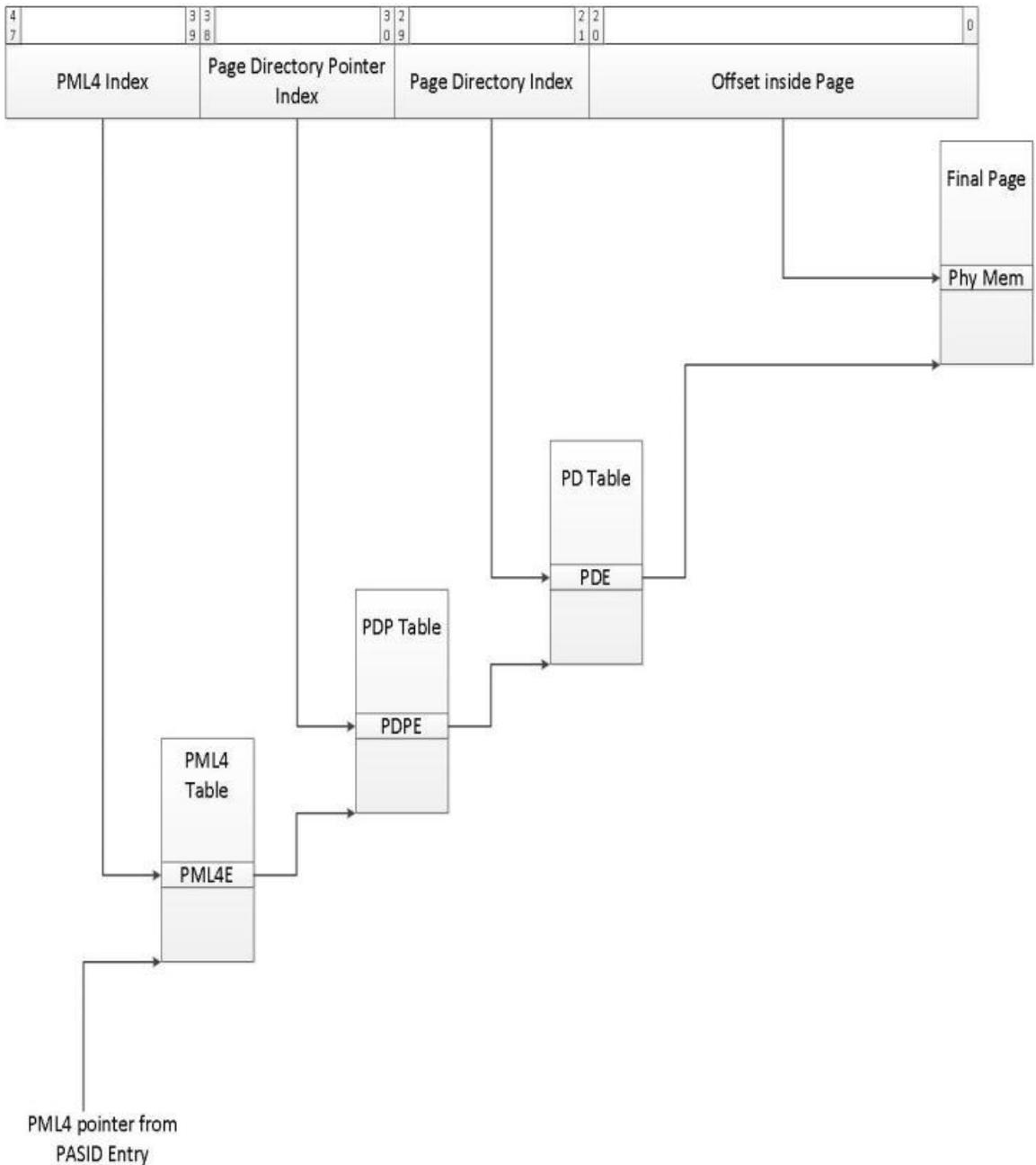


The design sections the 512 entries within 4KB into separate areas for PML4, PDP, and PD.

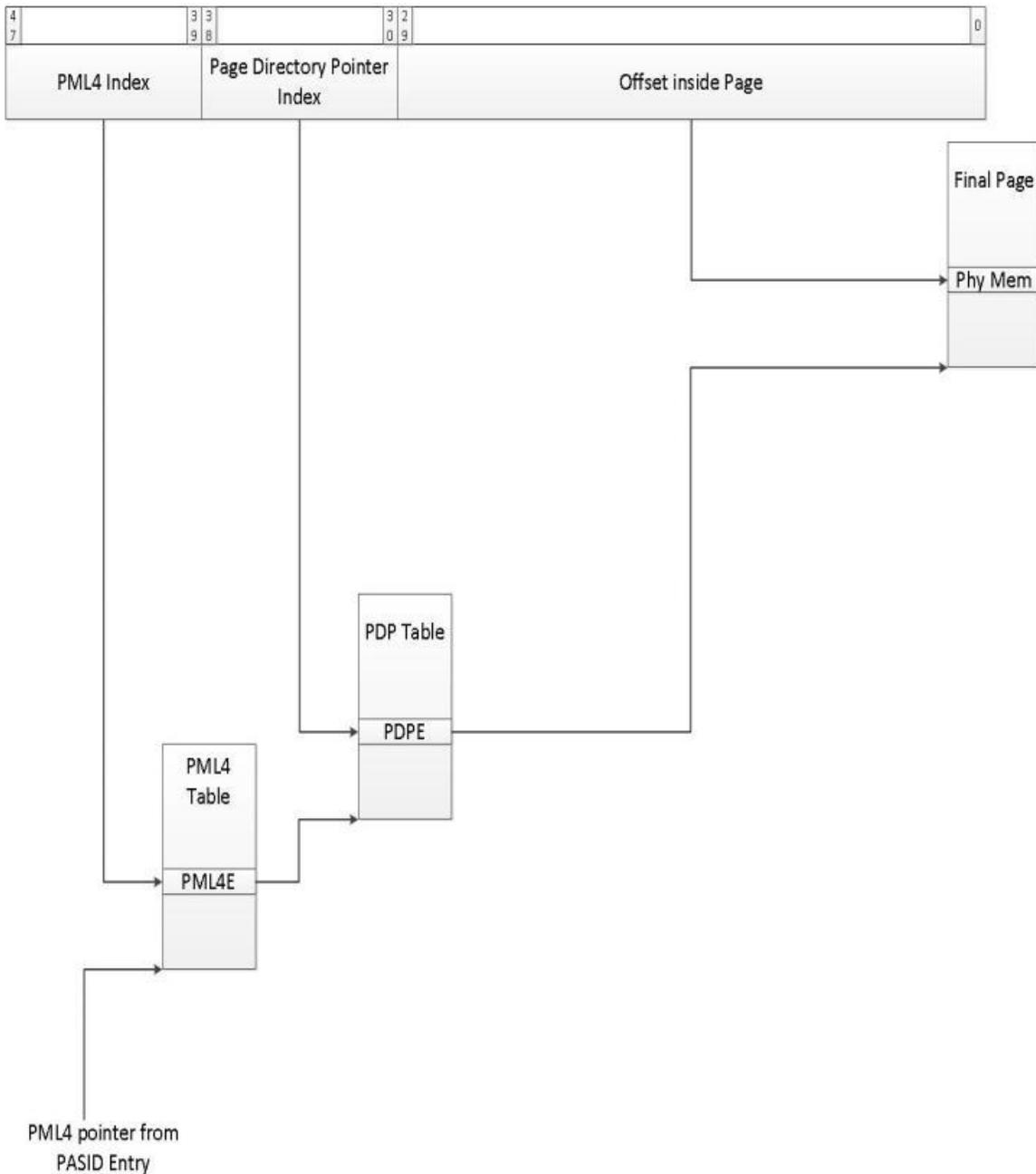
The 64KB Page size has a slightly different usage for how PTEs are selected for the corresponding 64KB page. In a page table every 16th entry (PTE#0, PTE#16, PTE#32, ... PTE#496) should be used to index. This is calculated using address[20:16] & "0000". Note that hardware should not make any assumptions for any other PTEs.



With the 2MB Page walk, the last level of the page walk is skipped where the PD entry points to the final page.



For the support for 1GB page size, the following mechanism is needed.



Pointer to PML4 Table

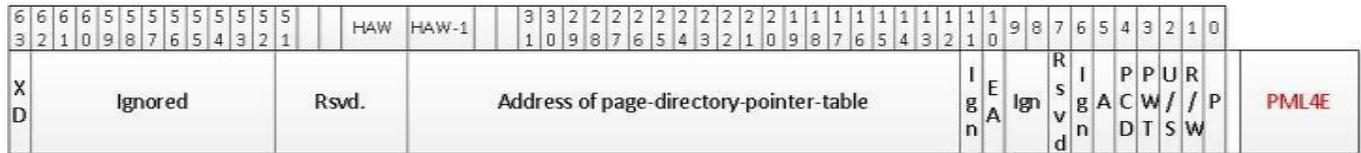
Page table pointer is the starting address where the PML4 table starts. The contents of pointer will be provided by PASID table entry in case of advanced context, else it will be provided by software as part of the legacy context with 48b addressing.

Details of PASID entry is given in later sections.



PML4E: Pointer to PDP Table

PML4 is used to locate the page directory pointer tables distributed in physical memory. PML4 will be used for advanced GPGPU context scheduled via PASID table as well as legacy context with 48b VA.



Bits	Field	Description
63	XD: Execute Disable	If NXE=1 in the relevant extended-context-entry, execute permission is not granted for requests to the memory region controlled by this entry when XD=1.
62:52	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
51:HAW*	<i>Reserved</i>	<i>Reserved (must return 0's)</i>
(HAW-1):12	ADDR: Address	Physical address of 4-KByte aligned page-directory-pointer table referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
11	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
10	EA: Extended Access	Extended Access bit is added for devices to separate accesses from IA cores. If EAFE=1 in the relevant PASID-entry, this bit indicates whether this entry has been used for address translation by device. It is the devices responsibility to set this bit. If EAFE=0 in the relevant PASID-entry, this bit is ignored. This bit applies to GPU Only.
9:8	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
7	<i>Reserved</i>	<i>Reserved (must return 0's)</i>
6	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
5	A: Accessed	A-bit needs to be managed as the table entry being accessed. Hardware needs to set this bit for the first access to the region defined with this page table entry. See later sections for A/D-bit management.
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry. <i>GPU does not support any memory type but WB when accessing paging structures.</i>
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry. <i>GPU does not support any memory type but WB when accessing paging structures.</i>
2	U/S: User/Supervisor	User vs supervisor access rights. If 0, requests with user-level privilege are not allowed to the memory region controlled by this entry. See section for access rights. <i>GPU does not support Supervisor mode contexts.</i>



Bits	Field	Description
10	EA: Extended Access	Extended Access bit is added for devices to separate accesses from IA cores. If EAFE=1 in the relevant PASID-entry, this bit indicates whether this entry has been used for address translation by device. It is the devices responsibility to set this bit. If EAFE=0 in the relevant PASID-entry, this bit is ignored. This bit applies to GPU Only.
9	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
8	G: Global	If PGE=1 in the corresponding context table entry, this field can be set by s/w to indicate that the memory region pointed by this entry can be considered global <i>Global paging is not used by GPU.</i>
7	Page Size	Must be 1 to indicate 1GB page.
6	D: Dirty	D-bit needs to be managed by h/w as the table entry is accessed with a successful write transaction. See later sections for A/D-bit management.
5	A: Accessed	A-bit needs to be managed as the table entry being accessed. Hardware needs to set this bit for the first access to the region defined with this page table entry. See later sections for A/D-bit management.
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	U/S: User/Supervisor	User vs supervisor access rights. If 0, requests with user-level privilege are not allowed to the memory region controlled by this entry. See section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (<i>and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry</i>) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	It must be "1" to point to a 1GB Page.

* HAW = 39 for client, and 46 for server.

PD: Pointer to Page Table

Page Directory entry has few different usage models:

1. It can identify the base of the page table.
2. It can define 2MB page table entries.

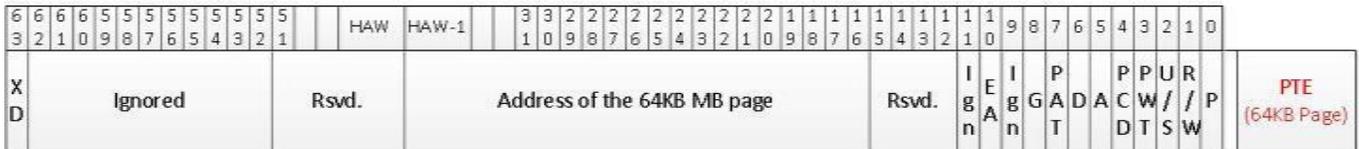
Pointer to page table is given below:



Bits	Field	Description
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	U/S: User/Supervisor	User vs supervisor access rights. If 0, requests with user-level privilege are not allowed to the memory region controlled by this entry. See section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (<i>and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry</i>) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	It must be "1" to point to a 2MB Page.

* HAW = 39 for client, and 46 for server.

PTE: Page Table Entry for 64KB Page



Bits	Field	Description
63	XD: Execute Disable	If NXE=1 in the relevant extended-context-entry, execute permission is not granted for requests to the memory region controlled by this entry when XD=1.
62:52	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
51:HAW*	<i>Reserved</i>	<i>Reserved (must return 0's)</i>
(HAW-1):16	ADDR: Address	Physical address of 64KB memory page referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
15:12	<i>Reserved</i>	<i>Reserved (must return 0's)</i>
11	<i>Ignored/Reserved</i>	<i>Ignored/not used by hardware</i>
10	EA: Extended Access	Extended Access bit is added for devices to separate accesses from IA cores. If EAFE=1 in the relevant PASID-entry, this bit indicates whether this entry has been used for address translation by device. It is the devices responsibility to set this bit. If EAFE=0 in the relevant PASID-entry, this bit is ignored. This bit applies to GPU Only.
9	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
8	G: Global	If PGE=1 in the corresponding context table entry, this field can be set by s/w to indicate that the memory region pointed by this entry can be considered global <i>Global paging is not used by GPU.</i>



Bits	Field	Description
(HAW-1):12	ADDR: Address	Physical address of 4KB memory page referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
11	Ignored/Reserved	Ignored/not used by hardware
10	EA: Extended Access	Extended Access bit is added for devices to separate accesses from IA cores. If EAFE=1 in the relevant PASID-entry, this bit indicates whether this entry has been used for address translation by device. It is the devices responsibility to set this bit. If EAFE=0 in the relevant PASID-entry, this bit is ignored. This bit applies to GPU Only.
9	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
8	G: Global	If PGE=1 in the corresponding context table entry, this field can be set by s/w to indicate that the memory region pointed by this entry can be considered global <i>Global paging is not used by GPU.</i>
7	PAT: Page Attribute	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
6	D: Dirty	D-bit needs to be managed by h/w as the table entry is accessed with a successful write transaction. See later sections for A/D-bit management.
5	A: Accessed	A-bit needs to be managed as the table entry being accessed. Hardware needs to set this bit for the first access to the region defined with this page table entry. See later sections for A/D-bit management.
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	U/S: User/Supervisor	User vs supervisor access rights. If 0, requests with user-level privilege are not allowed to the memory region controlled by this entry. See section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (<i>and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry</i>) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	It must be "1" to point to a 4KB Page.

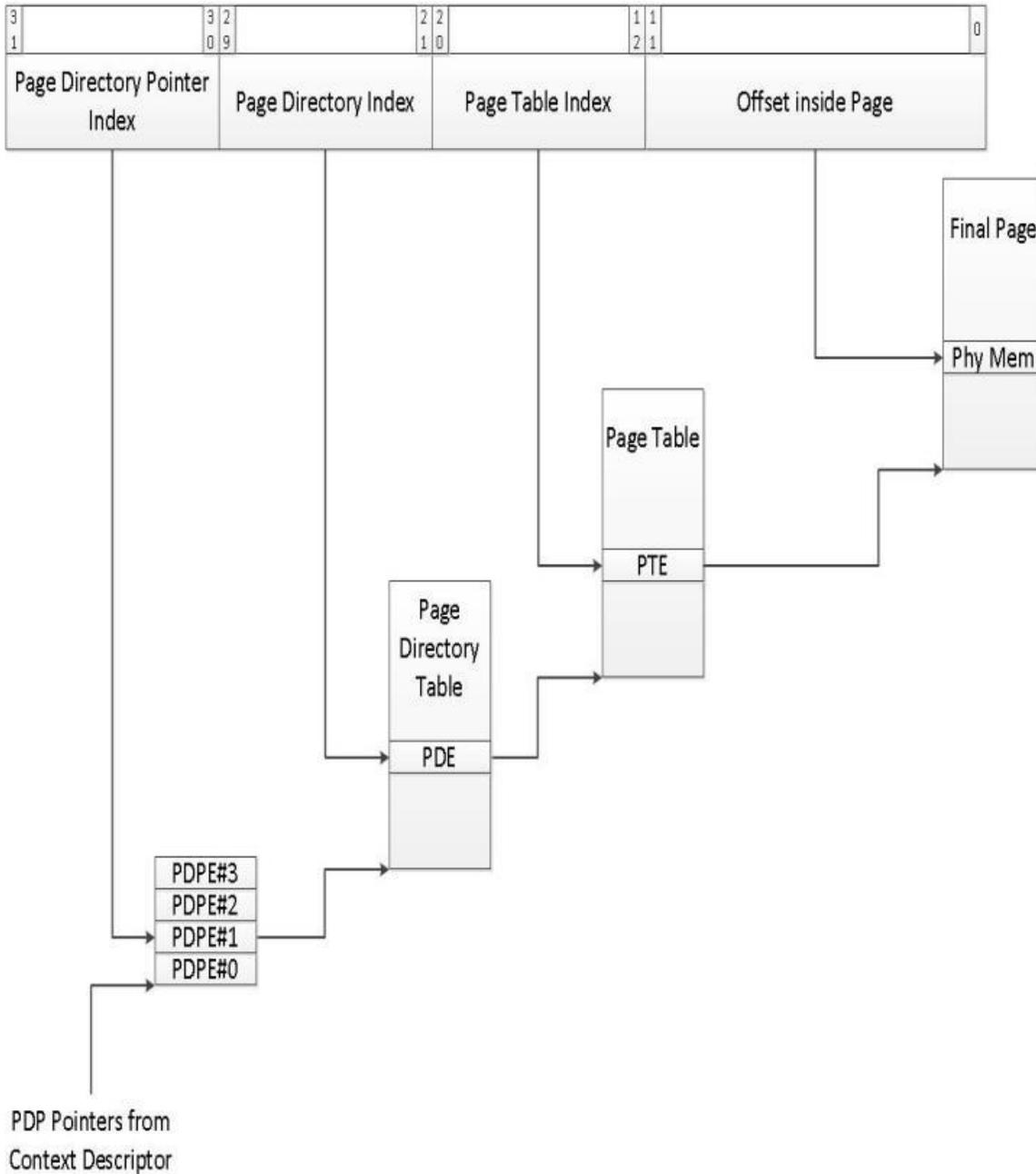
* HAW = 39 for client, and 46 for server.



PPGTT for 32b Virtual Address

For page walk in legacy mode with 32b VA, we need two levels. The walk starts with a PDP pointer provided by the context descriptor, and uses the 32b VA as an index to consecutive levels of page tables. Hardware implements 16KB intermediate caches to limit the page walk needed to a single level, to have the same sensitivity to latency as previous generations.

The following diagram shows the page walk needed for a 4KB page.

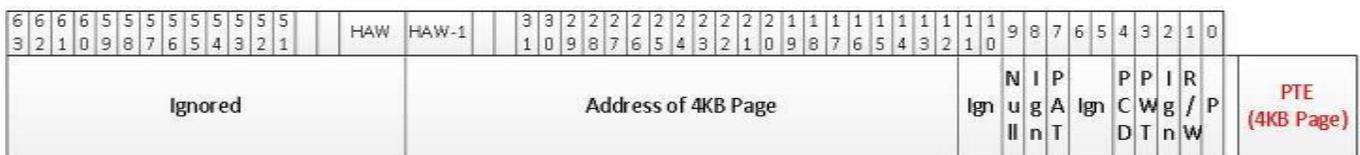


Page Table Entry formats for 32b VA use the following formats:



Bits	Field	Description
15:10	Ignored	Ignored (h/w does not care about values behind ignored registers)
9	N: Null	For Tile-Resources, private PPGTT tables enables for driver to merge Null Page information to primary (1 st Level) translation tables. If Null=1, the h/w will avoid the memory access and return all zero's for the read access with a null completion, write accesses are dropped.
8	Ignored	Ignored (h/w does not care about values behind ignored registers)
7	PAT: Page Attribute	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
6:5	Ignored	Ignored (h/w does not care about values behind ignored registers)
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	Ignored	Ignored (h/w does not care about values behind ignored registers)
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry) to the memory region controlled by this entry. See a later section for access rights. GPU does not support Supervisor mode contexts.
0	P: Present	It must be "1" to point to a 64KB Page.

PTE for 4KB Page



Bits	Field	Description
63:HAW*	Ignored	Ignored (h/w does not care about values behind ignored registers)
(HAW-1):12	ADDR: Address	Physical address of 64KB memory page referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
11:10	Ignored	Ignored (h/w does not care about values behind ignored registers)
9	N: Null	For Tile-Resources, private PPGTT tables enables for driver to merge Null Page information to primary (1 st Level) translation tables. If Null=1, the h/w will avoid the memory access and return all zero's for the read access with a null completion, write accesses are dropped.
8	Ignored	Ignored (h/w does not care about values behind ignored registers)

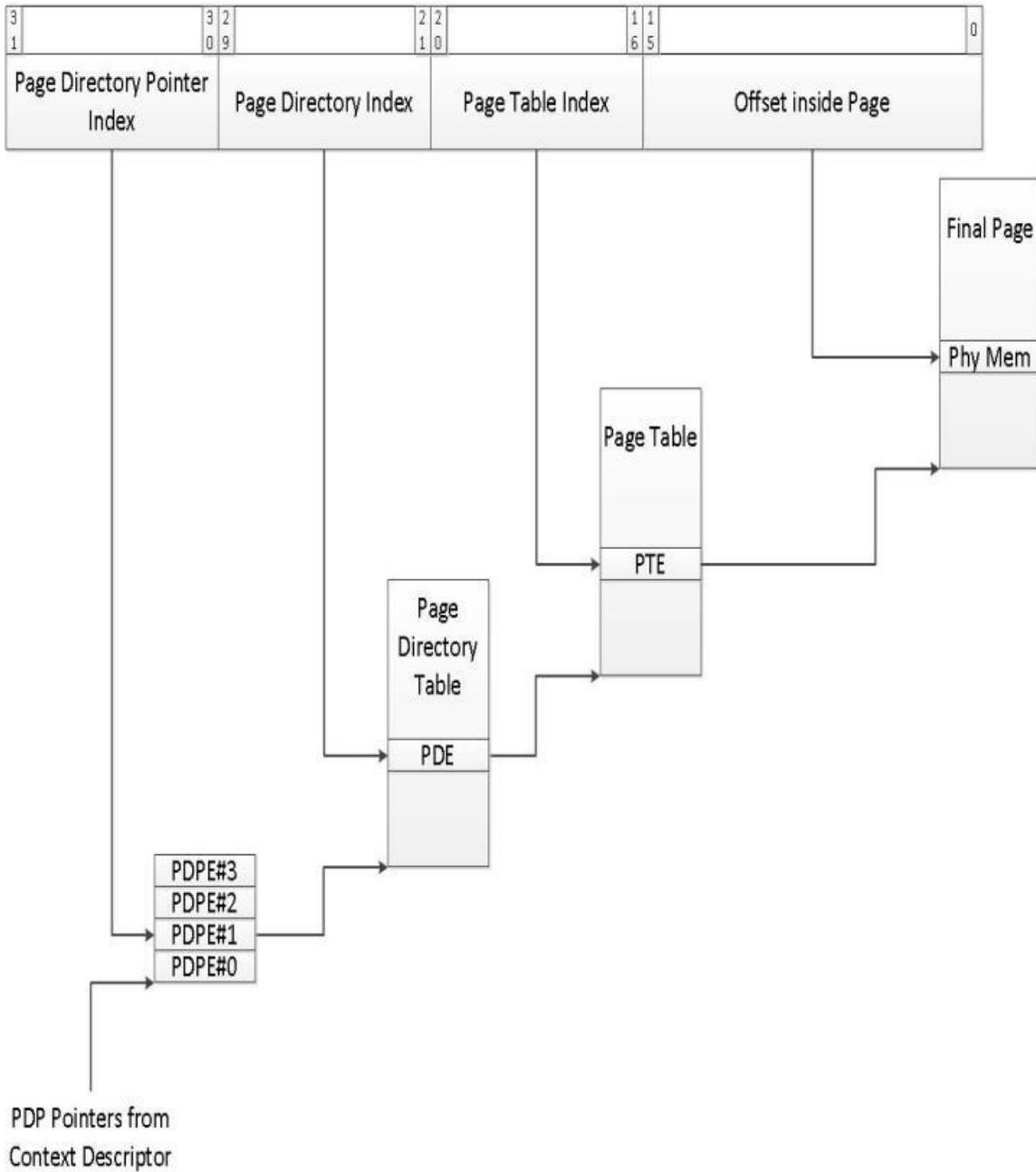


Bits	Field	Description
7	PAT: Page Attribute	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
6:5	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (<i>and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry</i>) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	It must be "1" to point to a 64KB Page.

* HAW = 39 for client, and 46 for server.

Walk with 64KB Page

64KB Page size has a slightly different usage for how PTEs are selected for the corresponding 64KB page. In page table every 16th entry (PTE#0, PTE#16, PTE#32....PTE#496) should be used to index. This is calculated using address[21:16] & "0000". Note that hardware should not make any assumptions for any other PTEs.



Walk with 2MB Page

PPGTT32 does not support 2MB pages.

Walk with 1GB Page

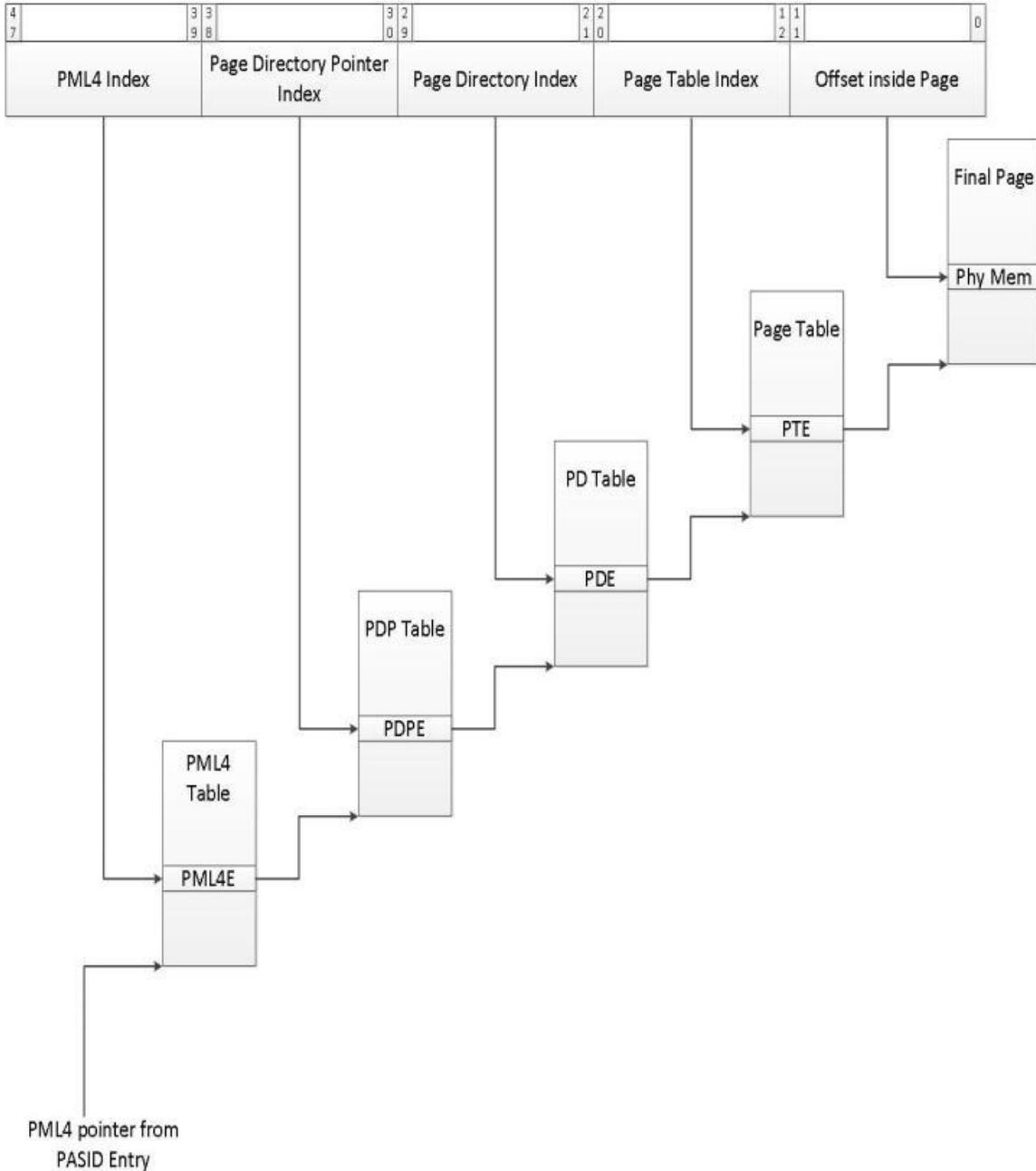
PPGTT32 does not support 1GB pages.



PPGTT for Standard Context (64b VA)

For page walk in advanced mode with 48b VA, we need four levels. The walk starts with a PML4 table pointer given by GFX software and uses the 48b VA as index to consecutive levels of page tables.

The following diagram shows the page walk that is needed for a 4KB page:



A 64-bit (48b canonical) address requires 4-levels of page table format where the context carries a pointer to the highest level page table (PML4 pointer) via PASID. The rest of the walk is a normal page walk thru the various levels.



PDP entry for 1GB Page

63:1	62:0	59:58	57:56	55:54	53:52	51:50	49:48	47:46	45:44	43:42	41:40	39:38	37:36	35:34	33:32	31:30	29:28	27:26	25:24	23:22	21:20	19:18	17:16	15:14	13:12	11:10	9:8	7:6	5:4	3:2	1:0					
Ignored										Address of the 1GB page										Reserved										PAT	Null	1	Ign	PCWg / P	IR / P	PDPE (1GB Page)

Bits	Field	Description
63:HAW*	Ignored	Ignored (h/w does not care about values behind ignored registers)
(HAW-1):30	ADDR: Address	Physical address of 1GB memory page referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
29:10	Ignored	Ignored (h/w does not care about values behind ignored registers)
9	N: Null	For Tile-Resources, private PPGTT tables enables for driver to merge Null Page information to primary (1 st Level) translation tables. If Null=1, the h/w will avoid the memory access and return all zero's for the read access with a null completion, write accesses are dropped.
8	Ignored	Ignored (h/w does not care about values behind ignored registers)
7	PAT: Page Attribute	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
6:5	Ignored	Ignored (h/w does not care about values behind ignored registers)
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	Ignored	Ignored (h/w does not care about values behind ignored registers)
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry) to the memory region controlled by this entry. See a later section for access rights. GPU does not support Supervisor mode contexts.
0	P: Present	It must be "1" to point to a 1GB Page.

Page Directory entry point to the base of the page table and format is given below.

63:1	62:0	59:58	57:56	55:54	53:52	51:50	49:48	47:46	45:44	43:42	41:40	39:38	37:36	35:34	33:32	31:30	29:28	27:26	25:24	23:22	21:20	19:18	17:16	15:14	13:12	11:10	9:8	7:6	5:4	3:2	1:0	
Ignored										Address of page-table										Ignored										R / P	W	PDE Page Table

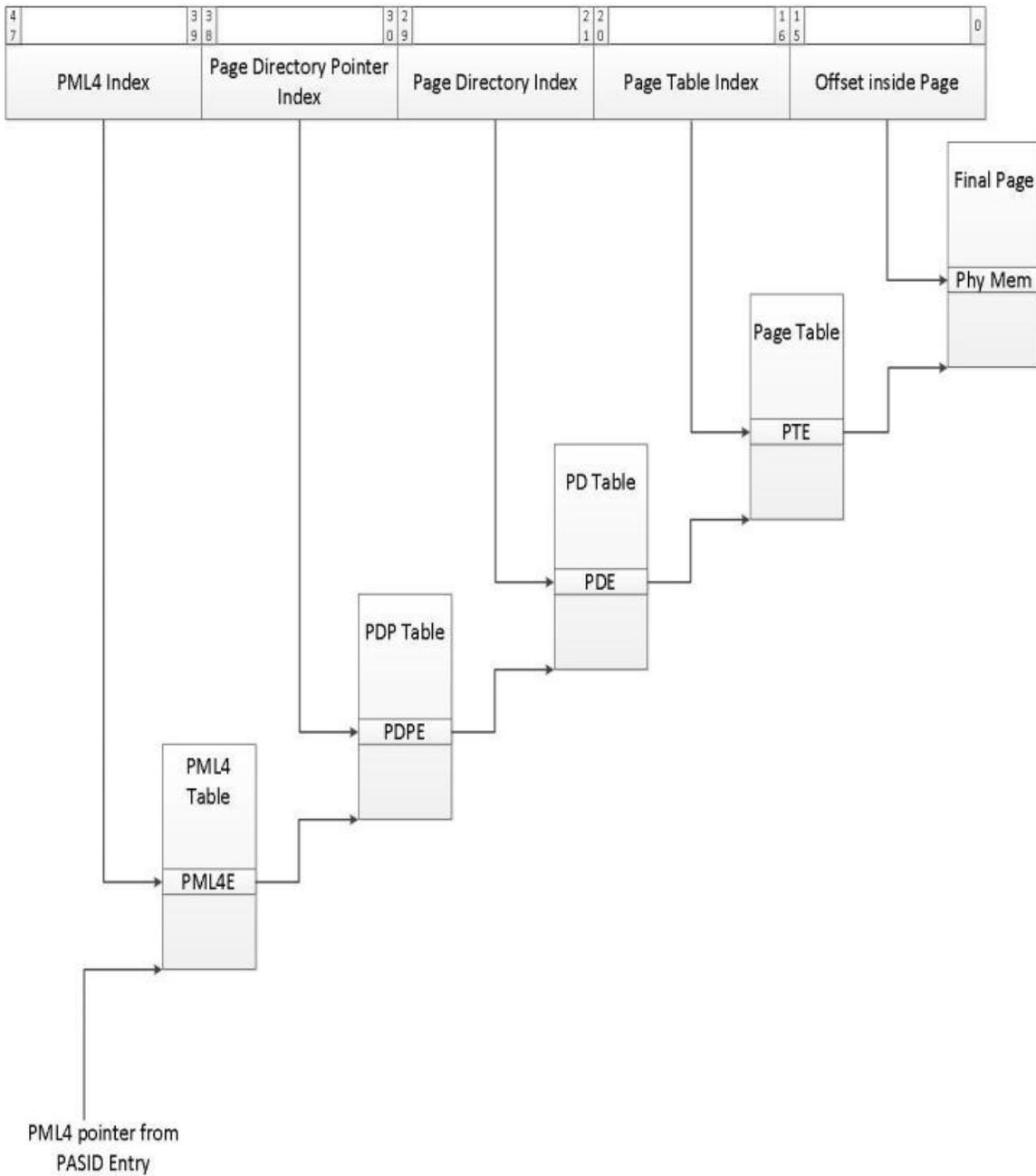


Bits	Field	Description
63:HAW*	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
(HAW-1):12	ADDR: Address	Physical address of 4-KByte aligned page- table referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
11:2	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i> <i>In 64b Legacy, R/W in PD entry can not be used for RO pages</i>
0	P: Present	PDP Entry is present. It must be "1" to point to a page directory pointer table

Page Directory entry for 2MB page:

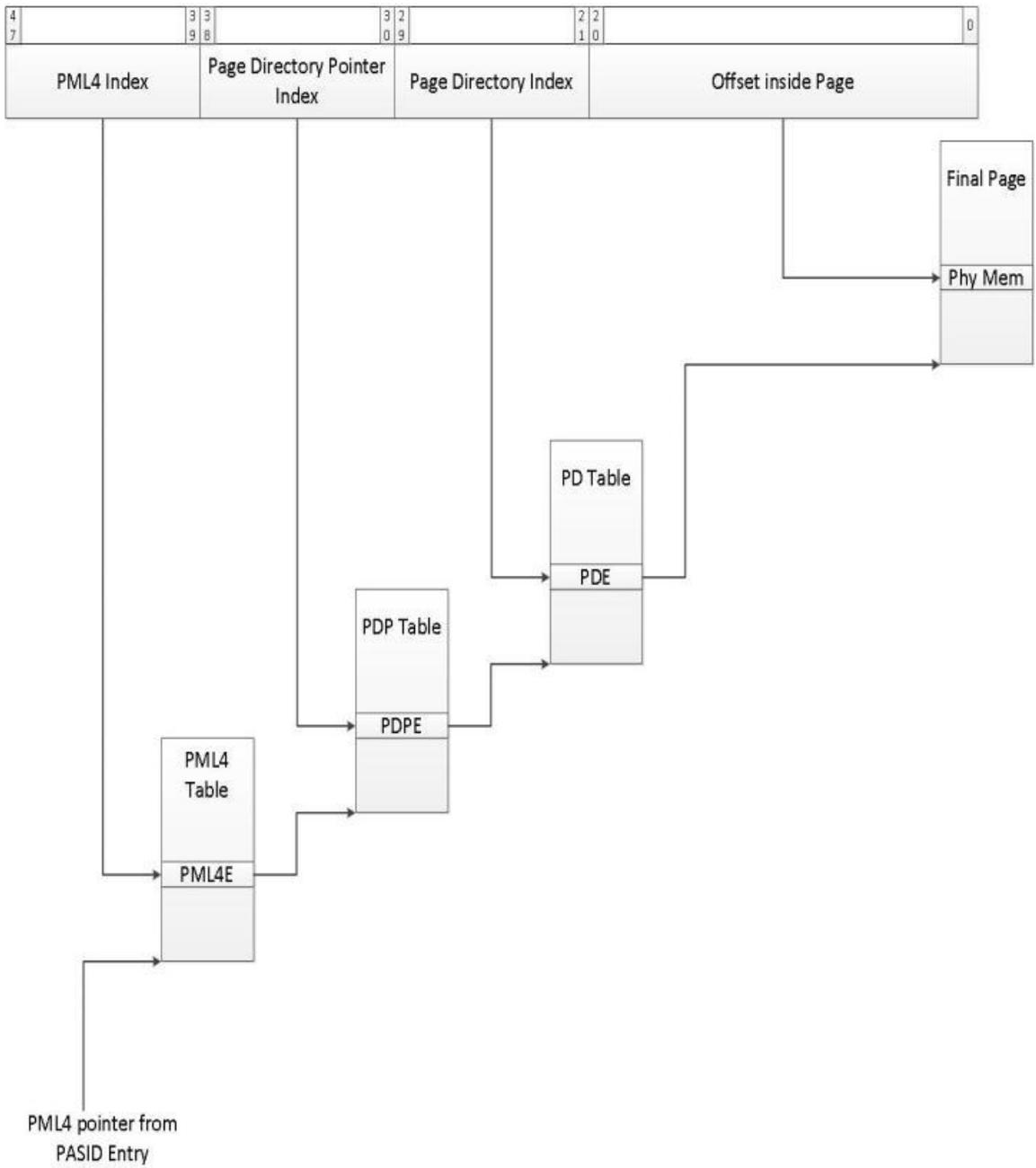


Bits	Field	Description
63:HAW*	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
(HAW-1):21	ADDR: Address	Physical address of 1GB memory page referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
20:10	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
9	N: Null	For Tile-Resources, private PPGTT tables enables for driver to merge Null Page information to primary (1 st Level) translation tables. If Null=1, the h/w will avoid the memory access and return all zero's for the read access with a null completion, write accesses are dropped.
8	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
7	PAT: Page Attribute	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
6:5	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.



Walk with 2MB Page

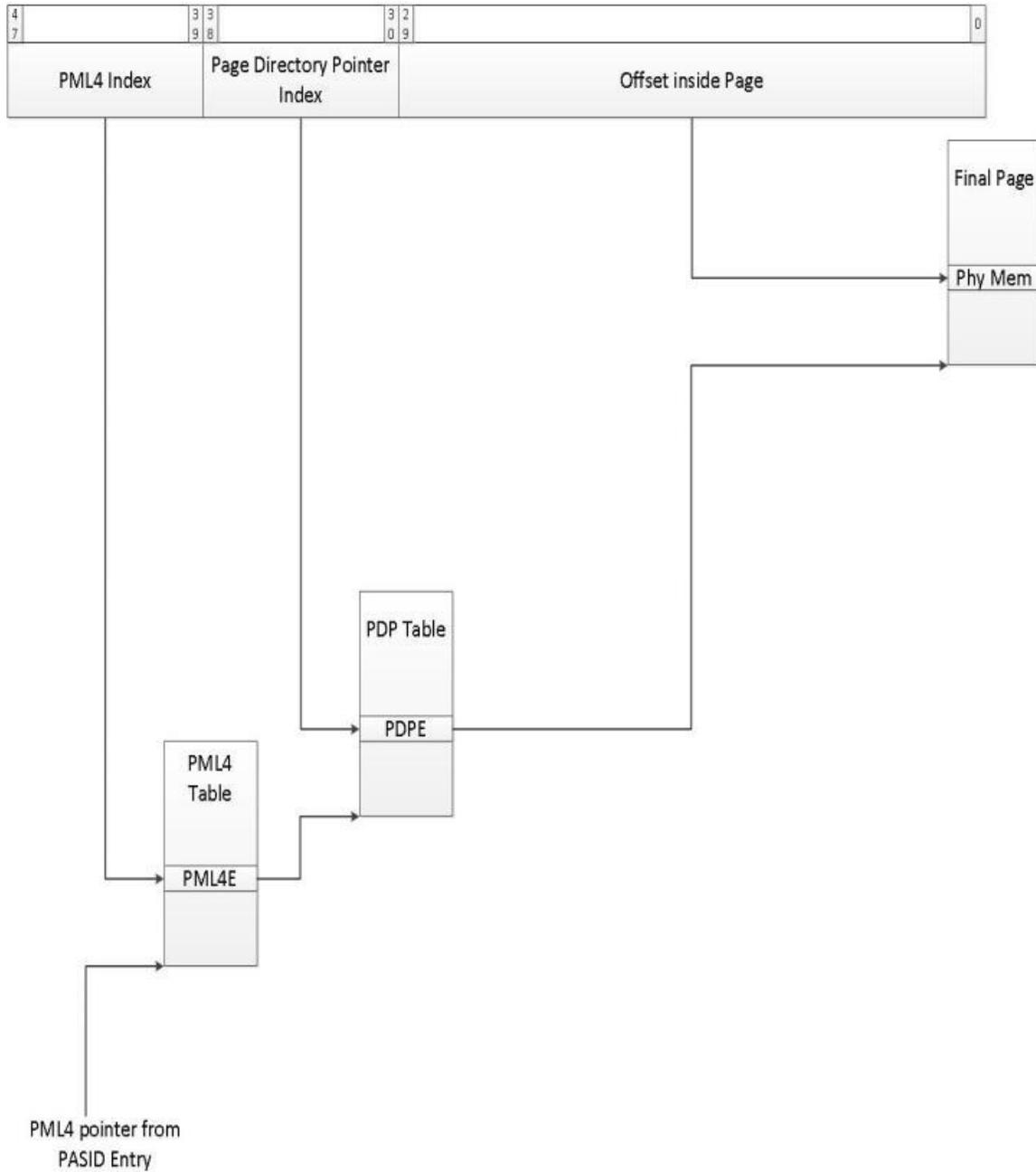
With the 2MB Page walk, last level of the page walk is skipped where the PD entry points to the final page.





Walk with 1GB Page

For the support for 1GB page size, the following mechanism is needed.





Global GTT

The Global GTT mechanism has the distinction of page table entry. Aperture and display will still use the global GTT even if GT core is mapped via per-process GTT.

The PTE format is updated to match per process GTT definitions and GSM is now expanded in size (2MB=>8MB) to cover for the entire 4GB (32b virtual addressing) space. Each entry corresponding to a 4KB page with 2^20 entries in GSM (each with 8B content)

For "MI_update_GTT", the page address provided 31:12 need to be shifted down to 22:3 for the correct QW position within the GGTT.

Page Table Entry

The following page table entry will be used for Global GTT:

6	6	6	6	5	5	5	5	5	5	5	5	5	5			HAW	HAW-1			3	3	2	2	2	2	2	2	2	2	2	1	1	1	1	1	1	1	1	1	1	9	8	7	6	5	4	3	2	1	0
Ignored																Address to Final Page (4KB)																Ignored																P	Global GTT Entry	

Bits	Field	Description
63:HAW*	Ignored	Ignored (h/w does not care about values behind ignored registers)
(HAW-1):12	Address	Physical address of 4KB memory page referenced by this entry.
11:1	Ignored	Ignored (h/w does not care about values behind ignored registers)
0	Present	When set to 1, indicates that this Page Table Entry is Valid, and the corresponding page is Present in physical memory

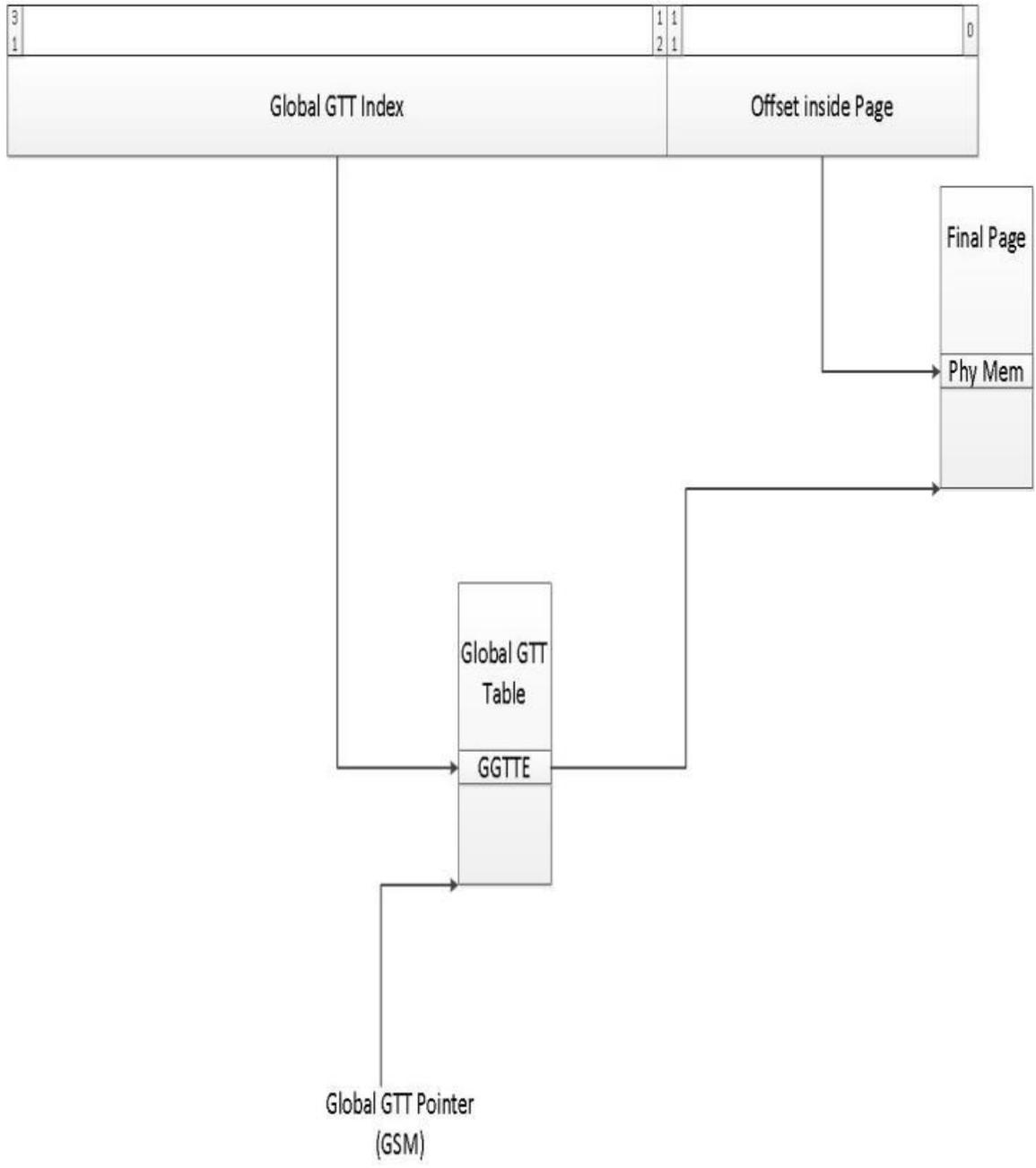
* HAW = 39 for client, and 46 for server.

The GPU accesses GGTT table entries as uncacheable.



Page Walk

The global GTT page walk has a difference and that would be that each entry is 8B (instead of 4B) hence the entry selection needs to be updated once the corresponding Page Table miss read is returned.





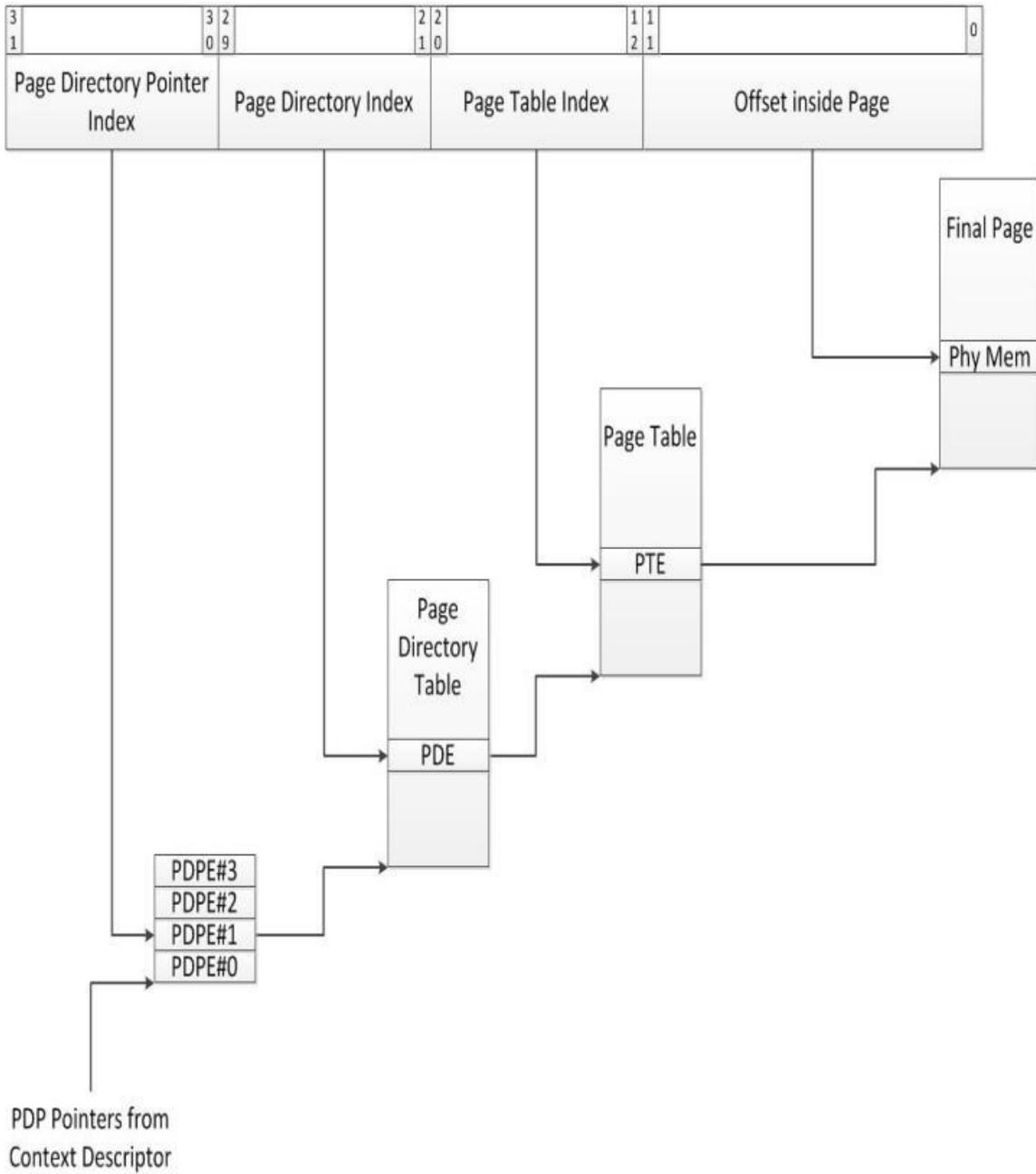
Legacy mode with 32b VA

Page walker is capable supporting 32b VA address with optimized page tables, this is to keep the walk to a single level.

Page Walk in Legacy mode with 32b VA

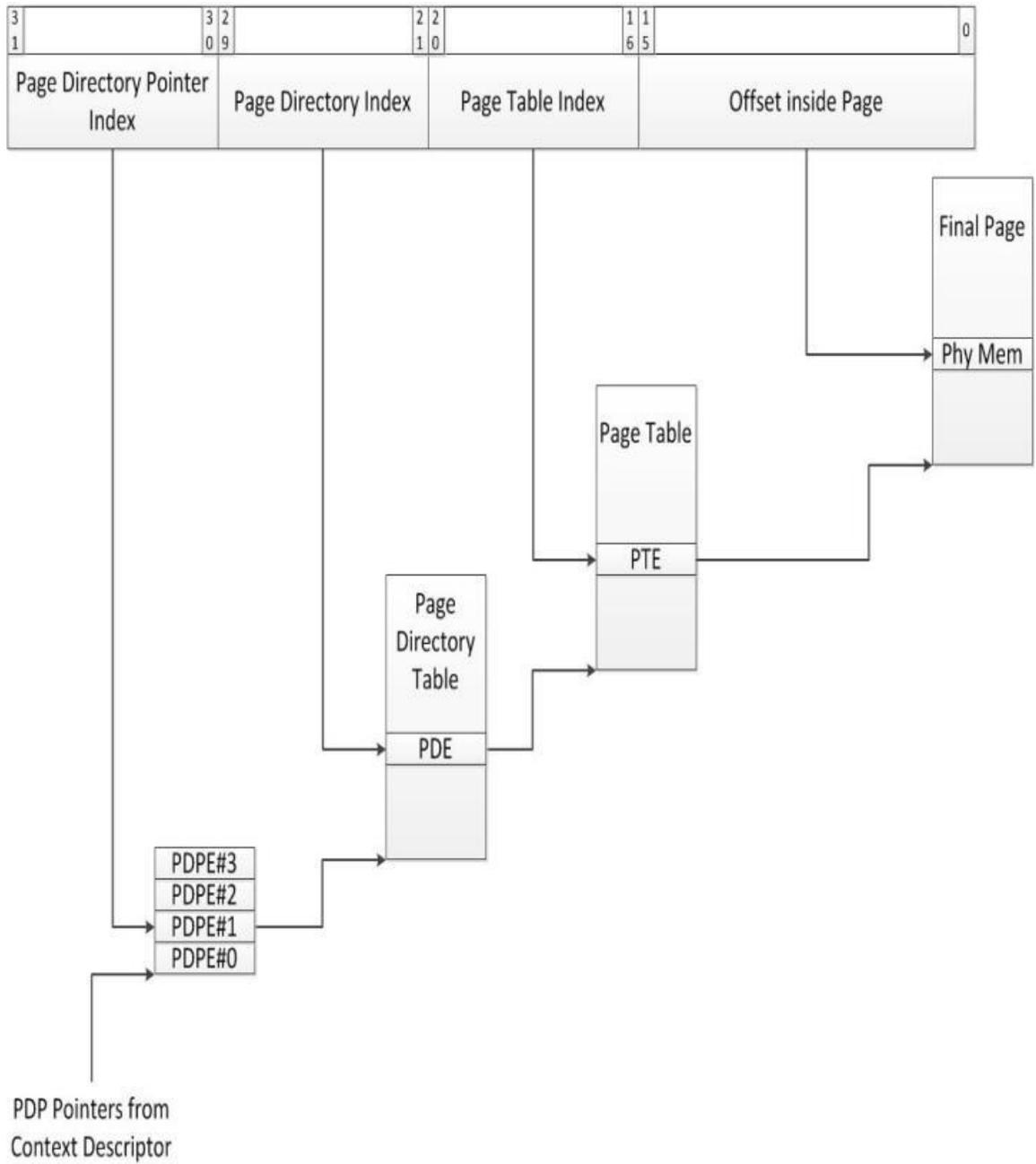
For page walk in legacy mode with 48b VA, we need 2 levels. The walk will start with a PDP pointer provided by the context descriptor and uses the GraphicsAddress as an index to consecutive levels of page tables. Hardware implements 16KB intermediate caches to limit the page walk needed to a single level to have the same sensitivity to latency as previous generations.

The following diagram shows the page walk that is needed for a 4KB page.





Walk with 64KB Page





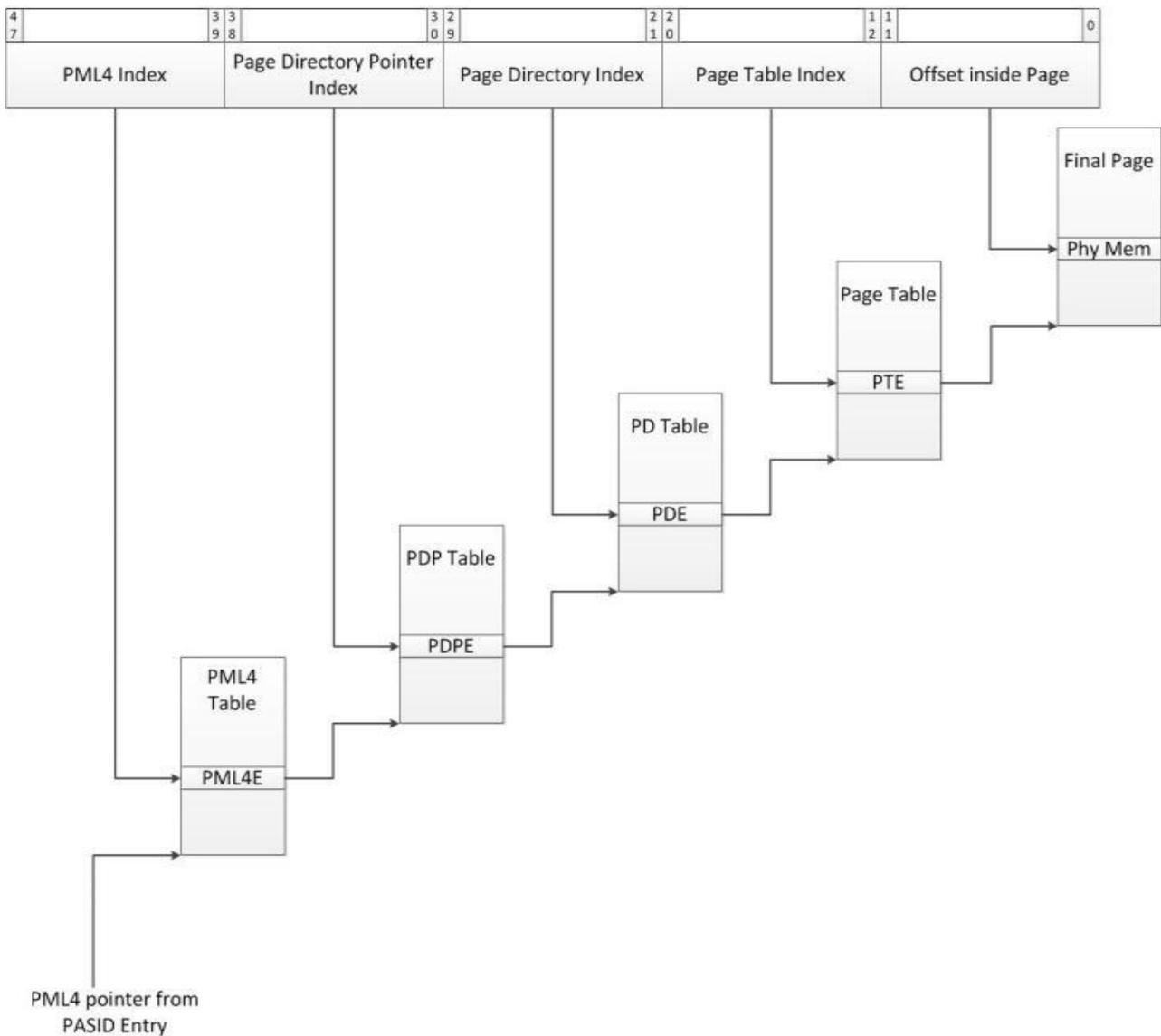
Legacy mode with 48b VA

Legacy mode with 48b VA enables larger virtual space while keeping the page walk compatible with IA32e.

Page Walk in Legacy 48b Mode

For page walk in advanced mode with 48b VA, we need 4 levels. The walk will start with a PML4 table pointer extracted from PASID entry and uses the 48b VA as index to consecutive levels of page tables.

The following diagram shows the page walk that is needed for a 4KB page.





64bit (48b canonical) address requires 4-levels of page table format where the context carries a pointer to highest level page table (PML4 pointer) via PASID. The rest of the walk is normal page walk thru various levels.

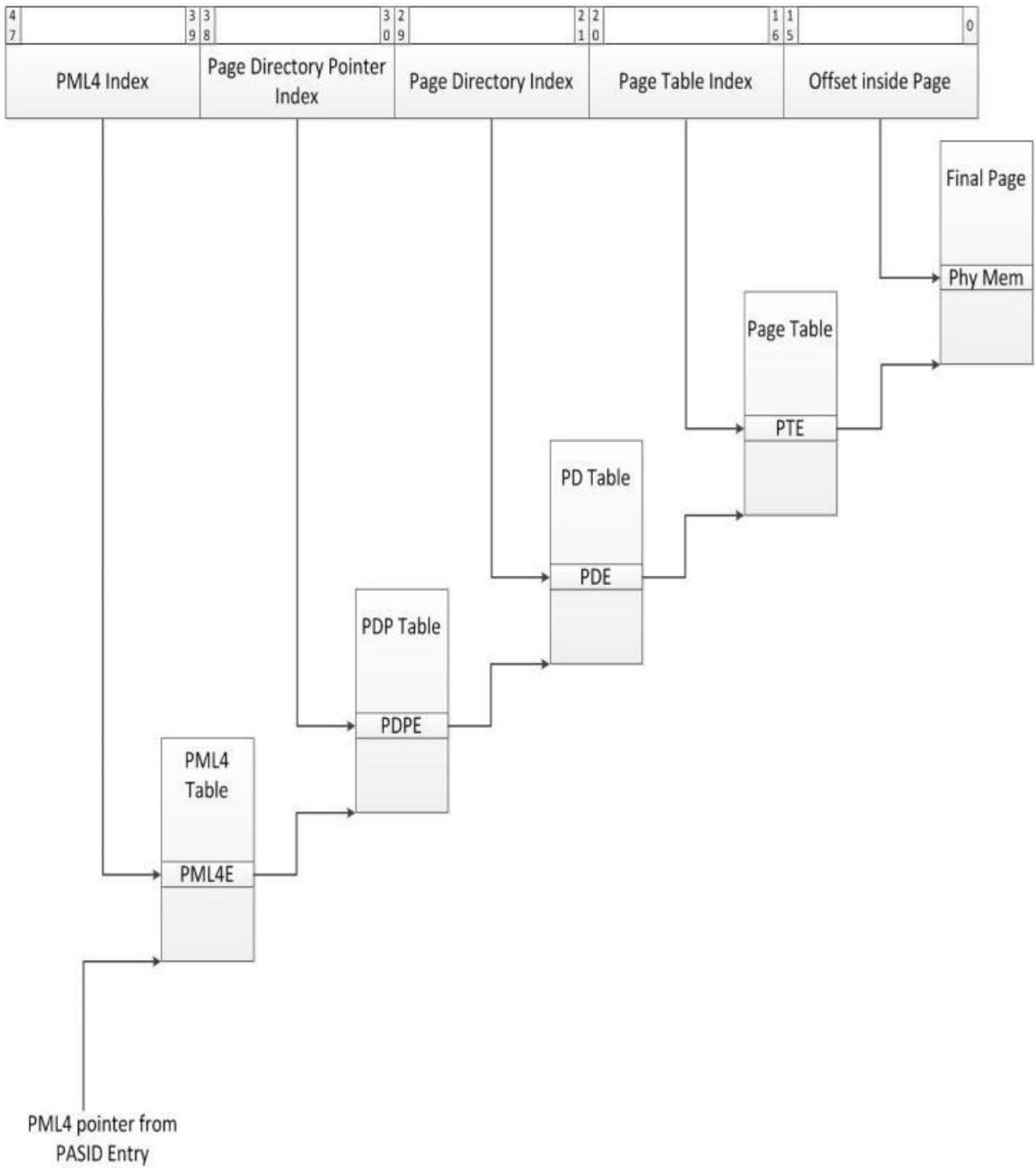
To repurpose the caches the following mechanism will be used:

- 3d: 4KB to store PML4, 4KB as PDP cache, 2x4PD cache
- Media: 4KB to store PML4, 4KB as PDP cache, 2x4PD cache
- VEBOX, Blitter: each with a 4KB acting as PML4, PDP, PD cache.

Note: design can section the 512 entries within 4KB to separate areas for PML4, PDP and PD.

Walk with 64KB Page

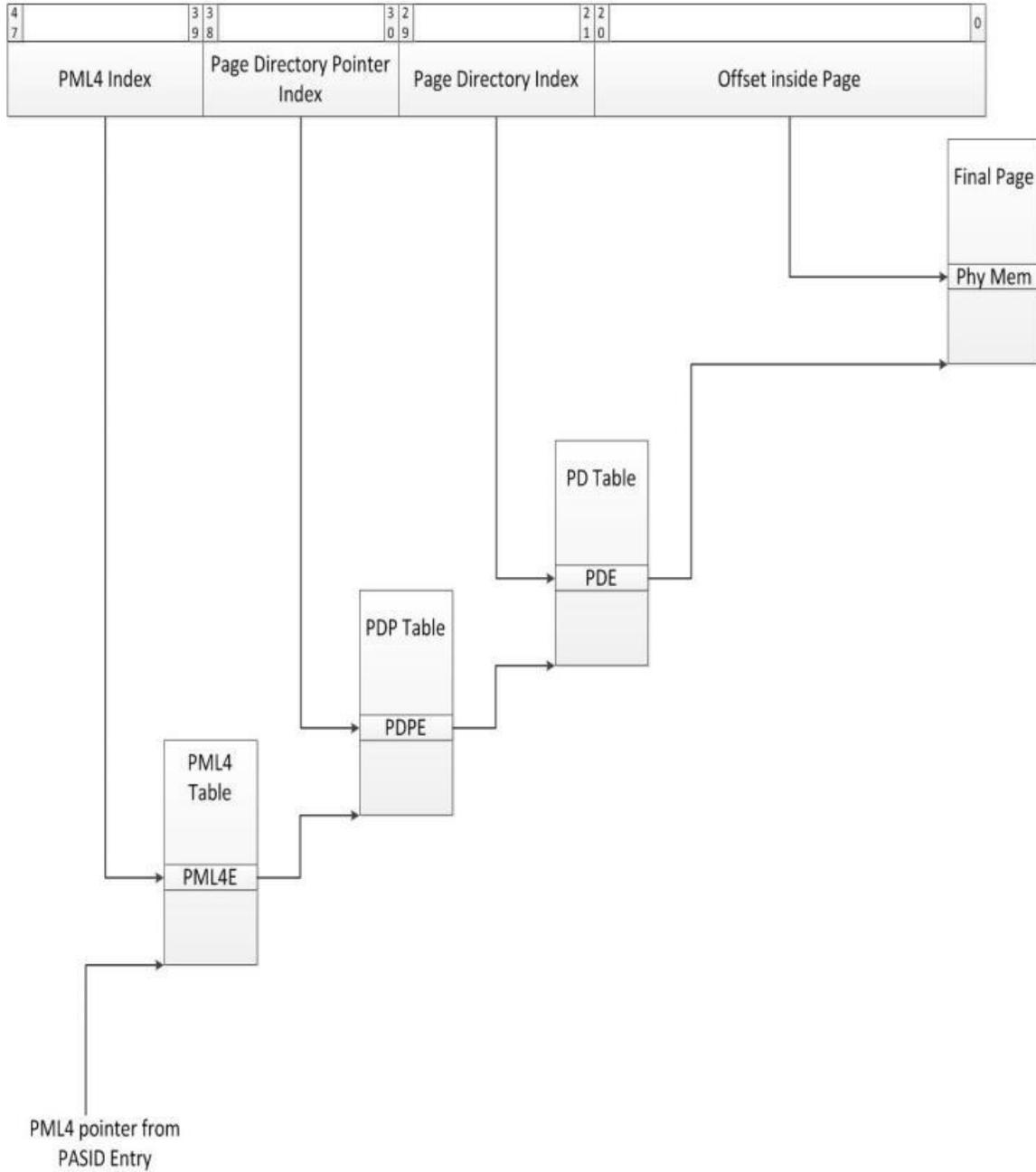
64KB Page size has a slightly different usage for how PTEs are selected for the corresponding 64KB page. In page table every 16th entry (PTE#0, PTE#16, PTE#32....PTE#496) should be used to index. This is calculated using address [20:16]& "0000". Note that hardware should not make any assumptions for any other PTEs. 64K paging in the PTE is indicated by [11] of PDE. When PDE[11] = '1, every 16th PTE entry is read (by masking Adr[15:12] bits).





Walk with 2MB Page

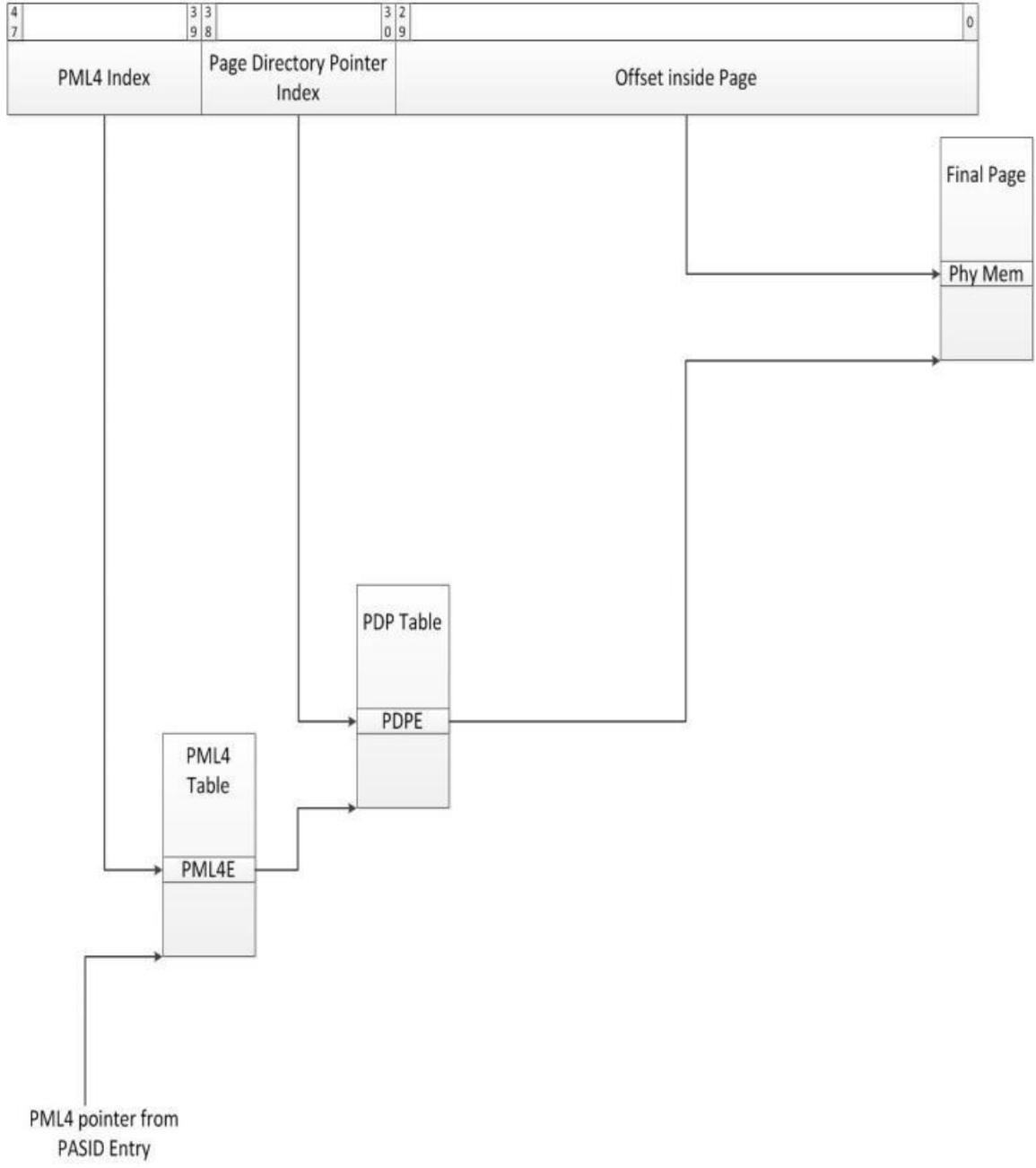
With the 2MB Page walk, last level of the page walk is skipped where the PD entry points to the final page.





Walk with 1GB Page

For the support for 1GB page size, the following mechanism is needed.

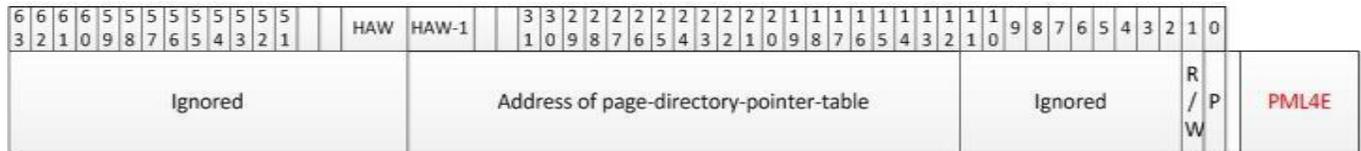




Pointer to PML4 table

In legacy mode, pointer to PML4 table is provided via the context descriptor.

PML4E: Pointer to PDP Table



Bits	Field	Description
63:HAW*	Ignored	Ignored (h/w does not care about values behind ignored registers)
(HAW-1):12	ADDR: Address	Physical address of 4-KByte aligned page-directory-pointer table referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
11:2	Ignored	Ignored (h/w does not care about values behind ignored registers)
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	PML4 Entry is present. It must be "1" to point to a page directory pointer table

* HAW = 39 for client, and 46 for server.

PDPE: Pointer to PD Table

PDP entry is used to locate the page directory. IA32e supports 1GB pages, the PDPE has a mechanism to identify a way to say whether this PDPE represents a pointer to page directory or to a contiguous 1GB physical memory.



PDPE for PD

6	6	6	5	5	5	5	5	5	5	5			HAW	HAW-1		3	3	2	2	2	2	2	2	2	2	2	1	1	1	1	1	1	1	1	1	9	8	7	6	5	4	3	2	1	0
Ignored														Address of page-directory-table														Ignored				R	P	PDPE											
																																/		Page											
																																W		Directory											

Bits	Field	Description
63:HAW*	Ignored	Ignored (h/w does not care about values behind ignored registers)
(HAW-1):12	ADDR: Address	Physical address of 4-KByte aligned page-directory table referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
11:2	Ignored	Ignored (h/w does not care about values behind ignored registers)
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry) to the memory region controlled by this entry. Access rights are described later. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	PDP Entry is present. It must be "1" to point to a page directory pointer table

* HAW = 39 for client, and 46 for server.



PDPE for 1GB Page

63	62	61	60	59	58	57	56	55	54	53	52	51			HAW	HAW-1			31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Ignored														Address of the 1GB page		Reserved														PAT	Null	1	Ign	CD	PWT	IR	Rn	PDPE (1GB Page)												

Bits	Field	Description
63:HAW*	Ignored	Ignored (h/w does not care about values behind ignored registers)
(HAW-1):30	ADDR: Address	Physical address of 1GB memory page referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
29:10	Ignored	Ignored (h/w does not care about values behind ignored registers)
9	N: Null	For Tile-Resources, private PPGTT tables enables for driver to merge Null Page information to primary (1 st Level) translation tables. If Null=1, the h/w will avoid the memory access and return all zero's for the read access with a null completion, write accesses are dropped.
8	Ignored	Ignored (h/w does not care about values behind ignored registers)
7	PAT: Page Attribute	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
6:5	Ignored	Ignored (h/w does not care about values behind ignored registers)
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	Ignored	Ignored (h/w does not care about values behind ignored registers)
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	This bit must be "1" to point to a valid Page.

* HAW = 39 for client, and 46 for server.

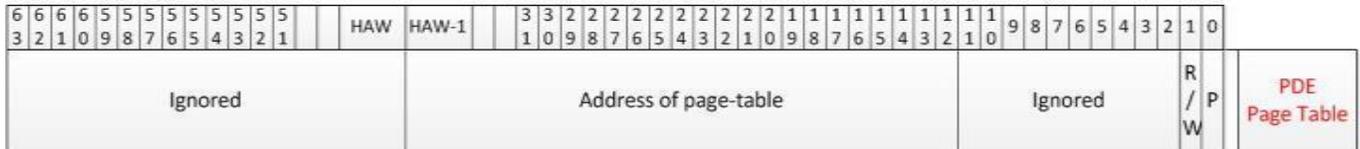


PD: Pointer to Page Table

This section describes the following:

- PDE for Page Table
- PDE for 2 MB Page

PDE for Page Table



Bits	Field	Description
63:HAW*	Ignored	Ignored (h/w does not care about values behind ignored registers)
(HAW-1):12	ADDR: Address	Physical address of 4-KByte aligned page- table referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
11:2	Ignored	Ignored (h/w does not care about values behind ignored registers)
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	PDP Entry is present. The value must be "1" to point to a page directory pointer table.

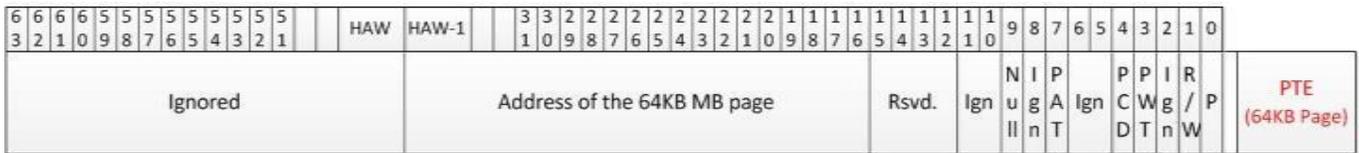
* HAW = 39 for client, and 46 for server.



Bits	Field	Description
		GPU does not support Supervisor mode contexts.
0	P: Present	It must be "1" to point to a 1GB Page.

* HAW = 39 for client, and 46 for server.

PTE: Page Table Entry for 64KB Page



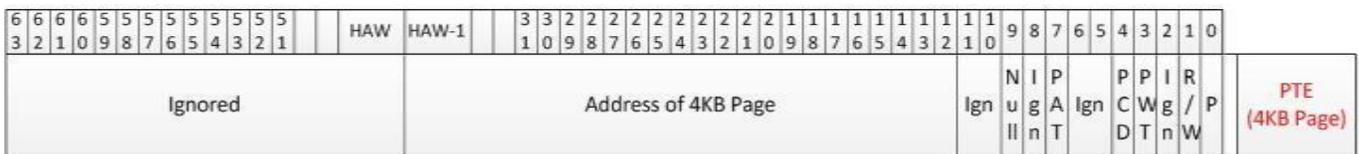
Bits	Field	Description
63:HAW*	Ignored	Ignored (h/w does not care about values behind ignored registers)
(HAW-1):16	ADDR: Address	Physical address of 64KB memory page referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
15:10	Ignored	Ignored (h/w does not care about values behind ignored registers)
9	N: Null	For Tile-Resources, private PPGTT tables enables for driver to merge Null Page information to primary (1 st Level) translation tables. If Null=1, the h/w will avoid the memory access and return all zero's for the read access with a null completion, write accesses are dropped.
8	Ignored	Ignored (h/w does not care about values behind ignored registers)
7	PAT: Page Attribute	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
6:5	Ignored	Ignored (h/w does not care about values behind ignored registers)
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.



Bits	Field	Description
2	Ignored	Ignored (h/w does not care about values behind ignored registers)
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry) to the memory region controlled by this entry. See a later section for access rights. GPU does not support Supervisor mode contexts.
0	P: Present	It must be "1" to point to a 64KB Page.

* HAW = 39 for client, and 46 for server.

PTE: Page Table Entry for 4KB Page



Bits	Field	Description
63:HAW*	Ignored	Ignored (h/w does not care about values behind ignored registers)
(HAW-1):12	ADDR: Address	Physical address of 64KB memory page referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
11:10	Ignored	Ignored (h/w does not care about values behind ignored registers)
9	N: Null	For Tile-Resources, private PPGTT tables enables for driver to merge Null Page information to primary (1 st Level) translation tables. If Null=1, the h/w will avoid the memory access and return all zero's for the read access with a null completion, write accesses are dropped.
8	Ignored	Ignored (h/w does not care about values behind ignored registers)
7	PAT: Page Attribute	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
6:5	Ignored	Ignored (h/w does not care about values behind ignored registers)
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.



Bits	Field	Description
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (<i>and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry</i>) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	It must be "1" to point to a 4KB Page.

* HAW = 39 for client, and 46 for server.

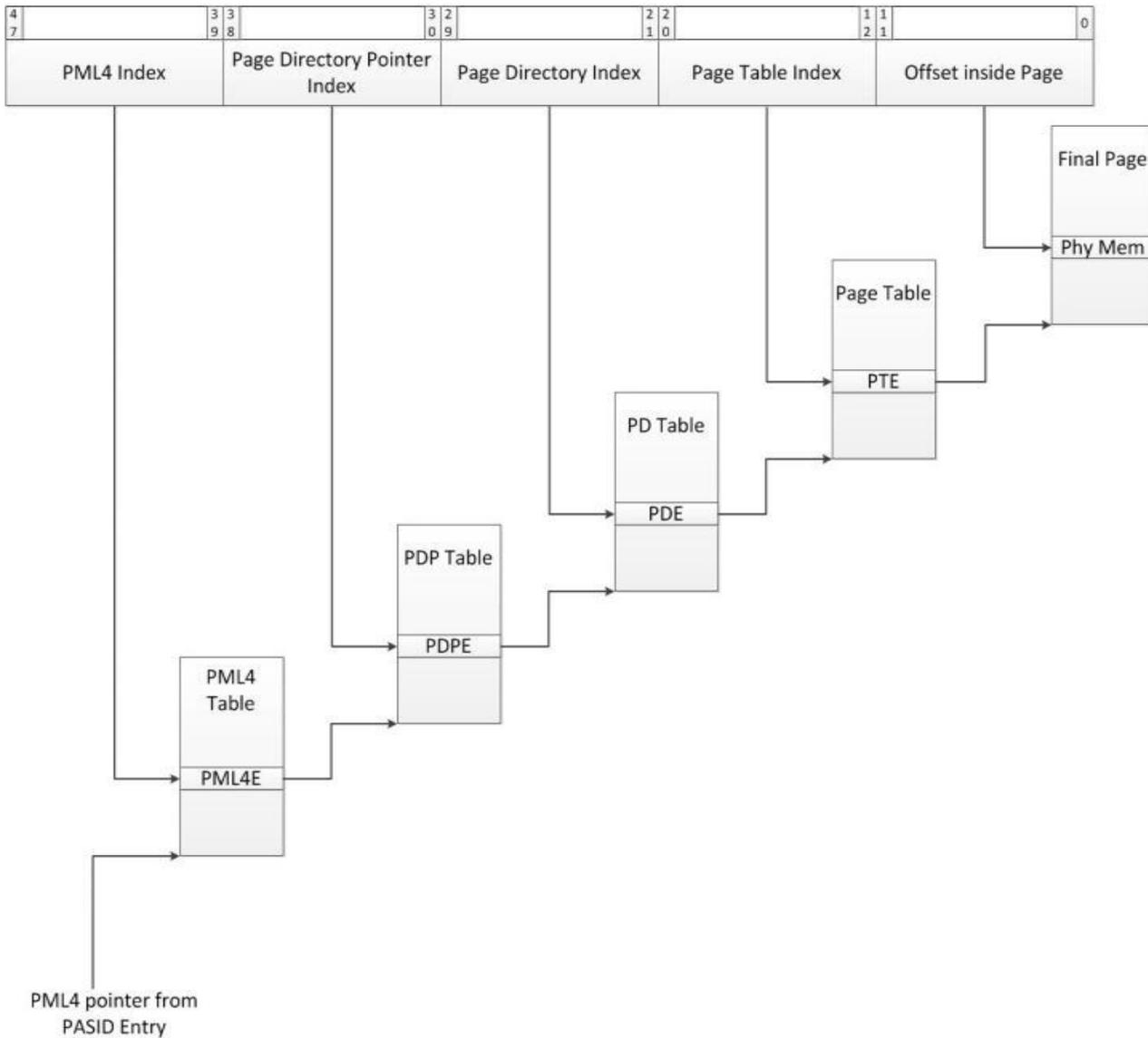
Advanced mode with 48b VA and IA32e Support

In advanced mode, per process GTT mechanism supports IA32e compatible page tables. Paging mechanism is controlled via IOMMU which shall be owned by OS or GFX driver (not both at the same time).

Page Walk in Advanced Mode

For page walk in advanced mode with 48b VA, we need 4 levels. The walk will start with a PML4 table pointer extracted from PASID entry and uses the 48b VA as index to consecutive levels of page tables.

The following diagram shows the page walk that is needed for a 4KB page.



64bit (48b canonical) address requires 4-levels of page table format where the context carries a pointer to highest level page table (PML4 pointer) via PASID. The rest of the walk is normal page walk thru various levels.

To repurpose the caches the following mechanism will be used:

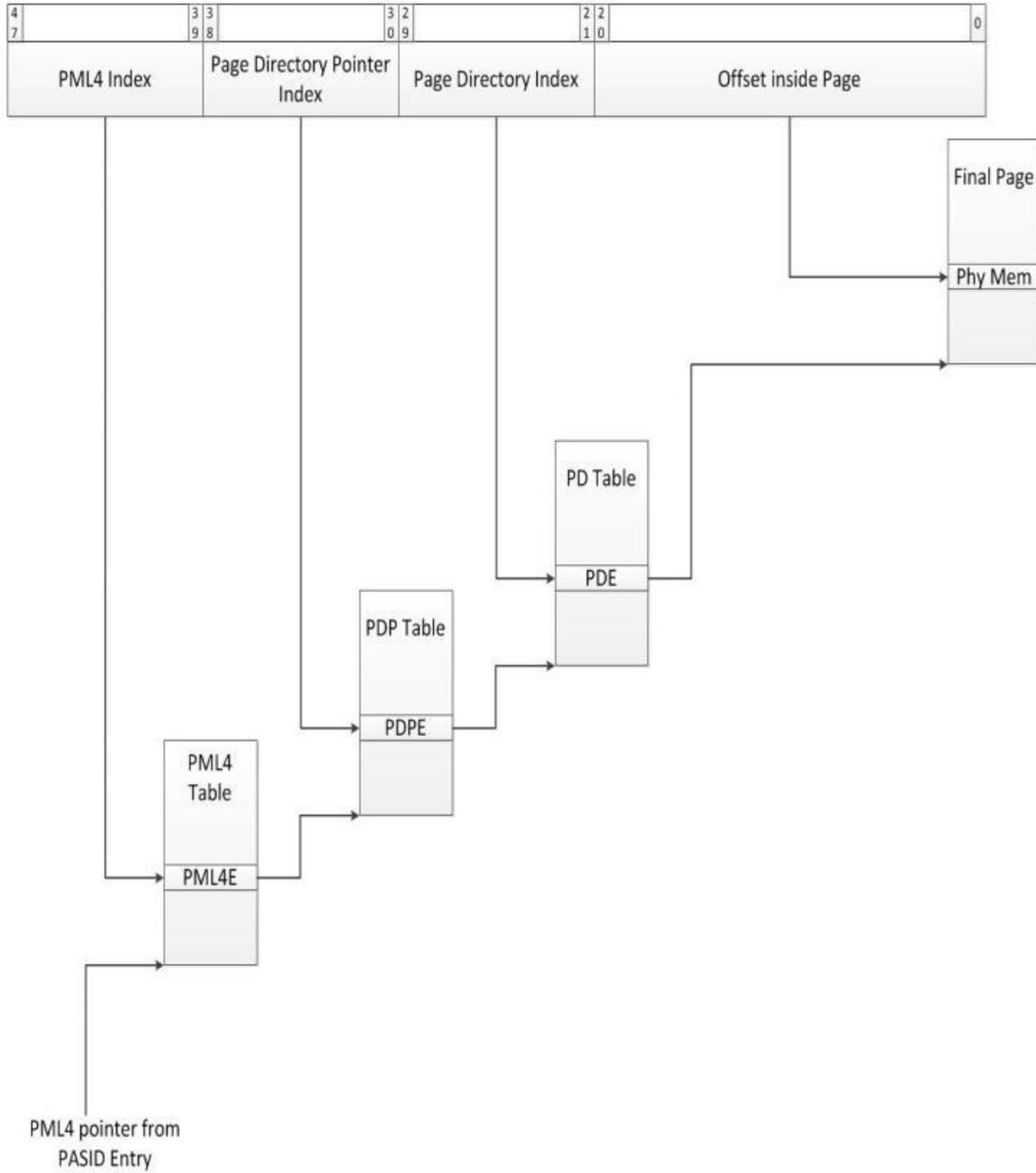
- 3d: 4KB to store PML4, 4KB as PDP cache, 2x4PD cache
- Media: 4KB to store PML4, 4KB as PDP cache, 2x4PD cache
- VEBOX, Blitter: each with a 4KB acting as PML4, PDP, PD cache.

Note: design can section the 512 entries within 4KB to separate areas for PML4, PDP and PD.



Walk with 2MB Page

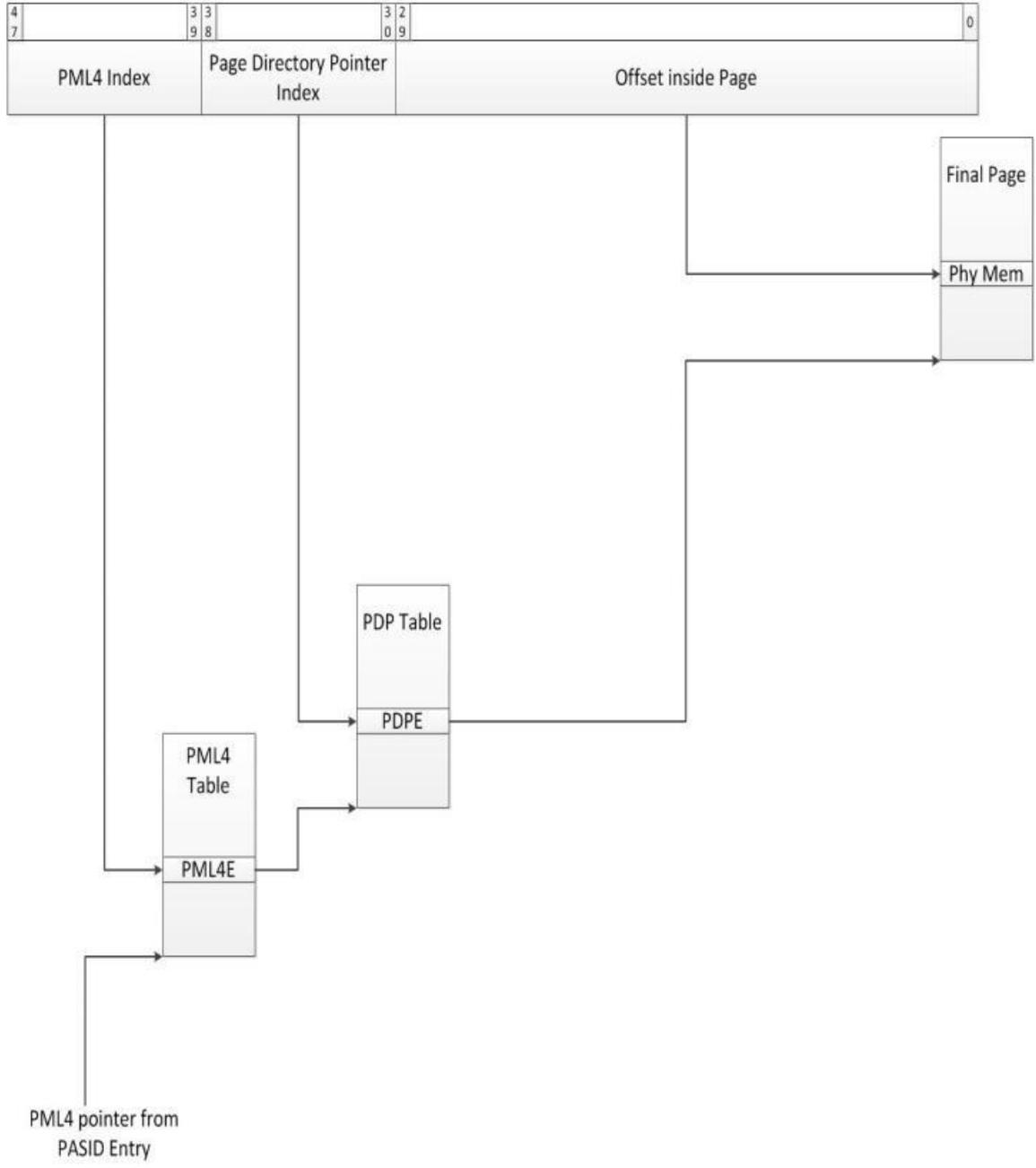
With the 2MB Page walk, last level of the page walk is skipped where the PD entry points to the final page.





Walk with 1GB Page

For the support for 1GB page size, the following mechanism is needed.





Bits	Field	Description
10	EA: Extended Access	Extended Access bit is added for devices to separate accesses from IA cores. If EAFE=1 in the relevant PASID-entry, this bit indicates whether this entry has been used for address translation by device. It is the devices responsibility to set this bit. If EAFE=0 in the relevant PASID-entry, this bit is ignored. This bit applies to GPU Only.
9:8	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
7	<i>Reserved</i>	<i>Reserved (must return 0's)</i>
6	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
5	A: Accessed	A-bit needs to be managed as the table entry being accessed. Hardware needs to set this bit for the first access to the region defined with this page table entry. See later sections for A/D-bit management.
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry. GPU does not support any memory type but WB when accessing paging structures.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry. GPU does not support any memory type but WB when accessing paging structures.
2	U/S: User/Supervisor	User vs supervisor access rights. If 0, requests with user-level privilege are not allowed to the memory region controlled by this entry. See section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (<i>and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry</i>) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	PDP Entry is present. It must be "1" to point to a page directory pointer table

* HAW = 39 for client, and 46 for server.

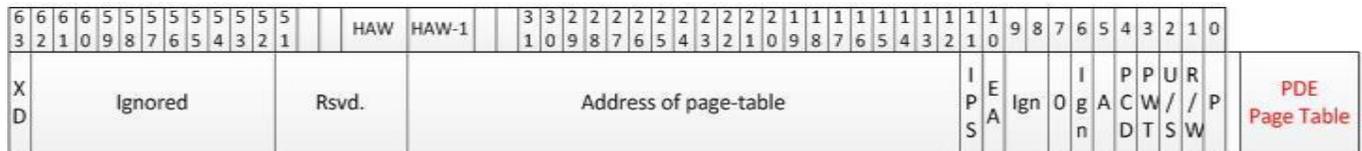


Bits	Field	Description
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	U/S: User/Supervisor	User vs supervisor access rights. If 0, requests with user-level privilege are not allowed to the memory region controlled by this entry. See section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (<i>and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry</i>) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	The value must be "1" to point to a 1GB Page.

* HAW = 39 for client, and 46 for server.

PD: Pointer to Page Table

PDE for Page Table



Bits	Field	Description
63	XD: Execute Disable	If NXE=1 in the relevant extended-context-entry, execute permission is not granted for requests to the memory region controlled by this entry when XD=1.
62:52	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
51:HAW*	<i>Reserved</i>	<i>Reserved (must return 0's)</i>
(HAW-1):12	ADDR: Address	Physical address of 4-KByte aligned page table referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.



Bits	Field	Description
11	IPS	If FL64KPE=1 in the corresponding PASID entry, the page table referenced by this PD entry with IPS=1 translates into 64KB pages. If IPS=0, the page table referenced here translates into 4KB pages. If FL64KPE=0 in the corresponding PASID entry, the IPS value is ignored and the page table referenced by this entry translates into 4KB pages.
10	EA: Extended Access	Extended Access bit is added for devices to separate accesses from IA cores. If EAFE=1 in the relevant PASID-entry, this bit indicates whether this entry has been used for address translation by device. It is the devices responsibility to set this bit. If EAFE=0 in the relevant PASID-entry, this bit is ignored. This bit applies to GPU Only.
9:8	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
7	<i>Reserved</i>	<i>Reserved (must return 0's)</i>
6	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
5	A: Accessed	A-bit needs to be managed as the table entry being accessed. Hardware needs to set this bit for the first access to the region defined with this page table entry. See later sections for A/D-bit management.
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry. GPU does not support any memory type but WB when accessing paging structures.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry. GPU does not support any memory type but WB when accessing paging structures.
2	U/S: User/Supervisor	User vs supervisor access rights. If 0, requests with user-level privilege are not allowed to the memory region controlled by this entry. See section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (<i>and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry</i>) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	PD Entry is present. It must be "1" to point to a page directory pointer table

* HAW = 39 for client, and 46 for server.



PDE for 2MB Page

63	62	61	60	59	58	57	56	55	54	53	52	51	50	49	48	47	46	45	44	43	42	41	40	39	38	37	36	35	34	33	32	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0						
X D														HAW		HAW-1		Address of the 2MB page														Reserved														PAT	EAg	I	G	1	D	A	C	W	/	/	P	P	U	R	P	D	T	S	W	P	D	E	(2MB Page)

Bits	Field	Description
63	XD: Execute Disable	If NXE=1 in the relevant extended-context-entry, execute permission is not granted for requests to the memory region controlled by this entry when XD=1.
62:52	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
51:HAW*	<i>Reserved</i>	<i>Reserved (must return 0's)</i>
(HAW-1):21	ADDR: Address	Physical address of 1GB memory page referenced by this entry. This field is treated as Guest Physical Address (GPA) when Nested translations are enabled (NESTE=1) in the relevant extended-context entry.
20:13	Reserved	<i>Reserved (must return 0's)</i>
12	PAT: Page Attribute	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
11	Ignored/Reserved	Ignored/not used by hardware
10	EA: Extended Access	Extended Access bit is added for devices to separate accesses from IA cores. If EAFE=1 in the relevant PASID-entry, this bit indicates whether this entry has been used for address translation by device. It is the devices responsibility to set this bit. If EAFE=0 in the relevant PASID-entry, this bit is ignored. This bit applies to GPU Only.
9	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
8	G: Global	If PGE=1 in the corresponding context table entry, this field can be set by s/w to indicate that the memory region pointed by this entry can be considered global <i>Global paging is not used by GPU.</i>
7	Page Size	Must be 1 to indicate 2MB page.
6	D: Dirty	D-bit needs to be managed by h/w as the table entry is accessed with a successful write transaction. See later sections for A/D-bit management.
5	A: Accessed	A-bit needs to be managed as the table entry being accessed. Hardware needs to set this bit for the first access to the region defined with this page table entry. See later sections for A/D-bit management.



Bits	Field	Description
10	EA: Extended Access	Extended Access bit is added for devices to separate accesses from IA cores. If EAFE=1 in the relevant PASID-entry, this bit indicates whether this entry has been used for address translation by device. It is the devices responsibility to set this bit. If EAFE=0 in the relevant PASID-entry, this bit is ignored. This bit applies to GPU Only.
9	<i>Ignored</i>	<i>Ignored (h/w does not care about values behind ignored registers)</i>
8	G: Global	If PGE=1 in the corresponding context table entry, this field can be set by s/w to indicate that the memory region pointed by this entry can be considered global <i>Global paging is not used by GPU.</i>
7	PAT: Page Attribute	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
6	D: Dirty	D-bit needs to be managed by h/w as the table entry is accessed with a successful write transaction. See later sections for A/D-bit management.
5	A: Accessed	A-bit needs to be managed as the table entry being accessed. Hardware needs to set this bit for the first access to the region defined with this page table entry. See later sections for A/D-bit management.
4	PCD: Page level cache disable	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory-pointer table referenced by this entry.
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	U/S: User/Supervisor	User vs supervisor access rights. If 0, requests with user-level privilege are not allowed to the memory region controlled by this entry. See section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (<i>and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry</i>) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	It must be "1" to point to a 64KB Page.

* HAW = 39 for client, and 46 for server.



Bits	Field	Description
3	PWT: Page level Write-through	For devices operating in the processor coherency domain, this field indirectly determines the memory type used to access the page directory- pointer table referenced by this entry.
2	U/S: User/Supervisor	User vs supervisor access rights. If 0, requests with user-level privilege are not allowed to the memory region controlled by this entry. See section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
1	R/W: Read/Write	Write permission rights. If 0, write permission not granted for requests with user-level privilege (<i>and requests with supervisor-level privilege, if WPE=1 in the relevant extended-context-entry</i>) to the memory region controlled by this entry. See a later section for access rights. <i>GPU does not support Supervisor mode contexts.</i>
0	P: Present	It must be "1" to point to a 4KB Page.

* HAW = 39 for client, and 46 for server.

GTT Cache

Processor graphics page walker implements a GTT cache which holds the remaining entries that are read as a cacheline but not used for the immediate page walk. This is only applicable in case of leaf walks and not including the 2MB/1GB page sizes. When SW enables the use of 2MB/1GB page sizes, it must disable the GTT cache.

When running advanced context, GTT cache must be disabled. This is needed as the GTT cache is not snooped, and no A/D bit updates are done on the PTEs that are cached in the GTT Cache.

GFX Page Walker (GAM)

GPU supports various engines behind the same page walker. These streams/contexts are identified Client level IDs which are carried via the arbitration pipeline. Page walker using look-up tables does the correct selection for the page tables in case of concurrent context are running at the same time.

There are two different types of page table types:

Global graphics translation table (GGTT) is a single common translation table used for all processes.

There can be many Per-process graphics translation table (PPGTT). This requires an additional lookup for translation.



Virtual Memory Structure	Memory Location
Global (GGTT)	GSM Only
Per-Process (PPGTT) – private	2 to4-level, Page Tables anywhere
Per-Process (IA32e) – shared	4 levels, Page Tables anywhere

IA32e compatible PPGTT is added enable SVM (shared virtual memory) functions.

Context Definition for GFX Page Walker

Page Walker blocks need details about the context to decide on what type of page tables are used, what the error handling cases are, and many other details to operate. The information is passed to Page Walker (GAM) by the respective command streamer/DMA.

GAM needs to support the following engines:

- Render
- Media (VDBOX) x2
- Blit
- VEBOX x2

The following fields are sent to GAM:

- **Context Type** (4 bits):
 - **Legacy vs Advanced Context.** Defines the context type and qualifies the rest of the fields. Same field may mean something else between the *Legacy vs Advanced* context. There is no restriction for what type of context can run in either combination.
 - *Requests without address-space-identifier (Legacy Context):* These are the normal memory requests from endpoint devices. These requests typically specify the type of access (read/write/atomics), targeted DMA address/size, and identity of the device originating the request.
 - *Requests with address-space-identifier (Advanced Context):* These are memory requests with added information identifying the targeted process address space from endpoint devices supporting virtual memory capabilities. Beyond attributes in normal requests, these requests specify the targeted process address space identifier (PASID), and extended attributes such as Execute-Requested (ER) flag (to indicate reads that are instruction fetches), and Privileged-mode-Requested (PR) flag (to distinguish user versus supervisor access). For details, refer to the Process Address Space ID (PASID) Capability in the PCI-Express specifications.
 - **A/D Support Enable.** Access and Dirty bits are used when OS is managing the page tables and has been added to IA32e compatible page walk. Context defines whether A/D bits need to be managed via GPU (only applicable in Advanced Context).



- **Privileged Context Support.** Enables GPU to be able to run a privileged context which translates into page table accesses regardless of user vs supervisor privileges (only applicable in Advanced Context).
- **32b vs 48b VA Support.** Enables 48b VA in page tables for the page walks. The rest of the HW is seamless to 32b vs 48b VA address walks, however GAM does the check and properly aligns the page walk to address bits. **Note:** Only applicable in Legacy Context. Advanced Context is always 48b.
- **Page Fault Support Model:**
 - *Fault and Hang:* The only supported fault handling mode for legacy context and it is not applicable to advanced mode. Optionally hang can be skipped for HW to make progress.
 - *Fault and Stream (Switch if needed):* Context can survive thru a number of page faults and could be switched out by the scheduler if a certain threshold is reached.
 - *Fault and Halt:* HW detects page fault and reports to SW; the request is flagged in pending queue as "waiting for page response" and is halted until the page response is returned.
- **Function Number** – 3-bit field that defines the function number of the device. GFX device is always on BUS=0 and DEVICE=2. If we are not virtualized, our FUNCTION#=0 however if virtualized function number can be any 8 possible values (i.e. 0-7). The BUS/DEVICE/FUNCTION numbers are used for the initial walk for ROOT and CONTEXT tables.
- **PASID** – Process Address Space Identifier: Use to identify the context that is submitted to HW. We use the PASID in many places where during the page walk (i.e. PASID table look up) or while communicating with SW on page faults. Each engine could be running an independent context with different PASID. The page walker should have a mechanism to be able to cache at least some number of PASID table entries (matching the engine count) for faster walk.
- **Context ID** (Queue ID, Bell ID) – Context ID is used to further qualify the running context beyond the PASID. PASID is given per process, and same process may allocate multiple queues to communicate with HW. The only way to further identify the process is to use an additional ID. For GFX HW Context ID could be same as the bell number assigned to it. GAM HW uses the context ID to populate the queue ID field while communicating page faults to SW.
- **Page Table Pointers** – The field could be up to 256 bits (i.e. 4x64bits) to identify the page table pointers associated with the context. For legacy 32b context, the entire 256b is valid representing the 4 PDPTR table entries. For 48b legacy context only the lower 64b is relevant pointing to base of PML4. In case of advanced context, PASID is given in the context definition.



Context Definition Delivery

Context Definition is supposed to be delivered from the corresponding command streamer to GAM and GAM has independent storage for each engine present.

Context Definition is given by *CS to GAM via a new message:

Message: "Context Available"

GAM prepares for new context, cleans up internal state and does the proper fencing. Most of these steps should have been performed when context switch request was done for the previous context, but added here for completeness.

Message: "Context Receive Ready"

GAM is ready for the context. *CS writes all new context values into the descriptor registers. To push all context descriptors CS sends the following message to GAM also indicating new context descriptor is downloaded.

Message: "Context Launched"

GAM does the context requirements and sends the following message to CS to resume its command parser.

Message: Context Confirmed

GAM should send context confirmed message only after PD restore is done. CS waiting for context confirmed message is treated as PD restore busy. Since all clients memory interface are blocked during PD restore it doesn't make any difference if the context confirmed message is send by GAM immediately or after PD restore.



Element Descriptor Register

General Description	Element Information: The register is populated by command streamer and consumed by GAM
Register Offset	See per engine list below.

Bits	Access	Default	Field
63:32	RO	Xh	<p>Context ID: Context identification number assigned to separate this context from others. Context IDs needs to be recycled in such a way that there cannot be two active contexts with the same ID. This is a unique identification number by which a context is identified and referenced.</p>
31:12	RO	Xh	<p>LRCA: Command Streamer Only</p>
11:9	RO	Xh	<p>Function Number: GFX device is considered to be on Bus0 with device number of 2. Function number is normally assigned as 000b.</p>
8	RO	Xh	<p>Privileged Context / GGTT vs PPGTT mode: Differs in legacy vs advanced context modes: In Legacy Context: Defines the page tables to be used. This is how page walker come to know PPGTT vs GGTT selection for the entire context. 0: Use Global GTT 1: Use Per-Process GTT</p> <div style="border: 1px solid black; padding: 5px; margin-top: 10px;"> <p>In Advanced Context: Defines the privilege level for the context. 0: User mode context 1: Supervisor mode context</p> </div>
7:6	RO	Xh	<p>Fault Model: 00b: Fault & Hang.</p> <div style="border: 1px solid black; padding: 5px; margin-top: 10px;"> <p>01b: Fault & Halt/Wait. Advanced Context mode Fault & Halt. If context switching is available, advanced mode is on, Fault & Halt utilizes Advanced Context capabilities as documented in "Memory Views > Page Fault Modes".</p> <p>10b: Fault & Stream & Switch. Advanced context switching will be utilized if it is available.</p> <p>11b: Reserved</p> </div>
5	RO	Xh	<p>Deeper IA coherency Support: In Advanced Context: Defines the level of IA coherency: 0: IA coherency is provided at LLC level for all streams of GPU. 1: IA coherency is provided at L3 level for EU data accesses of GPU.</p>



Bits	Access	Default	Field
4	RO	Xh	A&D Support / 32&64b Address Support: Differs in legacy vs advanced context modes: In Legacy Context: Defines 32b vs 64b (48b canonical) addressing format: 0: 32b addressing format. 1: 64b (48b canonical) addressing format. In Advanced Context: Defines A&D bit support: 0: A&D bit management in page tables is NOT supported. 1: A&D bit management in page tables is supported.
3	RO	Xh	Context Type: Legacy vs Advanced Defines the context type. 0: Advanced Context: Defines the rest of the advanced capabilities (i.e. OS page table support, fault models, ...). Note that advanced context is not bounded to GPGPU. 1: Legacy Context: Defines the context as legacy mode. Note: Bits [8:4] differs in functions when legacy vs advanced context modes are selected.
2	RO	Xh	FR: Command streamer specific.
1	RO	Xh	Scheduling Mode: 0: Indicates Ring Buffer mode of scheduling. 1: Indicates execlist mode of scheduling.
0	RO	Xh	Valid: Indicates that element descriptor is valid. If GAM is programmed with an invalid descriptor, it continues but flags an error.

PDP0/PML4/PASID Descriptor Register

General Description	PDP0/PML4/PASID: The register is populated by command streamer and consumed by GAM. It contains one of the 3 values which is determined by looking at the element descriptor.
Register Offset	See per engine list below

Bits	Access	Default	Field
63:0	RO	Xh	PDP0/PML4/PASID: This register can contain three values which depend on the element descriptor definition. PASID[19:0]: Populated in the first 20bits of the register and selected when Advanced Context flag is set. PML4[38:12]: Pointer to base address of PML4 and selected when Legacy Context flag is set and 64b address support is selected PDP0[38:12]: Pointer to one of the four page directory pointer (lowest) and defines the first 0-1GB of memory mapping <i>Note: This is a guest physical address</i>



PDP1 Descriptor Register

General Description	PDP1: The register is populated by command streamer and consumed by GAM. It contains one of the pointers to PD.
Register Offset	See per engine list below

Bits	Access	Default	Field
63:12	RO	Xh	PDP1: Pointer to one of the four page directory pointer (lowest+1) and defines the first 1-2GB of memory mapping <i>Note: This is a guest physical address</i>

PDP2 Descriptor Register

General Description	PDP2: The register is populated by command streamer and consumed by GAM. It contains one of the pointers to PD.
Register Offset	See per engine list below

Bits	Access	Default	Field
63:12	RO	Xh	PDP2: Pointer to one of the four page directory pointer (lowest+2) and defines the first 2-3GB of memory mapping <i>Note: This is a guest physical address</i>

PDP3 Descriptor Register

General Description	PDP3: The register is populated by command streamer and consumed by GAM. It contains one of the pointers to PD.
Register Offset	See per engine list below



Bits	Access	Default	Field
63:12	RO	Xh	PDP3: Pointer to one of the four page directory pointer (lowest+3) and defines the first 3-4GB of memory mapping <i>Note: This is a guest physical address</i>

List of Registers and Command Streamers

The following registers are message registers and not written directly by SW.

Engine	Offset	Description
Render	x4400h	Element Descriptor Register
	x4408h	PDP0/PML4/PASID Descriptor Register
	x4410h	PDP1 Descriptor Register
	x4418h	PDP2 Descriptor Register
	x4420h	PDP3 Descriptor Register
Media0 (VDBOX0)	x4440h	Element Descriptor Register
	x4448h	PDP0/PML4/PASID Descriptor Register
	x4450h	PDP1 Descriptor Register
	x4458h	PDP2 Descriptor Register
	x4460h	PDP3 Descriptor Register
Media1 (VDBOX1)	x4480h	Element Descriptor Register
	x4488h	PDP0/PML4/PASID Descriptor Register
	x4490h	PDP1 Descriptor Register
	x4498h	PDP2 Descriptor Register
	x44A0h	PDP3 Descriptor Register
VEBOX	x44C0h	Element Descriptor Register
	x44C8h	PDP0/PML4/PASID Descriptor Register
	x44D0h	PDP1 Descriptor Register
	x44D8h	PDP2 Descriptor Register
	x44E0h	PDP3 Descriptor Register
Blitter	x4500h	Element Descriptor Register
	x4508h	PDP0/PML4/PASID Descriptor Register
	x4510h	PDP1 Descriptor Register
	x4518h	PDP2 Descriptor Register
	x4520h	PDP3 Descriptor Register

**Messages:**

Message Name	Source	Destination	Category	Address	Bit	Mask Bit	Value	Description
Context Available	CS (GT)	GAM (GT)	self-clear	4004	0	16	1	Signal request from CS to GAM as new context is about to be submitted.
Context Receive Ready	GAM (GT)	CS(GT)	self-clear	3438	0	16	1	Signal ack from GAM to CS in response to Context Available message from CS to GAM.
Context Launched	CS (GT)	GAM (GT)	self-clear	4004	1	17	1	Signal indicator to GAM that context descriptor is pushed.
Context Confirmed	GAM (GT)	CS(GT)	self-clear	3438	1	17	1	Signal ack from GAM to CS in response to Context Launched message from CS to GAM.
Context Available	BCS (GT)	GAM (GT)	self-clear	4014	0	16	1	Signal request from CS to GAM as new context is about to be submitted.
Context Receive Ready	GAM (GT)	BCS(GT)	self-clear	23438	0	16	1	Signal ack from GAM to BCS in response to Context Available message from BCS to GAM.
Context Launched	BCS (GT)	GAM (GT)	self-clear	4014	1	17	1	Signal indicator to GAM that context descriptor is pushed.
Context Confirmed	GAM (GT)	BCS(GT)	self-clear	23438	1	17	1	Signal ack from GAM to BCS in response to Context Launched message from BCS to GAM.
Context Available	VECS (GT)	GAM (GT)	self-clear	4010	0	16	1	Signal request from CS to GAM as new context is about to be submitted.
Context Receive Ready	GAM (GT)	VECS(GT)	self-clear	1B438	0	16	1	Signal ack from GAM to VECS in response to Context Available message from VECS to GAM.
Context Launched	VECS (GT)	GAM (GT)	self-clear	4010	1	17	1	Signal indicator to GAM that context descriptor is pushed.
Context Confirmed	GAM (GT)	VECS(GT)	self-clear	1B438	1	17	1	Signal ack from GAM to VECS in response to Context Launched message from VECS to GAM.
Context Available	VCS0 (GT)	GAM (GT)	self-clear	4008	0	16	1	Signal request from CS to GAM as new context is about to be submitted.



Message Name	Source	Destination	Category	Address	Bit	Mask Bit	Value	Description
Context Receive Ready	GAM (GT)	VCS0(GT)	self-clear	13438	0	16	1	Signal ack from GAM to VCS in response to Context Available message from VCS to GAM.
Context Launched	VCS0 (GT)	GAM (GT)	self-clear	4008	1	17	1	Signal indicator to GAM that context descriptor is pushed.
Context Confirmed	GAM (GT)	VCS0(GT)	self-clear	13438	1	17	1	Signal ack from GAM to VCS in response to Context Launched message from VCS to GAM.
Context Available	VCS1 (GT)	GAM (GT)	self-clear	400C	0	16	1	Signal request from CS to GAM as new context is about to be submitted.
Context Receive Ready	GAM (GT)	VCS1(GT)	self-clear	1D438	0	16	1	Signal ack from GAM to VCS in response to Context Available message from VCS to GAM.
Context Launched	VCS1 (GT)	GAM (GT)	self-clear	400C	1	17	1	Signal indicator to GAM that context descriptor is pushed.
Context Confirmed	GAM (GT)	VCS1(GT)	self-clear	1D438	1	17	1	Signal ack from GAM to VCS in response to Context Launched message from VCS to GAM.

Updating Page Table Pointers (aka PD Load)

In case of legacy context, driver is allowed to add/remove pages as long as it is ensured that h/w is not using these entries. Previous flows allowed for a mid-context PD load to update the PD entries and directed h/w to reload updated entries.

Pre-loading of Page Directory Entries (PD load) for 32b legacy mode is not supported. PD entries are loaded on demand when there is a miss in the PDE cache of the corresponding page walker. Any new page additions by the driver are transparent to the HW, and the new page translations will be fetched on demand. However, any removal of the pages by the driver should initiate a TLB invalidation to remove the stale entries.



Page Walker (GAM) Reset

GAM gets all the engine specific resets as well as device and bus resets to manage its internal logic domains. It is the expectation of SW when a particular GPU engine (i.e. Render, Media...) gets reset, all its related HW is cleared and comes out fresh for reprogramming. That is true for most of the logic with the exception of some shared HW blocks. The following blocks require additional steps (post-reset) from SW to further clean-up the HW:

- **Hardware TLBs:** The caching structures for the page walks are often considered shared resources. The expectation for GFX driver to clear the TLBs via "TLB Invalidate" prior to re-using the engine post reset. This is the same process that was followed on previous GPU generations.
- **Page Requests:** At the time of the reset HW may have outstanding page requests to SW for page faulted accesses. These requests could be at any level hence it is required for SW to clear these paging requests pre/post-engine reset. Engine reset ensures that no new page requests are sent from HW. Page requests could be at the "page request queue" in memory where they could be mapped to a dummy page post engine reset completion. Or they could be at the MMIO registers which will block completion of the reset; it is up to SW to service paging request interrupts without waiting for the completion of reset request.

Device reset (FLR) covers most of the page walker. However there are exceptions where all messaging towards the rest of the system (system agent) should not be impacted by it.

All external interactions and IOMMU related blocks are kept under bus (system) reset. GAM keeps the following blocks outside the device reset:

- IOMMU registers and content
- All system agent messaging structures (including translation enable flows, root pointer structures, and DMA fault reporting pieces)

An engine being reset also means the particular context that engine is running, is complete or taken out. This requires GAM to decrement the PASID_State Counter if the engine was running a PASID based (advanced) context. For FLR (device reset) similar requirement holds. In case of device reset, GAM needs to decrement all the PASID state counters that are active on the GPU before completing the sequence.



TLB Caching and Management

As compared to previous generation of TLB entry, IA32e page translation entry is quite different. At every stage of the page different bits need to be taken into account and proper treatment is required. Regardless of PPGTT vs GGTT usage, the paging entry has the same format. Linear address are translated using a hierarchy of in-memory paging structures located using the contents of CR3. IA-32e paging translates 48-bit linear addresses to 52-bit physical addresses.¹ Although 52 bits corresponds to 4 PBytes, linear addresses are limited to 48 bits; at most 256 TBytes of linear-address space may be accessed at any given time. IA-32e paging may map linear addresses to 4-KByte pages, 2-MByte pages, or 1-GByte pages.



TLB Caches

The caching structures are separated as following with the architectural view, this is also applicable to s/w view of these caches when it comes to invalidations.

Context Cache - CC

This is the storage for context table entry which is achieved as part of root/context table walk.

Context cache can also be invalidated with directed invalidations, where HW needs to invalidate the content of the context cache along with all low level caches.

PASID Cache - PC

This is where the HW copy of the PASID table entry is kept and it is per context. This makes it unique for every HW engine that could be running an independent context (per GAM):

- Render/GPGPU
- MFX (VDBOX) – 1
- MFX (VDBOX) – 2
- Video Enhancement (VEBOX) – 1
- Video Enhancement (VEBOX) – 2
- Blitter

The cache content is updated if the corresponding engine is running an advanced context where its page table pointers are accessible via PASID table. In case of legacy context running engine, corresponding PASID Cache entry is not valid. Recommendation is to keep ONE physical storage per engine which is filled/invalidated during the context switch time.

PASID Cache can also be invalidated with the directed invalidations along with low level caches and needs to be re-filled prior to context resuming.

Intermediate Page Walk Caches (PML4, PDP, PD) – PWC

These are the stages where intermediate page walk entries are cached to speed-up/shorten the page walk when final TLB is missed. Each level can be cached separately or along with different levels, the cacheability structures will have programmability to move the boundary of different levels to accommodate more/less on each page walk level. However as a concept, for legacy 32b addressing mode, requirement is to cache 4PDPs along with 4x4KB PDs for certain engines, at least for render and media. The others will use cache concept.

TLB – Final Page Entry

The size of the TLBs has been increased over the previous generation and should be targeting using the following list:



- L3 TLB: 768 TLB entries – This is where all HDC, I\$, Constant, State, and Sampler streams are stored.
- MFX: 512 TLB entries – All Media streams (split 256/256 between two media engines).
- BLT: 32 entries.
- Z: 512 TLB entries – All depth accesses.
- C: 256 (256 TLB entries) – All color accesses.
- FF: 128 (128 TLB entries) – All FF accesses to memory.
- VLF: 32 (32 TLB entries) – Media surface.
- GAV: 64 (64 TLB entries) – Video enhancement.

All TLB entries are increased to 48b to contain larger address as well as the page attributes attached to it.

The max size of a single TLB is 256 entries, larger quantities have to be handled as set-associative storages. Set associativity will be managed by low order page bits (i.e. address#12, address#13, ...).

Both Color and Z TLBs are designed to process a single memory request per cycle. To achieve a higher throughput where concurrent Color or Z read/write's are used, following register bit needs to be enabled: mmio0x04A30h [31]

The size of the L3 TLB is also different between projects. The default TLB entry allocations are:

- (L3TLB-Gfx **640**): L3(**80:0-79**), DC(**100:80-179**), TX(**444:180-623**), GATR(**16:624-639**)
- (L3TLB-GPGPU **640**): L3(**80:0-79**), DC(**460:80-539**), TX(**100:540-639**)

For giving more TLB resources for both DC and TX, the following allocations are recommended.

- (L3TLB-Gfx **640**): L3(**80:0-79**), DC(**544:80-623**), TX(**544:80-623**), GATR(**16:624-639**)
- (L3TLB-GPGPU **640**): L3(**80:0-79**), DC(**560:80-639**), TX(**560:80-639**)

TLB Entry Content

When a page walk entry is cached (or loaded prior to context start), certain bits need to be cached as well along with the physical address bits. The treatment on these bits would be considered when a HIT vs MISS decision needs to be made during a look up.

The purpose of caching is to accelerate the paging process by caching individual translations in **translation look-aside buffers (TLBs)**. Each entry in a TLB is an individual translation. Each translation is referenced by a page number. It contains the following information from the paging-structure entries used to translate linear addresses with the page number:

- The physical address corresponding to the page number (the page frame).
- The access rights from the paging-structure entries used to translate linear addresses with the page number:
 - The logical-AND of the R/W flags.
 - The logical-AND of the U/S flags.



- The logical-OR of the XD flags.
- Attributes from a paging-structure entry that identifies the final page frame for the page number (either a PTE or a paging-structure entry in which the PS flag is 1):
 - The dirty flag.
 - The memory type.

PRESENT: This is the same VALID bit description we had in previous page table designs. The lack of present bit (i.e. bit[0]=0) points that rest of the information in the page table entry is being invalid. For some fault models, even NOT PRESENT entries are cached to filter further page faults (*see fault models on caching page faulting entries*). If such entry is cached, there are couple ways that it can be removed from the page tables:

1. LRA selection where the entry becomes a victim for replacement
2. Global or Selective invalidation
3. Page fault response stating the faulting page is now fixed.

R/W Privilege: Certain pages can be allocated as read-only and write operations are not allowed. To make this check work, TLB has to keep the R/W bit. This bit has no affect on read operations; however for write operation privilege needs to be checked. If there is mis-match, the result of the TLB look-up should be a MISS. This does not mean a page fault immediately; the walk has to be re-done as for any TLB MISS result. There are cases OS may change page table privileges without invalidating pages in TLB (*note: all downgrades result in invalidation of the TLB, however upgrades can be done silently hence re-walk is required*). In case where the TLB Miss is due to privilege mis-match, the existing entry from TLB has to be invalidated and page walk will bring in the most up-to-date copy from memory.

The R/W privilege on final frame is generated as a logical-AND process of all upper page walks pointing to this location.

User vs Supervisor Privilege: The GPU typically operates in user mode when it comes to page tables. So the GTT walk can be treated as faulted when GPU encounters a page with supervisor privileges and the context is marked as user mode. The faulted entry can be cached back into TLB with "P" bit off indicating a faulted entry. However the page fault report should carry the correct reason why h/w detected the fault in the first place which was the user vs supervisor privilege. There is an option in context header to define the context as supervisor, than it legal to access supervisor pages.

- This is not stored in TLB

The U/S privilege on final frame is generated as a logical-AND process of all upper page walks pointing to this location.

Accessed Bit: This where a stage of the page walk cannot be used if the accessed bit is not set for that level in the page walk. This is true for both storage into TLB as well as to make progress on the page walk. In order to achieve the process of Accessed bit, every stage of the ppGTT read is done via a new semantics between the GAM and GTI such that GTI can atomically process A-bit w/o running into access violations. The details of the semantics are defined as part of the following sections. The "A" bit does not



need to be stored as part of the TLB, just the fact that a valid page table entry is present in the TLB does mean that h/w took care off the “A” bit at the time the page was brought up to TLB. Note that TLB prefetching is disabled when A-bit management is enabled.

IA32e mode page tables can not co-exist with TLB pre-fetching due to lack of A-bit management for all entries of the line.

- This is not stored in TLB

Dirty Bit: Similar to accessed bit, dirty bit needs to be managed. It is only applicable for “write” accesses. Given there are cases where a TLB entry was acquired as part of a read operation, the presence of D-bit should be maintained with the TLB. This gives us the capability to declare a TLB miss for a write access when the D-bit is not set even though TLB has a valid translation. In such case, The TLB entry needs to be invalidated and the final stage of the walk needs to be re-done to ensure most up-to-date copy of GTT entry is brought into h/w. The operation of Dirty bit update is also atomic similar to A-bit management.

Execute (XD) Bit: XD bit is also present on every stage of the walk and applicable to executable code that GT would be fetching. In the first pass, instruction cache accesses are not allowed to proceed if the corresponding page does not have the execute credentials set properly. Similar treatment of the TLB entry as privilege bits is expected. A page entry that was already cached in TLB and later accessed for instruction space will have to check the XD bit which is also stored in TLB. If mis-match, the end result is a TLB miss and walk has to be re-done replacing the different stages of the walk.

The XD privilege on final frame is generated as a logical-OR process of all upper page walks pointing to this location.

Faulted Bit: There are usage models where the faulted entries are cached in TLB. This is to filter further faults to the same page as opportunistic way to prevent fault storms. When faulted bit is set the address is included in the TLB look up but final treatment is fault filtering. The rest of the bits are used to define what would be the reason for the fault. If the look-up conflicts with the original faulted reason, a re-walk is required. As a basic case, take a read access bringing up a PTE with W-flag cleared. A subsequent write access has a conflict on privilege, and it will perform a re-walk. If the result of the re-walk is W-flag set, then TLB is upgraded and write makes progress. However if the result is still W-flag cleared, the write access will fault and TLB entry will be tagged as a faulted entry with only read-allowed. Subsequent write accesses will be filtered as fault but read accesses should cause a re-walk of the page and if successful, the TLB can be updated with PTE as valid with read-only attribute.

TLB Accessed and Dirty Flags

For any paging-structure entry that is used during linear-address translation, bit 5 is the **accessed** flag. For paging-structure entries that map a page (as opposed to referencing another paging structure), bit 6 is the **dirty** flag. These flags are provided for use by memory-management software to manage the transfer of pages and paging structures into and out of physical memory.

Whenever the processor and/or GPU uses a paging-structure entry as part of linear-address translation, it sets the accessed flag in that entry (if it is not already set).



Whenever there is a write to a linear address, the processor and/or GPU sets the dirty flag (if it is not already set) in the paging-structure entry that identifies the final physical address for the linear address (either a PTE or a paging-structure entry in which the PS flag is 1).

Memory-management software may clear these flags when a page or a paging structure is initially loaded into physical memory. These flags are “sticky,” meaning that, once set, the processor and/or GPU does not clear them; only software can clear them.

A processor and/or GPU may cache information from the paging-structure entries in TLBs and paging-structure caches (see Section 4.10). This fact implies that, if software changes an accessed flag or a dirty flag from 1 to 0, the GPU might not set the corresponding bit in memory on a subsequent access using an affected linear address

Accessed bit is applicable to every stage of the page walk, however the dirty bit is only applicable to final stage of the walk.

The rule states that a particular access cannot be committed until the Accessed and/or Dirty bits are not visible to page management s/w. In order for GPU to follow the rule, GTT accesses (when A/D bits are supported) are going to be done via a special cycle definition between GAM and GTI.

Updating A/D Bits

New atomic operations are added to GAM to GPU interface (GTI) to handle paging entries. GAM has to set the correct atomic opcodes based on the access type and context entry controls as well as level of access.

Requires setting for opcodes are given in the table below. The steps of operations in the atomic ALUs are given later in the document.



The Following Atomics are only applicable in GTI and used for Page Walks

R/W => Bit[0]

Extended Access required => Bit[1]

Write Protect Enable => Bit[2]

Intermediate Entry => Bit[3]

Atomic Operation	Opcode	Description	New Destination Value	Applicable	Return Value (optional)
Atomic_Page_update_0000	1100_0000	Read Access Extended Access bit is disabled Write Protection is disabled Final PTE	Set bit[5] if not set		new_dst
Atomic_Page_update_0001	1100_0001	Write Access Extended Access bit is disabled Write Protection is disabled Final PTE	Set bit[5,6] if not set		new_dst
Atomic_Page_update_0000	1100_0010	Read Access Extended Access bit is enabled Write Protection is disabled Final PTE	Set bit[5,10] if not set		new_dst



Atomic_Page_update_0001	1100_0011	Write Access Extended Access bit is enabled Write Protection is disabled Final PTE	Set bit[5,6,10] if not set		new_dst
Atomic_Page_update_0100	1100_0100	Read Access Extended Access bit is disabled Write Protection is enabled Final PTE	Set bit[5] if not set		new_dst
Atomic_Page_update_0101	1100_0101	Write Access Extended Access bit is disabled Write Protection is enabled Final PTE	Set bit[5,6] if not set		new_dst
Atomic_Page_update_0100	1100_0110	Read Access Extended Access bit is enabled Write Protection is enabled Final PTE	Set bit[5,10] if not set		new_dst
Atomic_Page_update_0101	1100_0111	Write Access Extended Access bit is enabled Write Protection is enabled Final PTE	Set bit[5,6,10] if not set		new_dst



Atomic_Page_update_0000	1100_1000	Read Access Extended Access bit is disabled Write Protection is disabled Intermediate Paging Entry	Set bit[5] if not set		new_dst
Atomic_Page_update_0001	1100_1001	Write Access Extended Access bit is disabled Write Protection is disabled Intermediate Paging Entry	Set bit[5,6] if not set		new_dst
Atomic_Page_update_0000	1100_1010	Read Access Extended Access bit is enabled Write Protection is disabled Intermediate Paging Entry	Set bit[5,10] if not set		new_dst
Atomic_Page_update_0001	1100_1011	Write Access Extended Access bit is enabled Write Protection is disabled Intermediate Paging Entry	Set bit[5,6,10] if not set		new_dst
Atomic_Page_update_0100	1100_1100	Read Access Extended Access bit is disabled Write Protection is enabled Intermediate Paging Entry	Set bit[5] if not set		new_dst



Atomic_Page_update_0101	1100_1101	Write Access Extended Access bit is disabled Write Protection is enabled Intermediate Paging Entry	Set bit[5,6] if not set		new_dst
Atomic_Page_update_0100	1100_1110	Read Access Extended Access bit is enabled Write Protection is enabled Intermediate Paging Entry	Set bit[5,10] if not set		new_dst
Atomic_Page_update_0101	1100_1111	Write Access Extended Access bit is enabled Write Protection is enabled Intermediate Paging Entry	Set bit[5,6,10] if not set		new_dst

Atomic updates are only possible for cacheable memory types. There could be cases where the PTE could be in WT/WC/UC space where atomic update is not possible via WB space. Those are the cases where IA cores use bus lock to update the A/D bits in PTE.

GT core is not capable of supporting bus locks and has the following options. These options will be enabled/disabled via register space.

Option#1: Ignore the PAT/MTRR setting of the PTE and update the space as WB with atomic ops. This is the place GAM will decide to go forward with atomic updates assuming WB space works

Option#2: Once the memory type is determined and the end result of the page is WC/UC/WT space, we can not guarantee an atomic update. GAM will report an application error (catastrophic) to the scheduler and handle the case as error.



Bit	Access	Default Value	Description
1	R/W	0b	<p>A/D Bit Update on non-WB Space: A/D bit updates are only possible via atomic operations which are required to be on WB space to work properly. On non-WB spaces, the A/D bit updates are done via bus locks which are not supported for GT.</p> <p>"1": Ignore the page level cacheability and do atomic updates for A/D bit management</p> <p>"0": Detect the page level cacheability as part of the atomic operation and throw a catastrophic error when non-WB space is seen for A/D bit updates.</p>

Replacement

TLB replacements during runtime are based on LRA algorithm; in addition invalidations and page responses will have to invalidate the TLB entries.

Invalidations of TLB

There are various ways to invalidate TLBs:

1. **Traditional invalidation from command streamer:** Could be part of any fence accesses including newly added atomics
2. **SVM based invalidations:** Listed as part of the new SVM related invalidations, various stages of TLBs including intermediate stages can be invalidated selectively and/or as a whole.
3. **Context Switch:** A context switch has to invalidate caches to make sure we have no residual value of the TLBs across multiple PASIDs. GAM will treat the context reload message from CS as a form of TLB invalidation.
4. **A page response:** should invalidate faulted recordings. It should be done via address matching to kick the faulted entries within the matching PASID.

Invalidation response "Invalidation Wait Descriptor" should also be a fence for both READs and WRITEs that used the previous TLB entries. GAM can only respond to "invalidation wait descriptor" after getting a GTI EMPTY indication.

Optional Invalidations

The following cases are listed as page table updates which software may choose not to invalidate the TLBs.

- If a paging-structure is modified to change the Present (Valid) flag from 0 to 1, s/w may choose not to invalidate TLBs. This affects only the case where GPU keeps the faulted page in its TLB to filter out future faults. Regardless of s/w does invalidation or not, for the cases where h/w cares, there will be a page response from s/w which will be used to shutdown the faulted record from the TLB.



GAM will put faulted entries to its TLBs only if there has been page request for it, which means that only faultable surfaces can be stored in GAM TLBs as a faulted entry.

- If a paging-structure entry is modified to change the accessed flag from 0 to 1, no invalidation is necessary (assuming that an invalidation was performed the last time the accessed flag was changed from 1 to 0). This is because no TLB entry or paging-structure cache entry is created with information from a paging structure entry in which the accessed flag is 0.
- If a paging-structure entry is modified to change the R/W or U/S or XD flag from 0 to 1, failure to perform an invalidation may result in a “spurious” page-fault exception (e.g., in response to an attempted write access) but no other adverse behavior. Such an exception will occur at most once for each affected linear address

GTT Walk Request Port (HDC)

A private GTT request port has been added between the HDC(s) and GAM to service the page walks. HDC clusters will contain a mini-TLB and uses GAM’s page walker. Their accesses to this page walker is provided thru this private ports. Main GAM TLBs also act as a secondary cache to back these TLBs.

When page walk request comes to GAM, it will be treated as any normal request where the TLB look up will be done and in case of a miss further page walk will be performed. The results of the page walk will be returned on the private connection between the GAM and HDC clusters.

The hierarchy is defined as following diagram where each slice will contain a “Slice GTT Request Manager” (slice GRM) where all HDCs interface with. Each HDC get two credits (i.e. 2-deep ingress queue per HDC) where walk request response back to HDC is considered the release of credits. Slice GRM will collect the walk requests and arbitrate/forward them to GAM on per slice dedicated port.

The request interface is designed to support 1 page walk request per 4 core clocks. Hence both the HDC to slice GRM and slice GRM to GAM should be designed to carry a single page request distributed over 4 clocks to keep the wiring at minimum.

Page Request Interface:

- Valid – 1 bit
- Opcode – 1 bit (“0”: Page Request and “1”: TLB Invalidation Response)
- Slice ID – 1 bit
- HDC ID – 2 bits
- Virtual (GFX) Address – 36 bits (corresponds to [47:12])
- R/W – Read vs Write intend – 1 bit
- Tracking Number – 8 bits
- Faultable vs non-fautable surface - 1 bits

Page response interface from GAM is designed to deliver one page response every 4 clocks and it is broadcast bus that connects to all HDCs directly. It is up to HDC unit to decode slice/unit ID and claim the response as its own which is also treated as claiming the page miss credit back.



Page Response Interface:

- Valid – 1 bit
- Opcode – 1 bit
 - 00: for Page Response
 - 01: Reserved
 - 10: TLB Invalidation Start
 - 11: TLB Invalidation End
- PA – 27 bits (corresponds to [38:12])
- R/W – this was for a read or write
- Slice ID – 2 bit
- HDC ID – 2 bits
- D bit – 1 bit
- Fault Codes – 2 bits (6 bits)
- Cacheability (memory type) Override – 3 bits
- Tracking number – 8 bits

Fault Codes:

Bits[1:0]	Bit Description
00	No Faults
01	Page fault due to Page not present
10	Privilege level violation
11	Write permission violation



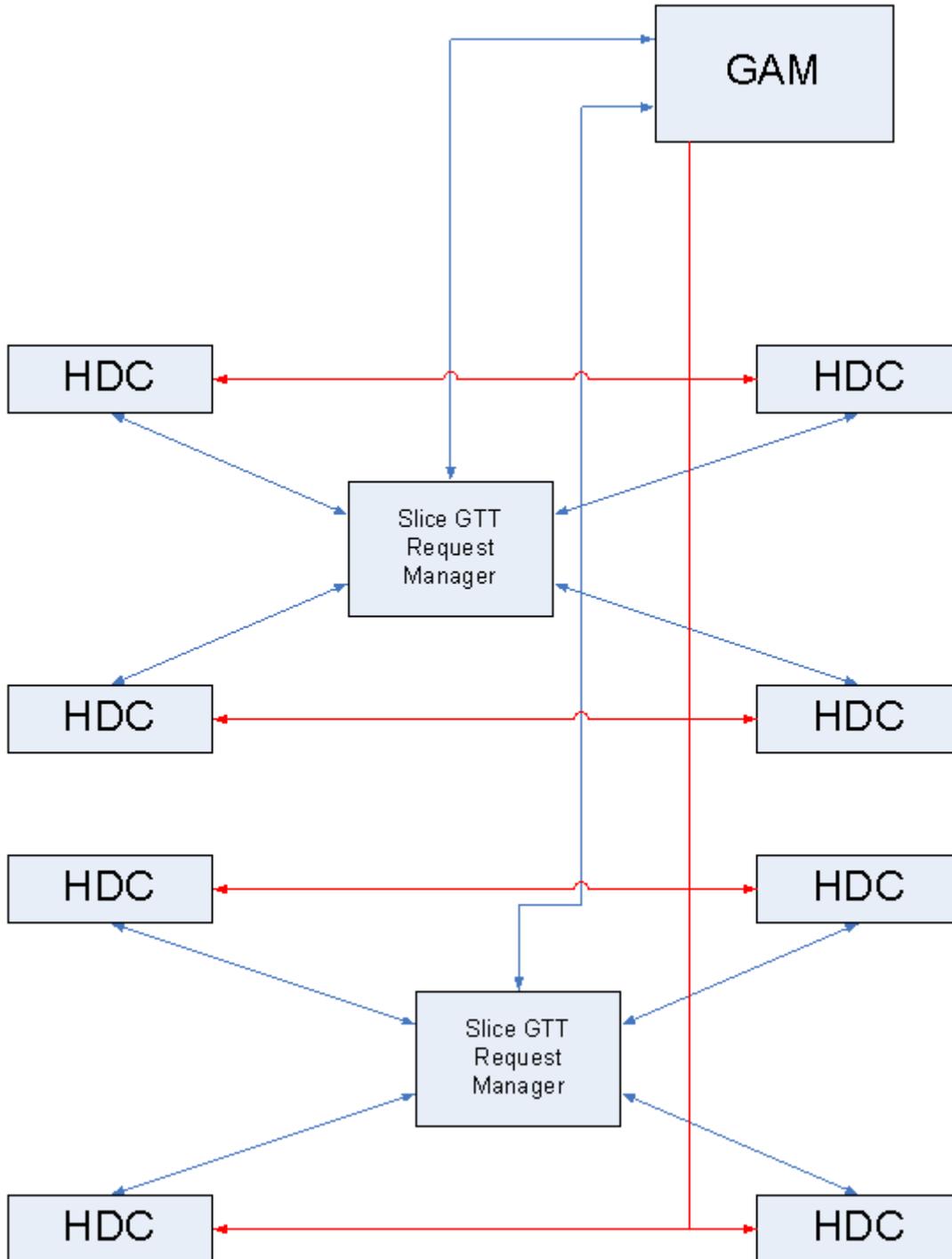
Cacheability (memory type) Override – In case of advanced context execution (where HDC coherent mode is only applicable), the cacheability from surface state will need to be overridden by the OS/VMM setting up the page tables (PAT), MTRR and CD. The effective memory type for HDC has to be used for cache allocation starting with L3. HDC needs to use the memory type bits reported by GAM for memory accesses.

Memory Type	Encoding in MTRR	HDC to L3 Control[3:2]
Uncacheable (UC)	0h	"00"
Write Combining (WC)	1h	"01"
Write Through (WT)	4h	"10"
Write Protected (WP) (Reads:WB and Writes:WC)	5h	Read: "11" Write: "01"
WriteBack (WB)	6h	"11"
Reserved*	2,3,7h	Reserved

*HDC is already capable of processing WT and WB memory types



Overall Signaling Diagram for HDC/GAM connection:





TLB Invalidation

In addition to page walk requests, there is also a communication needed between HDCs and GAM to relate the TLB invalidation events. GAM combines all TLB invalidation events into a single event as a global TLB invalidation to HDC where the entire content of mini-TLB is wiped out.

The protocol starts with GAM sending a "TLB invalidation start" on *page response* interface. All HDCs will act on the TLB invalidation request as it is a broadcast event. Inline communication of the TLB invalidation is to make sure all previous page responses are seen by the HDCs targeted. Upon receiving the TLB Invalidation start, HDCs will stop sending new TLB requests and only process already available translations pending and ensure corresponding (physical accesses) are GO'ed by L3. Once all these steps are complete HDC will send out the ACK on the "page request" interface to GAM.

GAM will stop sending any page responses post "TLB invalidation start" message and it is free to drop any new request that might have been enqueued by HDCs prior to HDCs seeing the invalidation request. The inline ACK from each HDC is meant to push pending HDC TLB requests towards GAM (where they are dropped). Once GAM collects all "TLB invalidations ACK's" from all HDCs, it will re-enable the TLB service path and send back (broadcast) "TLB invalidation end" message (inline).

HDCs seeing the "TLB Invalidation end" indicating the sequence are complete and synchronized are free to send TLB requests back to GAM.



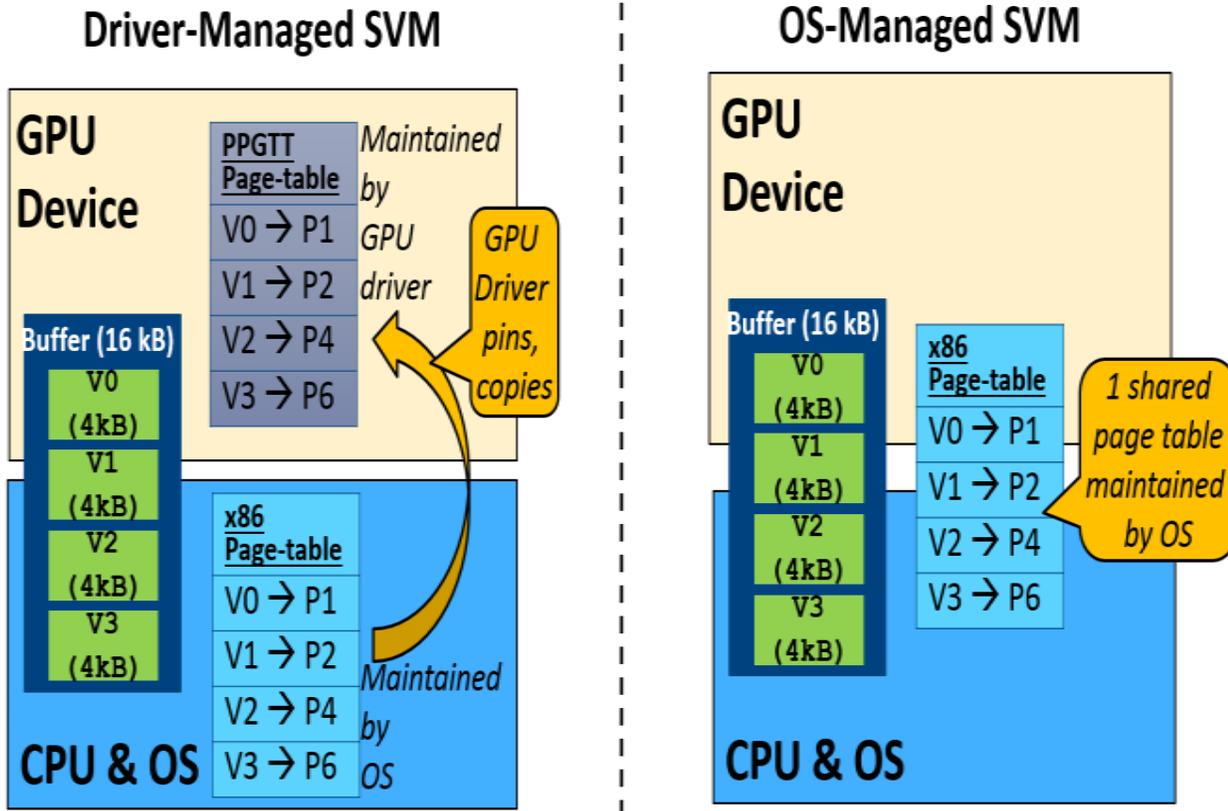
Shared Virtual Memory

The GPU can share virtual memory with the CPU. This is accomplished with Page Tables that map each shared virtual address for both CPU application and the GPU context to the same physical address. There are 2 ways to manage the page tables for shared virtual memory: Driver-Managed SVM and OS-Managed SVM.

Shared Virtual Memory Summary

	Driver-Managed SVM 2 page tables: PPGTT and OS PT	OS-Managed SVM 1 shared page table: OS PT
Page Table type	PPGTT	VT-d IOMMU
Tiled Resource Table	Yes (Driver-Managed TR-TT)	Yes (Driver-Managed TR-TT)
GPU Context Type	Legacy	Advanced
Page Fault Resiliency	None (Fault-and-Hang)	Yes (Fault-and-Halt, Fault-and-Stream)
Coherency	Both Driver-Managed and HW-Managed	Both Driver-Managed and HW-Managed

Page Table Types



Driver-Managed SVM uses 2 different page tables which the graphics driver keeps synchronized: the PPGTT and the OS page table. The driver copies OS page table entries into the GPU context's local PPGTT page table, and pins those physical pages in the OS page table so that OS doesn't change the mapping independent of the driver.

OS-Managed SVM uses 1 shared page table that only the OS manages. The OS coordinates the GPU and CPU use of the shared page table with the VT-d IOMMU. (See IOMMU section for more information on this.)



Page Faults

OS page management services may change a physical memory page mapping that is in use by the GPU, thereby exposing GPU virtual address translations to page faults. The GPU implements a "Fault-and-Halt" resiliency scheme to resolve such page faults: the GPU signals the page fault back to the OS, the OS corrects the memory mapping, and then the OS signals the GPU to retry the memory operation.

When the GPU is running in Advanced Context mode with OS-Managed SVM, this Fault-and-Halt page fault mode is enabled.

When the GPU is running in Legacy Context mode with Driver-Managed SVM, an invalid page translation causes the context to hang ("Fault-and-Hang" resiliency scheme). Driver-Managed SVM strictly avoids the Fault-and-Hang situation: the driver changes the page mappings in PPGTT when the GPU context is not active, and maps all invalid pages to null pages.

Programming Note	
Context:	Fault-and-Stream support
<p>In early configurations, there were two page fault modes supported: Fault-and-Halt and Fault-and-Stream. Most GPU programs use Fault-and-Halt, but GPU programs using coherent memory must use Fault-and-Stream mode. In later configurations, only Fault-and-Halt page fault mode is used.</p>	



SVM Coherency

Memory accesses made by the CPU and GPU are not necessarily coherent (consistent). Each device may have cached copies of the memory data, and require special protocols to keep them coherent. Coarse-grained SVM coherency uses a driver-managed programming model for consistency. Fine-grained SVM coherency uses a HW-managed protocol (MESI) for consistency.

	SW Coarse-Grain Coherency	HW Fine-Grain Coherency
<p>Driver Managed (Mirrored Page Tables via PPGTT)</p>	<p>OpenCL “Coarse Grain SVM (buffer)”</p> <p><u>Programmer benefits:</u></p> <ul style="list-style-type: none"> • Pointer based data structure sharing between CPU & GPU 	<p>OpenCL “Fine Grain SVM (buffer)”</p> <p><u>Programmer benefits:</u></p> <ul style="list-style-type: none"> • Pointer based data structure sharing between CPU & GPU • Concurrent & coherent CPU & GPU memory accesses • Synchronization via CPU & GPU shared memory atomic operations
<p>OS Managed (Shared Page Tables via VTd-IOMMU)</p>	<p>This combo does not exist in OpenCL specification</p>	<p>OpenCL “Fine Grain SVM System”</p> <p><u>Programmer benefits:</u> Same as Fine Grain SVM, plus:</p> <ul style="list-style-type: none"> • Use C/C++ malloc(), new() for memory allocation sharing b/t CPU & GPU • GPU can over-allocate physical memory. <p><u>(Potential/Eventual) Platform benefits :</u></p> <ul style="list-style-type: none"> • OS can centralize memory management • GPU may avoid overcommitting system memory or needlessly taxing system • Simpler driver code (no pinning)



Page Faults

Page fault handling has been fundamentally updated for production processor graphics. Previous generations of production GPUs had limited page faulting capabilities enabled, where such occurrences are either handled as hardware hangs or just simply ignored.

This generation introduces the Advanced Context mode and the Fault&Stream page fault mode as the preferred page fault model into production GPUs. The Advanced Context enables a context switch while a fault handler is run and then a switch back to resume the program. This enables shared virtual memory (SVM) support for GPGPU applications for dynamic allocation of the pages. There is limited support of the Legacy Fault&Halt page fault mode (which halts the Gen engine while the page fault is handled) to facilitate bringing up the new driver independent of bringing up the new page fault model.

This generation moves the page fault mode selection from context descriptor to per-surface state definition via memory object control state (MOCS). This capability enables the GFX driver to define a unique page fault mode at the surface level. H/W allows multiple different types of page fault modes to co-exists. The usage mode for per-surface fault context is exclusively either:

- The compatible Context Register page fault mode with every per-surface MOCS set to "use context register", or
- The per-surface model where the Context Register page fault mode is set to Fault&Halt and the per-surface page fault mode is any of the defined modes.

Page Walker (GAM) is the gateway to page tables, hence it is responsible to detect and handle the first level requirements for page faulting. The rest of the section is introduced to explain high level treatment of page faults in the hardware.



Hardware and Software Pieces for Page Faults

Various levels of software and hardware entities are involved in GPGPU/3D workloads and interact as part of page fault handling.

Entity	Description
KMD (Kernel Mode Driver)	Responsible for configuring/initialization of device, owns Graphics contexts/work-queue, performs privileged operations for GPGPU contexts (such as setup/teardown of application queue/ring-buffer, etc.).
UMD (User Mode Driver) & App	Capable of submitting commands directly from ring-3 for GPGPU applications/processes via the ring-buffer/queue allocated to it by the KMD. (The current expectation is that ring-buffer is allocated by the user mode driver and pinned by the kernel mode driver.)
IOMMU SW (and/or OS)	For IOMMU enabled future OSs, this would be the native OS kernel. For legacy OSs (i.e. not IOMMU aware), this would be a kernel-mode IOMMU driver (which may be packaged as part of the GPU/GPU software drivers/binaries). For early generations of page fault handling a companion driver model can be used for IOMMU SW. This mode is called SVM_DEVICE_MODE to indicate that, if enabled by BIOS, the IOMMU hardware is accessible to KMD through the Device-2 register resources, so that KMD can manage the IOMMU hardware for legacy (SVM-IOMMU-unaware) OSs.
Memory Interface Controller (Page Walker/GAM)	Hardware component responsible for doing the page walks, identifying page faults, and managing TLBs. The same interface manages the fault queues to/from SW, and reports out faults to other HW entities.
EUs (Execution Units)	Source of the memory accesses via messages, in this context handles the page fault response. Saves its context when we switch out, or retries the faulted transactions when told to do so. Also detects canonical errors.



Page Access Rights

The accesses permitted by a translation are determined by the access rights specified by the paging-structure entries controlling the translation. For legacy context, the access rights are not applicable and should not be considered during page walk.

The following items detail how paging determines access rights during Advanced Contexts:

- For accesses in supervisor context mode:
 - Data reads (Read requests with value of 0 in Execute-Requested (ER) field)
 - Data reads are allowed from any input address with a valid translation.
 - Instruction Fetches (Read requests with value of 1 in Execute-Requested (ER) field)
 - If No-Execute-Enable (NXE) field in extended-context-entry used to translate request is 0
 - If Supervisor-Mode-Execute-Protection (SMEP) field in extended-context-entry used to translate request is 0, instruction may be fetched from any input address with a valid translation.
 - If Supervisor-Mode-Execute-Protection (SMEP) field in extended-context-entry used to translate request is 1, instruction may be fetched from any input address with a valid translation for which the U/S field (bit 2) is 0 in at least one of the paging-structure entries controlling the translation.
 - If No-Execute-Enable (NXE) field in extended-context-entry used to translate request is 1
 - If Supervisor-Mode-Execute-Protection (SMEP) field in extended-context-entry used to translate request is 0, instruction may be fetched from any input address with a valid translation for which the XD field (bit 63) is 0 in every paging-structure entry controlling the translation
 - If Supervisor-Mode-Execute-Protection (SMEP) field in extended-context-entry used to translate request is 1, instruction may be fetched from any input address with a valid translation for which, the U/S field is 0 in at least one of the paging-structure entries controlling the translation, and the XD field is 0 in every paging-structure entry controlling the translation.
 - Write requests and Atomics requests
 - If Write-Protect-Enable (WPE) field in extended-context-entry used to translate request is 0, writes are allowed to any input address with a valid translation.
 - If WPE=1, writes are allowed to any input address with a valid translation for which the R/W field (bit 1) is 1 in every paging-structure entry controlling the translation.
 -
- For accesses in user context mode:
 - Data reads (Read requests with value of 0 in Execute-Requested (ER) field)



- Data reads are allowed from any input address with a valid translation for which the U/S field is 1 in every paging-structure entry controlling the translation.
- Instruction fetches (Read requests with value of 1 in Execute-Requested (ER) field)
 - If No-Execute-Enable (NXE) field in extended-context-entry used to translate request is 0, instructions may be fetched from any input address with a valid translation for which the U/S field is 1 in every paging structure entry controlling the translation.
 - If No-Execute-Enable (NXE) field in extended-context-entry used to translate request is 1, instructions may be fetched from any input address with a valid translation for which the U/S field is 1 and XD field is 0 in every paging-structure entry controlling the translation.
- Write requests and Atomics requests
 - Writes are allowed to any input address with a valid translation for which the R/W field and the U/S field are 1 in every paging-structure entry controlling the translation.

A GPU may cache information from the paging-structure entries in TLBs and paging-structure caches. These structures may include information about access rights. The GPU may enforce access rights based on the TLBs and paging-structure caches instead of on the paging structures in memory.



Page Fault Decision

Only PPGTT/IA-32e page-table accesses are faultable, GGTT accesses are pinned pages and ensured by KMD. This policy is not enforced in the hardware.

All surfaces are page faultable with the introduction into production of Fault&Halt mode.

Fault Aware Surfaces

The concept is that only advanced contexts can be stream page-faultable for clients that are fault aware, and handling mechanism for faults is defined as part of the context itself. GAM will get the fault handling policy as part of the context descriptor ahead of any memory accesses. Another point is that only PPGTT/IA-32e page-table accesses are faultable, GGTT accesses are pinned pages and ensured by KMD, this policy is not enforced in the hardware.

Both front pipeline accesses and backend pipeline accesses are not advanced faultable.

It is easier to limit the surfaces that are faultable than not faultable:

- HDC – Data port accesses (coherent only)
- IC – Instruction cache accesses
- Sampler – Sampler cache accesses

Any other accesses are handled as fault&halt if it is chosen to be so.

GAM will figure out the fault&stream capability of the surface based on the TAG coming from L3 (original requester) and/or based on the GTT paging request from HDC.



Page Fault Modes

Arbiters and memory subsystem will have different faulting modes and behaviors. The following fault behaviors are decided either as part of the context descriptor and/or surface state (MOCS).

To avoid the replay buffer limitations when using Fault & Stream, sampler accesses are handled as Fault&Halt. Advanced 3D and GPGPU contexts still need to be programmed as running under Fault & Stream mode to enable invalidations of TLB translations for coherent surfaces. Potential deadlocks can occur if Fault & Stream is not enabled for data port (HDC) accesses, as coherent cycles may not be able to get flushed out in the case of a TLB invalidation. Programming the context as Fault & Stream enables the replay buffering in the EUs, which is needed to avoid the deadlocks due to TLB invalidations of coherent surfaces. However, the actual fault handling mode in GAM is to be programmed as Fault & Halt, for all faults from all clients. This is done by setting 0x404C[0] = '1.

Context Type		Supported Fault Types	Context Switching on Faults	Notes
Legacy 3d		No Page Fault	n/a	
Legacy Media		No Page Fault	n/a	Programmable Media pipeline
Legacy GPGPU		No Page Fault	n/a	
Advanced 3d		No Page Fault	n/a	
	data port accesses	F&H	No context switch on F&H	
	instruction cache	F&H	No context switch on F&H	
	Sampler cache accesses	F&H	No context switch on F&H	
	all other surfaces	F&H	No context switch on F&H	
Advanced Media		F&H	No context switch on F&H	GPGPU Programmable Media pipeline must be F&H mode for IME/VME Sampler accesses
Advanced GPGPU		F&H or F&S	Context switch on F&S page fault	
	data port accesses	F&H or F&S	Context switch on F&S page fault	Coherent L3 accesses require F&S mode, and will context switch on F&S. Non-coherent accesses can run in either mode but will not context switch if faulted.
	instruction cache	F&H or F&S	Context switch on F&S page fault	



	Sampler cache accesses	F&H or F&S	No context switch on F&S	Sampler accesses are running under F&H mode
	all other surfaces	F&H or F&S	No context switch on F&S	All other accesses are running under F&H mode
Page Faultable Context?	No	Yes	Yes	
Fault Mode	Non-fault	Fault and Halt	Fault & Stream	
Context Type	Legacy or Advanced	Advanced	Advanced	
Shared Func. Support	n/a	All	Sampler, HDC (coherent), IC	
Fault Counters Inc'd	No	No	Yes	
IOMMU Action On Fault	Signal fatal error	Page Fill	Page Fill	
Shared Func Action on Fault	<oblivious>	Wait for fill	Continue; may retry subsequent msgs to ensure ordering rules	
Msg Retry (2)	n/a	No	Yes	
Kernel Visibility of Fault	None	None	None	
App Visibility of Fault	Via driver signaling of Fatal Error	None	None	
Scheduler Visibility of Fault	n/a	None	Yes; IRQ on first fault & counters	
Usage	Legacy Behavior			

Fault and Hang/Crash (Legacy Mode)

GPU cores prior to this release all implemented Fault and Hang behavior (optionally continue – MMIO based) with the exception of a simple fault and halt that was introduced earlier. This is where page walker detects a page which is not present as part of the translation and hangs the pipeline via reporting into a register/interrupt (through command streamer).

The resulting issue points to a s/w problem either in defining the GTT or using a surface which is not meant to be page faultable.

The same behavior will be carried forward and used for legacy context operation as well as optionally for surfaces that are not page fault-able. The same MMIO based mechanism will allow the engine to ignore the page fault and resume operating.



Fault and Halt

Fault&Halt mode is a simple way of handling page faults where GPU stalls on the page fault and expects services from page miss handler. The context that is faulted cannot be switched out until fault services are complete.

Fault & Halt has a single mechanism to work with:

1. **Advanced Reporting:** As part of the IOMMU additions, page request queue can also be used to report page faults for any levels of paging process. In case of advanced reporting in for Fault & Halt, request queue is used to send the paging request thru IOMMU. This mechanism is primarily used for non-stream fault-able surfaces.

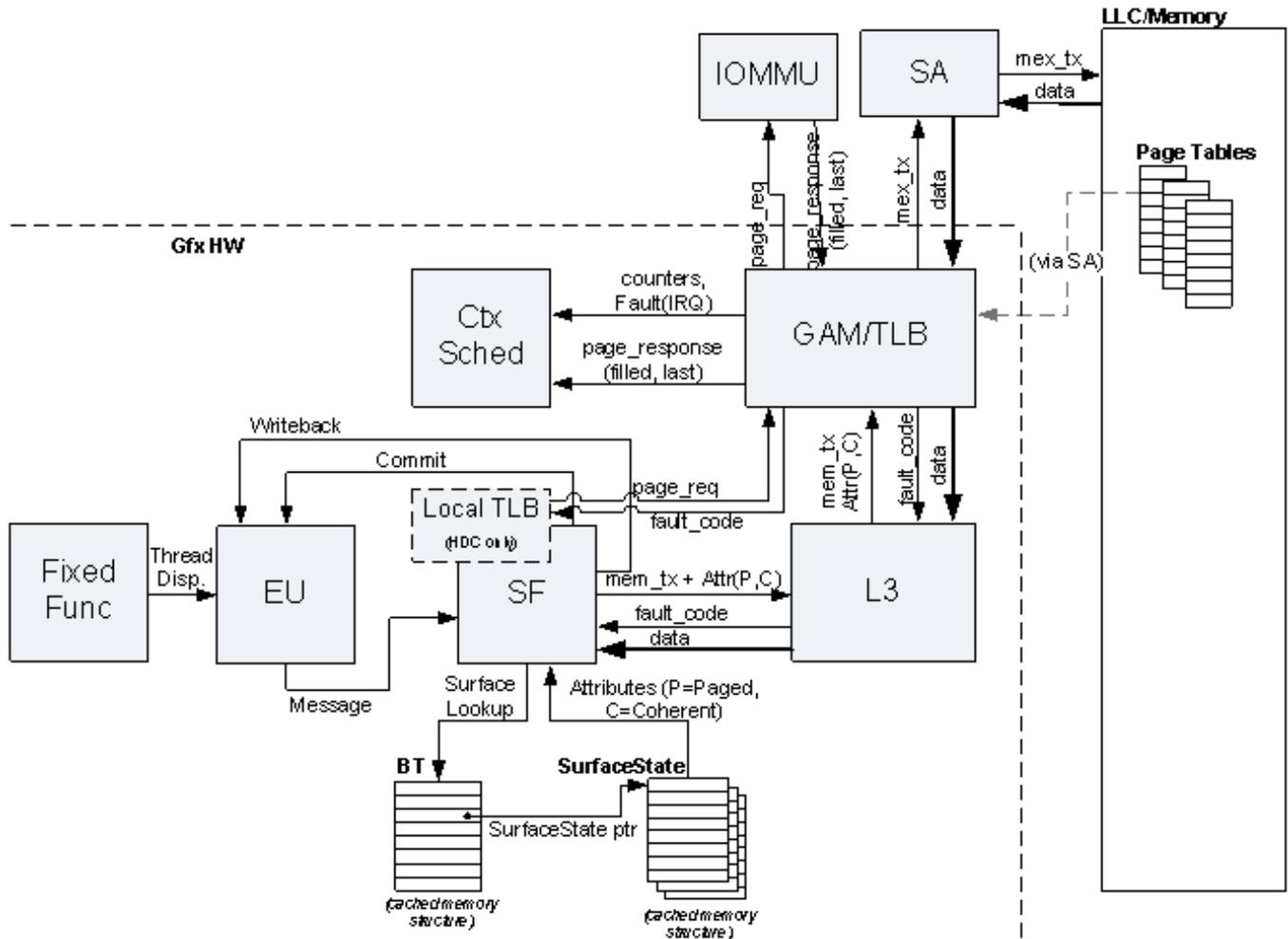
The basic promise of fault & halt is to provide a basic faulting mechanism for non-stream fault-able surfaces regardless of the context type.

As part of the operation, the miss pipeline is blocked until the TOP request is serviced by software. Meanwhile the TLB hits continue to make progress until the TLB MISS-Q fills up blocking the entire memory pipeline.



Fault Flows and Impact

The following diagram shows the relevant streams and fault interfaces for their communication. GAM plays a crucial role in facilitating the page fault information.



On a faultable context GAM is the interfacing HW block for Page Request and Page Response queues. Both queues are used to communicate with SW layer. For some fault modes (see “page fault modes”), the page faults need to be reported to different places. This section outlines these interfaces (excluding the page request/response interface which is tracked in a different section).

Client/GAM Interface

There are two ways that page faultable requests make their way to GAM:

1. Via HDC TLB Request Path: For both writes and reads originated from EUs
2. Shared Functions (Texture & Instructions) Read & Writes: Routed thru L3

HDC GTT request/response interface is already defined as part of the previous sections and the fault code is communicated as part of the page walk response.



There is a need to add new fields to Read Data return interface for communicating the fault information. This information is only relevant for some selective clients (L3, I\$, and Sampler) and the rest of the clients do not need to connect the new signals.

Legacy Memory Data Return Interface

Data Valid
Data Tag
Slice ID
Client ID
Data

The legacy return interface is only applicable for Reads, but for faults we need a write response interface not only for reads but also for writes. And the fact that GAM can walk reads and writes separately, we would need an additional response interface for writes (for faultable write clients – HDC only).

Memory Data Return Interface

Data Valid
Data Tag
Slice ID
Client ID
Data
Read Page Fault Code

The read return interface is managed by GTI on a regular scheduling basis. For GAM to intervene and insert a page fault response a “gap” is needed on the read return bus from GTI. However there is no guarantee a “gap” would be present on streaming returns which will lead to infinite holding of page fault responses in GAM. Note page faults do not generate a read to memory hence no data phase (data content is X for the faulted read return). To solve this issue a new signal needs to be inserted from GAM to GTI, which a pulse on that signal guarantees a bubble clock on the main read return bus. The bubble is generated within the 16 clocks within the pulse first seen. GAM can put a 16-deep read page fault response queue to insert page fault responses to the client. Note that all fields on the return path should be valid, except data.

A specific protocol to insert bubbles on the data stream from GTI to GAM is not needed given that GAM converts the faulted access to invalid access which would return data from stolen memory. The packet is later intercepted by GAM to insert the fault indicators.



Page Fault Codes Used

Bits[1:0]	Bit Description
00b	No Page Fault
01b	Page not present or reserved bit not 0
10b	Privilege level violation
11b	Write permission violation

GAM fault code output is only connected to L3 banks via GAFS; no other client takes in the fault codes. L3 behavior does not change for the cases where the returning data has no faults. But if there is a fault, L3 should not be filling the line into the cache (treat it as uncacheable) and instead just return the packed back to the client (Sampler, I\$) with the fault code.

Rescheduling a Faulted Context

A faultable context, which got pre-empted out before completing for any reason, needs to be scheduled back eventually for completion. If the context fault behavior is *"context switch on faults"*, then regardless of the context switch reason, it only makes sense to reschedule this context when the page fault handler returns the completion (response to LAST page fault). This is where memory interface HW informs the scheduler stating that page fault response has been fulfilled.

The scheduler then promotes the context (i.e. queue) to available pool (from pending pool) and makes it available for hardware submission.

The particular context that got switched out could have been *"stream on faults context"*; this is where the context is tolerant to page faults and it has enough parallelism to make limited forward progress with faults. If *"stream on fault context"* switches out, the simple option is to handle same as *"context switch on fault"* type context, where HW adds a last flag and scheduler puts it into pending pool. It will only be available for hardware submission when all related page faults are serviced. In this case HW will ignore the intermediate page responses for the switched out *"stream on fault context"* unless it is a response to LAST fault. This is the POR mode of rescheduling a faulted context.

However this behavior may not be the most optimized way of rescheduling a *"stream on fault context"* type. Given the context is tolerant to faults, as soon as priority context is complete (or preempted out), *"stream on fault context"* can be scheduled. Even though this process is possible in principle, the hardware determination to reschedule a *"stream on fault context"* could be quite complex.

The first difficulty is whether to put a LAST or not when the *"stream on fault context"* gets preempted out. If there is a LAST, that makes the termination cases very hard to determine whether any faults for this *"stream on fault context"* is pending before ensuring the page fault queue is clear. If there is no "LAST" and termination comes in, that means no response from IOMMU, again the same exposure on how to ensure faults are cleared from the system.

There are additional cases where the reason for the preemption out of a *"stream on fault context"* could be the number of page faults we are running into and scheduler statistics kicking in. Once we preempt out, those statistics are cleared and HW cannot track them while running a different context. So the



question comes in when to reschedule the “*stream on fault context*” when it was switched out due to high number of page faults.

Application Termination

There are various reasons why an application can be terminated, a few of them could be:

1. User killed the App
2. OS killed the App
3. H/W detected an unrecoverable error reported to s/w which killed the App.

Such termination cases will be overlapped to same sequence of events to cleanly switch out from the terminated application while ensure all h/w and s/w entities are cleaned up before the same PASIDs can be re-assigned.

Step#1: OS Handling the application termination

OS starts the process to kill the application; it will inform the KMD on application termination. KMD will get the chance to clean up any application state in the device h/w. OS or IOMMU software marks this PASID as “pending termination”, causing IOMMU page-fault handler to return page-responses with unsuccessful status for page-requests from this PASID.

Step#2: KMD informs the scheduler (with PASID/QueueID)

KMD is requesting the scheduler to clear the h/w status for the corresponding PASID/QueueID.

Step#3: Scheduler informs the h/w and prepares the h/w to switch out.

Step#4: This is where the h/w is now informed about the App termination. There are various cases for the status of the context:

1. This is the first time h/w is hearing “bad context” and context is active
2. This is the first time h/w is hearing “bad context”, however context was switched out already (i.e. preempted out)
3. H/W already detected this context as “bad” (i.e. unrecoverable error).

In all cases h/w will perform switch out from the bad context, and the only remaining piece is the page faults which might have been already reported to IOMMU. Here there are two cases of interest:

1. *There were page faults for this context:* If there were page faults, h/w will put a LAST into page faulting queue and put the context into Pending list for scheduler. Scheduler cannot complete the termination of the context, until h/w sees the response for the LAST from IOMMU or OS. Meanwhile IOMMU or OS can return unsuccessful completion for the LAST but the purpose is here is to ensure the entire page fault queue is cleared up for this context.
2. *There were no page faults for this context:* Than h/w communicates a successful switch out back to scheduler (which means context does not need to be held back in pending queue).

Step#5: Scheduler frees up the queues and PASID

Step#6: Scheduler informs the KMD and KMD cleans up it structures



KMD can de-allocate all kernel mode data structures for this app (i.e. context space,...) and makes the PASID available

Step#7: KMD informs the OS/IOMMU

IOMMU stops “dummy” page responses for this PASID, it removes all the pages assigned to this App. Performs and IOTLB invalidation (could be a redundant step), enables the PASID for future use. After completion of PASID termination, OS/IOMMU software to free this PASID entry and mark it as not-present, along with needed PTE-cache/IOTLB invalidation

Memory Types and Cache Interface

This section has additional information on the types of memory which are accessible via the various GT mechanisms. It includes discussion on how the various paging models are used and accessed. See the Graphics Translation Tables for more detailed discussions on paging models.

This section also includes descriptions of how different surface types (MOCS) can be cached in the L3 and the different behaviors which can be enabled.

Memory Object Control State (MOCS)

The memory object control state defines the behavior of memory accesses beyond the graphics core, graphics data types that allow selective flushing of data from outer caches, and controlling cacheability in the outer caches.

This control uses several mechanisms. Control state for all memory accesses can be defined page by page in the GTT entries. Memory objects that are defined by state per surface generally have additional memory object control state in the state structure that defines the other surface attributes. Memory objects without state defining them have memory object state control defined per class in the STATE_BASE_ADDRESS command, with class divisions the same as the base addresses. Finally, some memory objects only have the GTT entry mechanism for defining this control. The table below enumerates the memory objects and the location of the control state for each:

Memory Object	Location of Control State
surfaces defined by SURFACE_STATE: sampling engine surfaces, render targets, media surfaces, pull constant buffers, streamed vertex buffers	SURFACE_STATE
depth, stencil, and hierarchical depth buffers	corresponding state command that defined the buffer attributes
stateless buffers accessed by data port	STATE_BASE_ADDRESS
indirect state objects	STATE_BASE_ADDRESS
kernel instructions	STATE_BASE_ADDRESS
push constant buffers	3DSTATE_CONSTANT_(VS GS PS)
index buffers	3DSTATE_INDEX_BUFFER
vertex buffers	3DSTATE_VERTEX_BUFFERS
indirect media object	STATE_BASE_ADDRESS



Memory Object	Location of Control State
generic state prefetch	GTT control only
ring/batch buffers	GTT control only
context save buffers	GTT control only
store DWord	GTT control only

MOCS Registers

These registers provide the detailed format of the MOCS table entries that need to be programmed to define each surface state.

MEMORY_OBJECT_CONTROL_STATE

L3 Control Registers

64x16b control registers are defined within L3 space to interpret MOCS indexing and map it to cache events.

The incoming MOCS value is used to index into one of these registers which hardware uses as control parameters for a given surface. It allows 64 concurrent surface definitions with unique control values for L3 caching.

Also attached are the default settings for each 64 locations if driver chooses to use as is.

Following 16b defines per selection definition:

Register#64 (MOCS value 63) is reserved for h/w use and should not be used by s/w.

In L3 Node: B020-B09F (128 Bytes)

Bits	Description
16:6	Reserved.
5:4	<p>L3 Cacheability Control (L3CC).</p> <p>Memory type information used in L3. This field is combined with the additional two bits that are sent by HDC based on binding table index. For all other L3 requesters, this field is the primary source of L3 cache controls.</p> <p>00b: Use binding table index for direct EU accesses – for rest it is reserved.</p> <p>01b: Uncacheable (UC) – non-cacheable.</p> <p>10b: Reserved</p> <p>11b: Writeback (WB).</p>



Bits	Description
3:1	<p>Skip Caching Control (SCC).</p> <p>Defines the bit values to enable caching. Outcome overrides the L3caching for the surface.</p> <p>If "0" – than corresponding address bit value is don't care.</p> <p>Bit[1]=1: Address bit[9] needs to be "0" to cache in target.</p> <p>Bit[2]=1: Address bit[10] needs to be "0" to cache in target.</p> <p>Bit[3]=1: Address bit[11] needs to be "0" to cache in target.</p>
0	<p>Enable Skip Caching (ESC).</p> <p>Enable for the Skip cache mechanism.</p> <p>0: Not enabled.</p> <p>1: Enabled for L3.</p>

Defaults Table

Default	L3CC	SCC	ESC		Default	L3CC	SCC	ESC
000000	00	000	0		100000	00	000	0
000001	01	000	0		100001	01	000	0
000010	01	001	1		100010	01	001	1
000011	01	011	1		100011	01	011	1
000100	01	111	1		100100	01	111	1
000101	10	000	0		100101	10	000	0
000110	01	001	1		100110	01	001	1
000111	01	011	1		100111	01	011	1
001000	01	111	1		101000	01	111	1
001001	11	000	0		101001	11	000	0
001010	01	001	1		101010	01	001	1
001011	01	011	1		101011	01	011	1
001100	01	111	1		101100	01	111	1
001101	00	000	0		101101	00	000	0
001110	00	000	0		101110	00	000	0
001111	00	000	0		101111	00	000	0
010000	00	000	0		110000	00	000	0
010001	01	000	0		110001	01	000	0
010010	01	001	1		110010	01	001	1
010011	01	011	1		110011	01	011	1
010100	01	111	1		110100	01	111	1



Default	L3CC	SCC	ESC		Default	L3CC	SCC	ESC
010101	10	000	0		110101	10	000	0
010110	01	001	1		110110	01	001	1
010111	01	011	1		110111	01	011	1
011000	01	111	1		111000	01	111	1
011001	11	000	0		111001	11	000	0
011010	01	001	1		111010	01	001	1
011011	01	011	1		111011	01	011	1
011100	01	111	1		111100	01	111	1
011101	00	000	0		111101	00	000	0
011110	00	000	0		111110	00	000	0
011111	00	000	0		111111	00	000	0

Memory Interface Control Registers

8*64x32b control registers are defined within the page walker where control parameters for LLC/eDRAM caching are defined. Incoming memory control object state index is used to do a look up into the table where the corresponding control parameters are picked for a given surface. These control values are used to control LLC/eDRAM caching.

For EU surfaces where binding table index is used, we also pass two bits of information in the hardware.

Following 32b defines per selection definition:

These set of registers have to be engine specific (8x).

All MOCS registers are considered part of the HW context and need to be saved part of the context that command streamers are controlling.

Register#64/#63 (MOCS value 63&62) are reserved for h/w use and should not be used by s/w.

- Register#64 is for Coherent L3 evictions
- Register#63 is used for Tiled-Resources page walker accesses

In GAMT: C800-CFFF (8x256 Bytes)

Bits	Description
31:19	Reserved
18:17	Reserved
16:15	<p>Class of Service</p> <p>This field controls the Class of Service sent to the LLC to determine which sub-set of Ways the surface will be stored</p> <p>in.The allocation of certain LLC ways to different class of service settings is a project dependent decision and listed in the Bspec.</p>



Bits	Description
	00: Value from Private PAT Registers(40E0/40E4/40E8/40EC) 01: Class 1 10: Class 2 11: Class 3
14	<p>Snoop Control Field (SCF):</p> <p>Enables s/w to have GFX h/w to be able to consume IA generated buffers that are tagged as WB. Driver can mark these buffers as WB when generating them from IA. In LP-SOCs, the fabric is not forced to be coherent all the time. IA-core generated WB buffers can only be consumed by GPU if that buffer is tagged as snoop-able in GPUs buffer definitions (or via GPU Page tables).</p> <p>1: Hardware will snoop the IA caches while accessing this surface 0: Hardware will not snoop the IA caches while accessing this surface</p> <p><i>Note: There is a performance & power penalty in accessing surfaces that are tagged as snooped.</i> <i>Note: S/W should NOT set this field in client platforms.</i></p>
13:11	<p>Page Faulting Mode</p> <p>This fields controls the page faulting mode that will be used in the memory interface block for the given request coming from this surface:</p> <p>000: Use the global page faulting mode from context descriptor (default) 001-111: Reserved</p>
10:8	<p>Skip Caching Control</p> <p>Defines the bit values to enable caching. Outcome overrides the LLC caching for the surface.</p> <p>If "0" - than corresponding address bit value is do not care</p> <p>Bit[8]=1: address bit[9] needs to be "0" to cache in target Bit[9]=1: address bit[10] needs to be "0" to cache in target Bit[10]=1: address bit[11] needs to be "0" to cache in target</p> <p>The default value of this field is '000. For coherent surfaces, skip caching should not be enabled, as not caching in LLC breaks the coherency.</p>
7	<p>Enable Reverse Skip Caching</p> <p>Enable for the Skip cache mechanism</p> <p>0: Not enabled 1: Enabled for LLC</p>



Bits	Description
6	<p>Don't Allocate on miss</p> <p>Controls defined for RO surfaces in mind, where if the target cache is missed - do not bring the line (applicable to LLC/eDRAM).</p> <p>0: Allocate on MISS (normal cache behavior)</p> <p>1: Do NOT allocate on MISS</p>
5:4	<p>LRU (Cache Replacement) Management (LRUM).</p> <p>This field allows the selection of AGE parameter for a given surface in LLC or eLLC. If a particular allocation is done at youngest age ("3") it tends to stay longer in the cache as compared to older age allocations ("2", "1", or "0"). This option is given to driver to be able to decide which surfaces are more likely to generate HITS, hence need to be replaced least often in caches.</p> <p>00: Take the age value from Uncore CRs.</p> <p>01: Assign the age of "0"</p> <p>10: Dont change the age on a hit.</p> <p>11: Assign the age of "3"</p>
3:2	<p>Target Cache (TC).</p> <p>This field allows the choice of LLC vs eLLC for caching.</p> <p>00b: Use TC/LRU controls from page table</p> <p>01b: LLC Only.</p> <p>10b: LLC/eLLC Allowed.</p> <p>11b: LLC/eLLC Allowed.</p> <p>For coherent surfaces ensure that LLC caching is enabled - even when using target cache controls from page table.</p>
1:0	<p>LLC/eDRAM Cacheability Control (LeCC).</p> <p>Memory type information used in LLC/eDRAM.</p> <p>00b: Use Cacheability Controls from page table / UC with Fence (if coherent cycle).</p> <p>01b: Uncacheable (UC) – non-cacheable.</p> <p>10b: Writethrough (WT).</p> <p>11b: Writeback (WB).</p> <p>Note: In case of SVM (advanced context), LLC/eDRAM memory type is used based on the page table controls and cannot be managed via MOCS index.</p>



Defaults Table

Default	LeCC	TC	LRUM	AOM	ESC	SCC	PFM	Default	LeCC	TC	LRUM	AOM	ESC	SCC	PFM
000000	00	00	11	0	0	00	000	000000	00	00	11	0	0	00	000
000001	00	01	11	0	0	00	000	000001	00	01	11	0	0	00	000
000010	00	10	11	0	0	00	000	000010	00	10	11	0	0	00	000
000011	01	00	11	0	0	00	000	000011	01	00	11	0	0	00	000
000100	10	00	11	0	0	00	000	000100	10	00	11	0	0	00	000
000101	10	01	11	0	0	00	000	000101	10	01	11	0	0	00	000
000110	10	10	11	0	0	00	000	000110	10	10	11	0	0	00	000
000111	11	00	11	0	0	00	000	000111	11	00	11	0	0	00	000
001000	11	01	11	0	0	00	000	001000	11	01	11	0	0	00	000
001001	11	10	11	0	0	00	000	001001	11	10	11	0	0	00	000
001010	10	00	11	0	0	00	000	001010	10	00	11	0	0	00	000
001011	10	01	11	0	0	00	000	001011	10	01	11	0	0	00	000
001100	10	10	11	0	0	00	000	001100	10	10	11	0	0	00	000
001101	11	00	11	0	0	00	000	001101	11	00	11	0	0	00	000
001110	11	01	11	0	0	00	000	001110	11	01	11	0	0	00	000
001111	11	10	11	0	0	00	000	001111	11	10	11	0	0	00	000
010000	00	00	11	0	0	00	000	010000	00	00	11	0	0	00	000
010001	00	01	11	0	0	00	000	010001	00	01	11	0	0	00	000
010010	00	10	11	0	0	00	000	010010	00	10	11	0	0	00	000
010011	01	00	11	0	0	00	000	010011	01	00	11	0	0	00	000
010100	10	00	11	0	0	00	000	010100	10	00	11	0	0	00	000
010101	10	01	11	0	0	00	000	010101	10	01	11	0	0	00	000
010110	10	10	11	0	0	00	000	010110	10	10	11	0	0	00	000
010111	11	00	11	0	0	00	000	010111	11	00	11	0	0	00	000
011000	11	01	11	0	0	00	000	011000	11	01	11	0	0	00	000
011001	11	10	11	0	0	00	000	011001	11	10	11	0	0	00	000
011010	10	00	11	0	0	00	000	011010	10	00	11	0	0	00	000
011011	10	01	11	0	0	00	000	011011	10	01	11	0	0	00	000
011100	10	10	11	0	0	00	000	011100	10	10	11	0	0	00	000
011101	11	00	11	0	0	00	000	011101	11	00	11	0	0	00	000
011110	11	01	11	0	0	00	000	011110	11	01	11	0	0	00	000
011111	11	10	11	0	0	00	000	011111	11	10	11	0	0	00	000



HDCL3GAM Change Specific to Coherent L3

Given memory object control state is an index for L3 coherent accesses HDC cannot replace the bit[3:2] with the memory type information coming from GAM. Instead these two bits need to be communicated separately.

Both L3 and GAM override the memory type information that is extracted from the index table with these two bits passed by HDC in case of L3 coherent accesses.

Memory Type	Encoding in MTRR	HDC to L3 Control[3:2]
Uncacheable (UC)	0h	"00"
Write Combining (WC)	1h	"01"
Write Through (WT)	4h	"10"
Write Protected (WP) (Reads:WB and Writes:WC)	5h	Read: "11" Write: "01"
WriteBack (WB)	6h	"11"
Reserved*	2,3,7h	Reserved

Also for the HDC GAM interface (page request response), the faulting mode from indexed table needs to be communicated along with response. This would add 2 bits and HDC can use the mode bits to figure out what to do with the data.

This is also applicable to read return data from GAM.



Graphics Cache and Memory Interface

The memory interface has further improvements over previous generations. These improvements are either on existing functions or new features that are added to this particular generation.

Skip Caching in LLC and eDRAM

Skip Caching is added to deal with two specific problems:

1. If a given surface is too large for LLC or eDRAM, we want to cache a portion of the surface in the cache and get limited benefits instead of trying to cache the entire surface and trash the cache. Or not cache at all and lose any benefit of using a cache.
2. If a given surface can benefit from additional/concurrent b/w of both caches and/or memory, we can split the surface via allocating a certain segments of it in different caches and memory, and try to extract additional b/w. The opportunity would be additional b/w from different sources rather being stuck with cache b/w only.

For coherent surfaces, skip caching should not be enabled, as not caching in LLC breaks the coherency.

Mechanism can be controlled via memory object control state which is used to identify each surface separately.

Bit	Description
10:8	<p>Skip Caching Control (SCC).</p> <p>Defines the bit values to enable caching. Outcome overrides the LLC caching for the surface.</p> <p>If "0" then corresponding address bit value is don't care.</p> <ul style="list-style-type: none"> • Bit[8]=1: Address bit[9] needs to be "0" to cache in target. • Bit[9]=1: Address bit[10] needs to be "0" to cache in target. • Bit[10]=1: Address bit[11] needs to be "0" to cache in target.
7	<p>Enable Reverse Skip Caching (ESC).</p> <p>Enable for the Skip cache mechanism.</p> <ul style="list-style-type: none"> • 0: Not enabled. • 1: Enabled for reverse caching.

Here is the mechanism:

If bit[7]=0:

- If access is LLC cacheable and skip caching is enabled, match the enabled address bits:
 - If matched address bits, let the caching to be in LLC
 - If no-matched address bits, downgrade the caching to eLLC
- If access is eLLC/eDRAM cacheable (Only) and skip caching is enabled, match the enabled address bits:



- If matched address bits, let the caching to be in eLLC
- If no-matched address bits, downgrade the memory type to UC (uncacheable).

If bit[7]=1:

- If access is LLC cacheable and skip caching is enabled, match the enabled address bits:
 - If matched address bits, downgrade the caching to eLLC
 - If no-matched address bits, let the caching to be in LLC
- If access is eLLC/eDRAM cacheable (Only) and skip caching is enabled, match the enabled address bits:
 - If matched address bits, downgrade the memory type to UC (uncacheable).
 - If no-matched address bits, let the caching to be in eLLC

Caching Display Surfaces in LLC

Using LLC for the output Color pipeline when Display buffers are accessed has been tried for many generations. Previous generations enabled write-through caching to get benefits from reads. Generation GFX adds a mechanism to be able to cache display buffers that are immediate target of the color pipeline as write-back. In order to synchronize the contents of the display buffer within LLC to display controller, PG added an option at the pipe-control flush to select whether a color buffer flush is needed along with pipeline flush (see pipe-control and MI_Flush_DW definition updates).

For Frame buffer caching GFX driver will tag the corresponding Display buffer target as cacheable in LLC. LLC cacheability shall be selected via GFX Page tables (using private PAT) or MOCS (memory object control state). However this setting would enable for display buffers to be cached along with general GFX accesses which could lead to trashing in LLC cache along with long flush penalties. In order to limit the implications of an LLC flush, a global setting register (*IDICR – IDI Control Register[23:22]*) is included to control the QOS (quality of service) value for display buffers only. GFX driver is required to tune the QOS value based on system settings to limit the number of ways required to be allocated for frame buffer caching and to be flushed at the FLIP time.

For proper LLC flush event, GFX driver will program the cache definition registers (*FBCDR – Frame Buffer Cache Definition Register*) in the Page Walker register space to define different parameters of the LLCcache on the system.

Pipe-control and/or MI_FLUSH_DW for the contexts that have Frame Buffer caching has to be enhanced to enable overlap execution of the LLC flush as well as the execution of next context/frame by h/w. Not doing the following steps will cause GT h/w to stall on LLC flush which is not desirable.

In the case where Frame Buffer is cached, driver is required to put 2 pipe-controls and/or MI_FLUSH_DW's.

- The first will be used to flush the GPU h/w with a stall, and will not have LLC flush or SYNC'ing DW/interrupt to the driver.
- Second will be used to flush LLC with a SYNC DW/interrupt to the driver. This will not be a stalling pipe-control and/or MI_FLUSH_DW.



After first pipe-control/MI_FLUSH_DW, hardware will be free to execute forward on the command ring and 2nd pipe-control/MI_FLUSH_DW will be non-stalling for h/w but will hold off the FLIP synchronization to display controller until display buffer contents are flushed from LLC.

Page Walker Access and Memory Types

Most of these notes are further explained in the document however summarized as part of the page table behavior:

Page Walker Memory Types

1. Legacy Contexts
 - a. GT access to root/extended-root table and context/extended-context table
 - b. GTT access to private paging (PPGTT) entries
 - c. GT access to GPA-to-HPA paging entries
 - d. GT access to the translated page
2. Advanced context (without nesting)
 - a. GT access to extended-root table and extended-context table
 - b. GT access to PASID-entry & PASID-state entry
 - c. GT access to IA-32e paging entries
 - d. GT access to the translated page
3. Advanced context (with nesting)
 - a. GT access to extended-root table and extended-context table
 - b. GT access to PASID-entry & PASID-state entry
 - c. GT access to IA-32e paging entries
 - d. GT access to the translated page
 - e. GT access to GPA-to-HPA paging entries to translate address of PASID-entry and PASID-state entry
 - f. GT access to GPA-to-HPA paging entries to translate address of IA-32e paging entries
 - g. GT access to GPA-to-HPA paging entries to translate address of page

Error Cases

- A/D bit update attempt for paging entry in non-WB memory, cause page-walk to be aborted; Error reported to device in Translation Response; For Gen, gets reported to driver as GPGPU context in error – catastrophic error case.
- Locked/Atomic operations to pages in non-WB memory aborted; For Gen, gets reported to driver as GPGPU context in error (catastrophic error)
- CD=1 treated same as non-WB memory, for above lock behavior



Common Surface Formats

This section documents surfaces and how they are stored in memory, including 3D and video surfaces, including the details of compressed texture formats. Also covered are the surface layouts based on tiling mode and surface type.

Non-Video Surface Formats

This section describes the lowest-level organization of a surfaces containing discrete “pixel” oriented data (e.g., discrete pixel (RGB,YUV) colors, subsampled video data, 3D depth/stencil buffer pixel formats, bump map values etc. Many of these pixel formats are common to the various pixel-oriented memory object types.

Surface Format Naming

Unless indicated otherwise, all pixels are **stored** in “**little endian**” byte order. i.e., pixel bits 7:0 are stored in byte n , pixel bits 15:8 are stored in byte $n+1$, and so on. The format labels include color components in little endian order (e.g., R8G8B8A8 format is physically stored as R, G, B, A).

The name of most of the surface formats specifies its format. Channels are listed in little endian order (LSB channel on the left, MSB channel on the right), with the channel format specified following the channels with that format. For example, R5G5_SNORM_B6_UNORM contains, from LSB to MSB, 5 bits of red in SNORM format, 5 bits of green in SNORM format, and 6 bits of blue in UNORM format.

Intensity Formats

All surface formats containing “I” include an intensity value. When used as a source surface for the sampling engine, the intensity value is replicated to all four channels (R,G,B,A) before being filtered. Intensity surfaces are not supported as destinations.

Luminance Formats

All surface formats containing “L” include a luminance value. When used as a source surface for the sampling engine, the luminance value is replicated to the three color channels (R,G,B) before being filtered. The alpha channel is provided either from another field or receives a default value. Luminance surfaces are not supported as destinations.



R1_UNORM (same as R1_UINT) and MONO8

When used as a texel format, the R1_UNORM format contains 8 1-bit Intensity (I) values that are replicated to all color channels. Note that T0 of byte 0 of a R1_UNORM-formatted texture corresponds to Texel[0,0]. This is different from the format used for monochrome sources in the BLT engine.

7	6	5	4	3	2	1	0
T7	T6	T5	T4	T3	T2	T1	T0

Bit	Description
T0	<p>Texel 0</p> <p>On texture reads, this (unsigned) 1-bit value is replicated to all color channels.</p> <p>Format: U1</p>
...	...
T7	<p>Texel 7</p> <p>On texture reads, this (unsigned) 1-bit value is replicated to all color channels.</p> <p>Format: U1</p>

MONO8 format is identical to R1_UNORM but has different semantics for filtering. MONO8 is the only supported format for the MAPFILTER_MONO filter. See the *Sampling Engine* chapter.



Palette Formats

Palette formats are supported by the sampling engine. These formats include an index into the palette (Px) that selects the actual channel values from the palette, which is loaded via the 3DSTATE_SAMPLER_PALETTE_LOAD0 command.

P4A4_UNORM

This surface format contains a 4-bit Alpha value (in the high nibble) and a 4-bit Palette Index value (in the low nibble).

7	6	5	4	3	2	1	0
Alpha				Palette Index			

Bit	Description
7:4	<p>Alpha</p> <p>Alpha value which will be replicated to both the high and low nibble of an 8-bit value, and then divided by 255 to yield a [0.0,1.0] Alpha value.</p> <p>Format: U4</p>
3:0	<p>Palette Index</p> <p>A 4-bit index which is used to lookup a 24-bit (RGB) value in the texture palette (loaded via 3DSTATE_SAMPLER_PALETTE_LOADx)</p> <p>Format: U4</p>

A4P4_UNORM

This surface format contains a 4-bit Alpha value (in the low nibble) and a 4-bit Color Index value (in the high nibble).

7	6	5	4	3	2	1	0
Palette Index				Alpha			

Bit	Description
7:4	<p>Palette Index</p> <p>A 4-bit color index which is used to lookup a 24-bit RGB value in the texture palette.</p> <p>Format: U4</p>



Bit	Description
3:0	<p>Alpha</p> <p>Alpha value which will be replicated to both the high and low nibble of an 8-bit value, and then divided by 255 to yield a [0.0,1.0] alpha value.</p> <p>Format: U4</p>

P8A8_UNORM

This surface format contains an 8-bit Alpha value (in the high byte) and an 8-bit Palette Index value (in the low byte).

15		8	7			0
Alpha			Palette Index			

Bit	Description
15:8	<p>Alpha</p> <p>Alpha value which will be divided by 255 to yield a [0.0,1.0] Alpha value.</p> <p>Format: U8</p>
7:0	<p>Palette Index</p> <p>An 8-bit index which is used to lookup a 24-bit (RGB) value in the texture palette (loaded via 3DSTATE_SAMPLER_PALETTE_LOADx)</p> <p>Format: U8</p>

A8P8_UNORM

This surface format contains an 8-bit Alpha value (in the low byte) and an 8-bit Color Index value (in the high byte).

15			8	7		0
Palette Index			Alpha			

Bit	Description
15:8	<p>Palette Index</p> <p>An 8-bit color index which is used to lookup a 24-bit RGB value in the texture palette.</p> <p>Format: U8</p>



Bit	Description
7:0	Alpha Alpha value which will be divided by 255 to yield a [0.0,1.0] alpha value. Format: U8

P8_UNORM

This surface format contains only an 8-bit Color Index value.

Bit	Description
7:0	Palette Index An 8-bit color index which is used to lookup a 32-bit ARGB value in the texture palette. Format: U8

P2_UNORM

This surface format contains only a 2-bit Color Index value.

Bit	Description
1:0	Palette Index A 2-bit color index which is used to lookup a 32-bit ARGB value in the texture palette. Format: U2

Compressed Surface Formats

This section contains information on the internal organization of compressed surface formats.

ETC1_RGB8

This format compresses UNORM RGB data using an 8-byte compression block representing a 4x4 block of texels. The texels are labeled as texel[row][column] where both row and column range from 0 to 3. Texel[0][0] is the upper left texel.

The 8-byte compression block is laid out as follows.

High 24 bits if “diff” is zero (individual mode):

Bits	Description
7:4	R0[3:0]
3:0	R1[3:0]
15:12	G0[3:0]
11:8	G1[3:0]
23:20	B0[3:0]
19:16	B1[3:0]

High 24 bits if “diff” is one (differential mode):

Bits	Description
7:3	R0[4:0]
2:0	dR1[2:0]
15:11	G0[4:0]
10:8	dG1[2:0]
23:19	B0[4:0]
18:16	dB1[2:0]

Low 40 bits:

Bits	Description
31:29	lum table index for sub-block 0
28:26	lum table index for sub-block 1
25	diff
24	flip
39	texel[3][3] index MSB
38	texel[2][3] index MSB
37	texel[1][3] index MSB
36	texel[0][3] index MSB
35	texel[3][2] index MSB



Bits	Description
34	texel[2][2] index MSB
33	texel[1][2] index MSB
32	texel[0][2] index MSB
47	texel[3][1] index MSB
46	texel[2][1] index MSB
45	texel[1][1] index MSB
44	texel[0][1] index MSB
43	texel[3][0] index MSB
42	texel[2][0] index MSB
41	texel[1][0] index MSB
40	texel[0][0] index MSB
55	texel[3][3] index LSB
54	texel[2][3] index LSB
53	texel[1][3] index LSB
52	texel[0][3] index LSB
51	texel[3][2] index LSB
50	texel[2][2] index LSB
49	texel[1][2] index LSB
48	texel[0][2] index LSB
63	texel[3][1] index LSB
62	texel[2][1] index LSB
61	texel[1][1] index LSB
60	texel[0][1] index LSB
59	texel[3][0] index LSB
58	texel[2][0] index LSB
57	texel[1][0] index LSB
56	texel[0][0] index LSB

The 4x4 is divided into two 8-pixel sub-blocks, either two 2x4 sub-blocks or two 4x2 sub-blocks controlled by the “flip” bit. If flip=0, sub-block 0 is the 2x4 on the left and sub-block 1 is the 2x4 on the right. If flip=1, sub-block 0 is the 4x2 on the top and sub-block 1 is the 4x2 on the bottom.

The “diff” bit controls whether the red/green/blue values (R0/G0/B0/R1/G1/B1) are stored as one 444 value per sub-block (“individual” mode with diff = 0), or a single 555 value for the first sub-block (R0/G0/B0) and a 333 delta value (dR1/dG1/dB1) for the second sub-block (“differential” mode with diff = 1). The delta values are 3-bit two’s-complement values that hold values in the range [-4,3]. These values are added to the 5-bit values for sub-block 0 to obtain the 5-bit values for sub-block 1 (if the value is outside of the range [0,31], the result of the decompression is undefined). From the 4- or 5-bit



per channel values, an 8-bit value for each channel is extended by replication and provides the 888 base color for each sub-block.

For each sub-block one of 8 different luminance columns is selected based on the 3-bit lum table index. Then each texel selects one of the 4 rows of the selected column with a 2-bit per-texel index. The chosen value in the table is added to the 8-bit base color for the sub-block (obtained in the previous step) to obtain the texel's color. Values in the table are given in decimal, representing an 8-bit UNORM as an 8-bit signed integer.

Luminance Table

	0	1	2	3	4	5	6	7
0	2	5	9	13	18	24	33	47
1	8	17	29	42	60	80	106	183
2	-2	-5	-9	-13	-18	-24	-33	-47
3	-8	-17	-29	-42	-60	-80	-106	-183

ETC2_RGB8 and ETC2_SRGB8

The ETC2_RGB8 format builds on top of ETC1_RGB8, using a set of invalid bit sequences to enable three new modes. The two modes of ETC1_RGB8 are also supported with ETC2_RGB8, and will not be documented in this section as they are covered in the ETC1_RGB8 section.

The detection of the three new modes is based on RGB and diff bits in locations as defined for ETC1 differential mode. The mode is determined as follows (x indicates don't care):

diff	Rt	Gt	Bt	mode
0	x	x	x	individual
1	0	x	x	T
1	1	0	x	H
1	1	1	0	planar
1	1	1	1	differential

The inputs in the above table are defined as follows:

```
Rt = (R0 + dR1) in [0,31]
Gt = (G0 + dG1) in [0,31]
Bt = (G0 + dB1) in [0,31]
```



8-byte compression block for mode determination

Bits	Description
7:3	R0[4:0]
2:0	dR1[2:0]
15:11	G0[4:0]
10:8	dG1[2:0]
23:19	B0[4:0]
18:16	dB1[2:0]
31:26	ignored
25	diff
24	ignored
63:32	ignored

The fields in the table above are used *only* for mode determination. Some of the bits in this table are overloaded with other values within each mode. The algorithm is defined such that there is no ambiguity in modes when this is done.

T mode

The “T” mode has the following bit definition:

8-byte compression block for “T” mode

Bits	Description
7:5	ignored
4:3	R0[3:2]
2	ignored
1:0	R0[1:0]
15:12	G0[3:0]
11:8	B0[3:0]
23:20	R1[3:0]
19:16	G1[3:0]
31:28	B1[3:0]
27:26	di[2:1]
25	diff = 1
24	di[0]
39	texel[3][3] index MSB
38	texel[2][3] index MSB
37	texel[1][3] index MSB



Bits	Description
36	texel[0][3] index MSB
35	texel[3][2] index MSB
34	texel[2][2] index MSB
33	texel[1][2] index MSB
32	texel[0][2] index MSB
47	texel[3][1] index MSB
46	texel[2][1] index MSB
45	texel[1][1] index MSB
44	texel[0][1] index MSB
43	texel[3][0] index MSB
42	texel[2][0] index MSB
41	texel[1][0] index MSB
40	texel[0][0] index MSB
55	texel[0][0] index LSB
54	texel[2][3] index LSB
53	texel[1][3] index LSB
52	texel[0][3] index LSB
51	texel[3][2] index LSB
50	texel[2][2] index LSB
49	texel[1][2] index LSB
48	texel[0][2] index LSB
63	texel[3][1] index LSB
62	texel[2][1] index LSB
61	texel[1][1] index LSB
60	texel[0][1] index LSB
59	texel[3][0] index LSB
58	texel[2][0] index LSB
57	texel[1][0] index LSB
56	texel[0][0] index LSB

The "T" mode has two base colors stored as 4 bits per channel, R0/G0/B0 and R1/G1/B1, as in the individual mode, however the bit positions for these are different. For each channel, the 4 bits are extended to 8 bits by bit replication.

A 3-bit distance index "di" is also defined in the compression block. This value is used to look up the distance in the following table:



distance index "di"	distance "d"
0	3
1	6
2	11
3	16
4	23
5	32
6	41
7	64

Four colors are possible on each texel. These colors are defined as the following:

$$\begin{aligned} P0 &= (R0, G0, B0) \\ P1 &= (R1, G1, B1) + (d, d, d) \\ P2 &= (R1, G1, B1) \\ P3 &= (R1, G1, B1) - (d, d, d) \end{aligned}$$

All resulting channels are clamped to the range [0,255]. One of the four colors is then assigned to each texel in the block based on the 2-bit texel index.

H mode

The "H" mode has the following bit definition:

8-byte compression block for "H" mode

Bits	Description
7	ignored
6:3	R0[3:0]
2:0	G0[3:1]
15:13	ignored
12	G0[0]
11	B0[3]
10	ignored
9:8	B0[2:1]
23	B0[0]
22:19	R1[3:0]
18:16	G1[3:1]
31	G1[0]
30:27	B1[3:0]
26	di[2]



Bits	Description
25	diff = 1
24	di[1]
39	texel[3][3] index MSB
38	texel[2][3] index MSB
37	texel[1][3] index MSB
36	texel[0][3] index MSB
35	texel[3][2] index MSB
34	texel[2][2] index MSB
33	texel[1][2] index MSB
32	texel[0][2] index MSB
47	texel[3][1] index MSB
46	texel[2][1] index MSB
45	texel[1][1] index MSB
44	texel[0][1] index MSB
43	texel[3][0] index MSB
42	texel[2][0] index MSB
41	texel[1][0] index MSB
40	texel[0][0] index MSB
55	texel[3][3] index LSB
54	texel[2][3] index LSB
53	texel[1][3] index LSB
52	texel[0][3] index LSB
51	texel[3][2] index LSB
50	texel[2][2] index LSB
49	texel[1][2] index LSB
48	texel[0][2] index LSB
63	texel[3][1] index LSB
62	texel[2][1] index LSB
61	texel[1][1] index LSB
60	texel[0][1] index LSB
59	texel[3][0] index LSB
58	texel[2][0] index LSB
57	texel[1][0] index LSB
56	texel[0][0] index LSB



The "H" mode has two base colors stored as 4 bits per channel, R0/G0/B0 and R1/G1/B1, as in the individual and T modes, however the bit positions for these are different. For each channel, the 4 bits are extended to 8 bits by bit replication.

A 3-bit distance index "di" is defined by 2 MSBs in the compression block and the LSB computed by the following equation, where R/G/B values are the 8-bit values from the first step:

$$di[0] = ((R0 \ll 16) | (G0 \ll 8) | B0) \gg ((R1 \ll 16) | (G1 \ll 8) | B1)$$

The distance "d" is then looked up in the same table used for T mode. The four colors for H mode are computed as follows:

$$\begin{aligned}
P0 &= (R0, G0, B0) + (d, d, d) \\
P1 &= (R0, G0, B0) - (d, d, d) \\
P2 &= (R1, G1, B1) + (d, d, d) \\
P3 &= (R1, G1, B1) - (d, d, d)
\end{aligned}$$

All resulting channels are clamped to the range [0,255]. One of the four colors is then assigned to each texel in the block based on the 2-bit texel index as in T mode.

Planar mode

The "planar" mode has the following bit definition:

8-byte compression block for "planar" mode

Bits	Description
7	ignored
6:1	R0[5:0]
0	G0[6]
15	ignored
14:9	G0[5:0]
8	B[5]
23:21	ignored
20:19	B[4:3]
18	ignored
17:16	B0[2:1]
31	B0[0]
30:26	RH[5:1]
25	diff = 1
24	RH[0]
39:33	GH[6:0]
32	BH[5]
47:43	BH[4:0]



Bits	Description
42:40	RV[5:3]
55:53	RV[2:0]
52:48	GV[6:2]
63:62	GV[1:0]
61:56	BV[5:0]

The “planar” mode has three base colors stored as RGB 676, with red & blue having 6 bits and green having 7 bits. These three base colors are each extended to RGB 888 with bit replication.

The color of each texel is then computed using the following equations, with x and y representing the texel position within the compression block:

$$\begin{aligned} \text{texel}[y][x].R &= x(RH-R0)/4 + y(RV-R0)/4 + R0 \\ \text{texel}[y][x].G &= x(GH-G0)/4 + y(GV-G0)/4 + G0 \\ \text{texel}[y][x].B &= x(BH-B0)/4 + y(BV-B0)/4 + B0 \end{aligned}$$

All resulting channels are clamped to the range [0,255].

The ETC2_SRGB8 format is decompressed as if it is ETC2_RGB8, then a conversion from the resulting RGB values to SRGB space is performed.

EAC_R11 and EAC_SIGNED_R11

These formats compress UNORM/SNORM single-channel data using an 8-byte compression block representing a 4x4 block of texels. The texels are labeled as texel[row][column] where both row and column range from 0 to 3. Texel[0][0] is the upper left texel.

The 8-byte compression block is laid out as follows.

EAC_R11 compression block layout

Bits	Description
7:0	R0[7:0]
15:12	m[3:0]
11:8	ti[3:0]
23:21	texel[0][0] index
20:18	texel[1][0] index
17:16,31	texel[2][0] index
30:28	texel[3][0] index
27:25	texel[0][1] index
24,39:38	texel[1][1] index
37:35	texel[2][1] index
34:32	texel[3][1] index
47:45	texel[0][2] index



Bits	Description
44:42	texel[1][2] index
41:40,55	texel[2][2] index
54:52	texel[3][2] index
51:49	texel[0][3] index
48,63:62	texel[1][3] index
61:59	texel[2][3] index
58:56	texel[3][3] index

The "ti" (table index) value from the compression block is used to select one of the columns in the table below.

Intensity modifier (im) table

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	-3	-3	-2	-2	-3	-3	-4	-3	-2	-2	-2	-2	-3	-1	-4	-3
1	-6	-7	-5	-4	-6	-7	-7	-5	-6	-5	-4	-5	-4	-2	-6	-5
2	-9	-10	-8	-6	-8	-9	-8	-8	-8	-8	-8	-7	-7	-3	-8	-7
3	-15	-13	-13	-13	-12	-11	-11	-11	-10	-10	-10	-10	-10	-10	-9	-9
4	2	2	1	1	2	2	3	2	1	1	1	1	2	0	3	2
5	5	6	4	3	5	6	6	4	5	4	3	4	3	1	5	4
6	8	9	7	5	7	8	7	7	7	7	7	6	6	2	7	6
7	14	12	12	12	11	10	10	10	9	9	9	9	9	9	8	8

The eight possible color values R_i are then computed from the 8 values in the column labeled im_i , where i ranges from 0 to 7:

For EAC_R11:

$$\text{if } (m == 0) R_i = R0 * 8 + 4 + im_i \text{ else } R_i = R0 * 8 + 4 + (im_i * m * 8)$$

Each value is clamped to the range [0,2047].

For EAC_SIGNED_R11:

$$\text{if } (m == 0) R_i = R0 * 8 + im_i \text{ else } R_i = R0 * 8 + (im_i * m * 8)$$

Each value is clamped to the range [-1023,1023].



Note that in the signed case, the R0 value is a signed, 2's complement value in the range [-127, 127]. Before being used in the above equations, an R0 value of -128 must be clamped to -127.

Finally, each texel red value is selected from the 8 possible values R_i using the 3-bit index for that texel. The green, blue, and alpha values are set to their default values.

The final value represents an 11-bit UNORM or SNORM as an unsigned/signed integer.

ETC2_RGB8_PTA and ETC2_SRGB8_PTA

The ETC2_RGB8_PTA format is similar to ETC2_RGB8 but eliminates the "individual" mode in favor of allowing a punch-through alpha. The "diff" bit from ETC2_RGB8 is renamed to "opaque" in this format, and the mode selection behaves as if the "diff" bit is always 1, making the "individual" mode inaccessible for these formats.

An alpha value of either 0 or 255 (representing 0.0 or 1.0) is possible with this format. If alpha is determined to be zero, the three other channels are also forced to zero, regardless of what value the normal decompression algorithm would have produced.

Differential Mode

In differential mode, if the opaque bit is set, the luminance table for ETC2_RGB8 is used. If the opaque bit is not set, the following luminance table is used (note that rows 0 and 2 have been zeroed out, otherwise the table is the same):

Luminance Table for opaque bit not set

	0	1	2	3	4	5	6	7
0	0	0	0	0	0	0	0	0
1	8	17	29	42	60	80	106	183
2	0	0	0	0	0	0	0	0
3	-8	-17	-29	-42	-60	-80	-106	-183

For each texel, if the opaque bit is zero and the corresponding texel index is equal to 2, the alpha value is set to zero (and therefore RGB for that texel will also end up at zero). Otherwise alpha is set to 255 and RGB is the result of the normal decompression calculations.

T and H Modes

In both of these modes, if the opaque bit is zero and the texel index is equal to 2, the alpha value is set to zero (and therefore RGB will also end up at zero). Otherwise alpha is set to 255.



Planar Mode

In planar mode, the opaque bit is ignored and alpha is set to 255.

The ETC2_SRGB8_PTA format is decompressed as if it is ETC2_RGB8_PTA, then a conversion from the resulting RGB values to SRGB space is performed, with alpha remaining unchanged.

ETC2_EAC_RGBA8 and ETC2_EAC_SRGB8_A8

The ETC2_EAC_RGBA8 format is a combination of ETC2_RGB8 and EAC_R8. A 16-byte compression block represents each 4x4. The low-order 8 bytes are used to compute alpha (instead of red) using the EAC_R8 algorithm. The high-order 8 bytes are used to compute RGB using the ETC2_RGB8 algorithm. The EAC_R8 format differs from EAC_R11 as described below.

The ETC2_EAC_SRGB8_A8 format is decompressed as if it is ETC2_EAC_RGBA8, then a conversion from the resulting RGB values to SRGB space is performed, with alpha remaining unchanged.

EAC_R8 Format:

The EAC_R8 format used within these surface formats is identical to EAC_R11 described in an earlier section, except the procedure for computing the eight possible color values Ri is performed as follows:

$$R_i = R_0 + (i \cdot m)$$

Each value is clamped to the range [0,255].

EAC_RG11 and EAC_SIGNED_RG11

These formats compress UNORM/SNORM double-channel data using a 16-byte compression block representing a 4x4 block of texels. The texels are labeled as texel[row][column] where both row and column range from 0 to 3. Texel[0][0] is the upper left texel.

The 16-byte compression block is laid out as follows.

EAC_RG11 compression block layout

Bits	Description
63:56	G0[7:0]
55:52	Gm[3:0]
51:48	Gti[3:0]
47:45	texel[0][0] G index
44:42	texel[1][0] G index
41:39	texel[2][0] G index
38:36	texel[3][0] G index
35:33	texel[0][1] G index
32:30	texel[1][1] G index
29:27	texel[2][1] G index
26:24	texel[3][1] G index



Bits	Description
23:21	texel[0][2] G index
20:18	texel[1][2] G index
17:15	texel[2][2] G index
14:12	texel[3][2] G index
11:9	texel[0][3] G index
8:6	texel[1][3] G index
5:3	texel[2][3] G index
66:64	texel[3][3] G index
63:56	R0[7:0]
55:52	Rm[3:0]
51:48	Rti[3:0]
47:45	texel[0][0] R index
44:42	texel[1][0] R index
41:39	texel[2][0] R index
38:36	texel[3][0] R index
35:33	texel[0][1] R index
32:30	texel[1][1] R index
29:27	texel[2][1] R index
26:24	texel[3][1] R index
23:21	texel[0][2] R index
20:18	texel[1][2] R index
17:15	texel[2][2] R index
14:12	texel[3][2] R index
11:9	texel[0][3] R index
8:6	texel[1][3] R index
5:3	texel[2][3] R index
2:0	texel[3][3] R index

These compression formats are identical to the EAC_R11 and EAC_SIGNED_R11 formats, except that they supply two channels of output data, both red and green, from two independent 8-byte portions of the compression block. The low half of the compression block contains the red information, and the high half contains the green information. Blue and alpha channels are set to their default values.

Refer to the EAC_R11 and EAC_SIGNED_R11 specification for details on how the red and green channels are generated using the data in the compression block.



FXT Texture Formats

There are four different FXT1 compressed texture formats. Each of the formats compress two 4x4 texel blocks into 128 bits. In each compression format, the 32 texels in the two 4x4 blocks are arranged according to the following diagram:

FXT1 Encoded Blocks

t0	t1	t2	t3	t16	t17	t18	t19
t4	t5	t6	t7	t20	t21	t22	t23
t8	t9	t10	t11	t24	t25	t26	t27
t12	t13	t14	t15	t28	t29	t30	t31

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Overview of FXT1 Formats

During the compression phase, the encoder selects one of the four formats for each block based on which encoding scheme results in best overall visual quality. The following table lists the four different modes and their encodings:

FXT1 Format Summary

Bit 127	Bit 126	Bit 125	Block Compression Mode	Summary Description
0	0	X	CC_HI	2 R5G5B5 colors supplied. Single LUT with 7 interpolated color values and transparent black
0	1	0	CC_CHROMA	4 R5G5B5 colors used directly as 4-entry LUT.
0	1	1	CC_ALPHA	3 A5R5G5B5 colors supplied. LERP bit selects between 1 LUT with 3 discrete colors + transparent black and 2 LUTs using interpolated values of Color 0,1 (t0-15) and Color 1,2 (t16-31).
1	x	x	CC_MIXED	4 R5G5B5 colors supplied, where Color0,1 LUT is used for t0-t15, and Color2,3 LUT used for t16-31. Alpha bit selects between LUTs with 4 interpolated colors or 3 interpolated colors + transparent black.

FXT1 CC_HI Format

In the CC_HI encoding format, two base 15-bit R5G5B5 colors (Color 0, Color 1) are included in the encoded block. These base colors are then expanded (using high-order bit replication) to 24-bit RGB colors, and used to define an 8-entry lookup table of interpolated color values (the 8th entry is



transparent black). The encoded block contains a 3-bit index value per texel that is used to lookup a color from the table.

CC_HI Block Encoding

The following table describes the encoding of the 128-bit (DQWord) CC_HI block format:

FXT CC_HI Block Encoding

Bit	Description
127:126	Mode = '00'b (CC_HI)
125:121	Color 1 Red
120:116	Color 1 Green
115:111	Color 1 Blue
110:106	Color 0 Red
105:101	Color 0 Green
100:96	Color 0 Blue
95:93	Texel 31 Select
...	...
50:48	Texel 16 Select
47:45	Texel 15 Select
...	...
2:0	Texel 0 Select

CC_HI Block Decoding

The two base colors, Color 0 and Color 1 are converted from R5G5B5 to R8G8B8 by replicating the 3 MSBs into the 3 LSBs, as shown in the following table:

FXT CC_HI Decoded Colors

Expanded Color Bit	Expanded Channel Bit	Encoded Block Source Bit
Color 1 [23:19]	Color 1 Red [7:3]	[125:121]
Color 1 [18:16]	Color 1 Red [2:0]	[125:123]
Color 1 [15:11]	Color 1 Green [7:3]	[120:116]
Color 1 [10:08]	Color 1 Green [2:0]	[120:118]
Color 1 [07:03]	Color 1 Blue [7:3]	[115:111]
Color 1 [02:00]	Color 1 Blue [2:0]	[115:113]
Color 0 [23:19]	Color 0 Red [7:3]	[110:106]
Color 0 [18:16]	Color 0 Red [2:0]	[110:108]
Color 0 [15:11]	Color 0 Green [7:3]	[105:101]



Expanded Color Bit	Expanded Channel Bit	Encoded Block Source Bit
Color 0 [10:08]	Color 0 Green [2:0]	[105:103]
Color 0 [07:03]	Color 0 Blue [7:3]	[100:96]
Color 0 [02:00]	Color 0 Blue [2:0]	[100:98]

These two 24-bit colors (Color 0, Color 1) are then used to create a table of seven interpolated colors (with Alpha = 0FFh), along with an eight entry equal to RGBA = 0,0,0,0, as shown in the following table:

FXT CC_HI Interpolated Color Table

Interpolated Color	Color RGB	Alpha
0	Color0.RGB	0FFh
1	$(5 * \text{Color0.RGB} + 1 * \text{Color1.RGB} + 3) / 6$	0FFh
2	$(4 * \text{Color0.RGB} + 2 * \text{Color1.RGB} + 3) / 6$	0FFh
3	$(3 * \text{Color0.RGB} + 3 * \text{Color1.RGB} + 3) / 6$	0FFh
4	$(2 * \text{Color0.RGB} + 4 * \text{Color1.RGB} + 3) / 6$	0FFh
5	$(1 * \text{Color0.RGB} + 5 * \text{Color1.RGB} + 3) / 6$	0FFh
6	Color1.RGB	0FFh
7	RGB = 0,0,0	0

This table is then used as an 8-entry Lookup Table, where each 3-bit Texel n Select field of the encoded CC_HI block is used to index into a 32-bit A8R8G8B8 color from the table completing the decode of the CC_HI block.

FXT1 CC_CHROMA Format

In the CC_CHROMA encoding format, four 15-bit R5B5G5 colors are included in the encoded block. These colors are then expanded (using high-order bit replication) to form a 4-entry table of 24-bit RGB colors. The encoded block contains a 2-bit index value per texel that is used to lookup a 24-bit RGB color from the table. The Alpha component defaults to fully opaque (0FFh).

CC_CHROMA Block Encoding

The following table describes the encoding of the 128-bit (DQWord) CC_CHROMA block format:

FXT CC_CHROMA Block Encoding

Bit	Description
127:125	Mode = '010'b (CC_CHROMA)
124	Unused
123:119	Color 3 Red
118:114	Color 3 Green
113:109	Color 3 Blue



Bit	Description
108:104	Color 2 Red
103:99	Color 2 Green
98:94	Color 2 Blue
93:89	Color 1 Red
88:84	Color 1 Green
83:79	Color 1 Blue
78:74	Color 0 Red
73:69	Color 0 Green
68:64	Color 0 Blue
63:62	Texel 31 Select
...	
33:32	Texel 16 Select
31:30	Texel 15 Select
...	
1:0	Texel 0 Select

CC_CHROMA Block Decoding

The four colors (Color 0-3) are converted from R5G5B5 to R8G8B8 by replicating the 3 MSBs into the 3 LSBs, as shown in the following tables:

FXT CC_CHROMA Decoded Colors

Expanded Color Bit	Expanded Channel Bit	Encoded Block Source Bit
Color 3 [23:17]	Color 3 Red [7:3]	[123:119]
Color 3 [18:16]	Color 3 Red [2:0]	[123:121]
Color 3 [15:11]	Color 3 Green [7:3]	[118:114]
Color 3 [10:08]	Color 3 Green [2:0]	[118:116]
Color 3 [07:03]	Color 3 Blue [7:3]	[113:109]
Color 3 [02:00]	Color 3 Blue [2:0]	[113:111]
Color 2 [23:17]	Color 2 Red [7:3]	[108:104]
Color 2 [18:16]	Color 2 Red [2:0]	[108:106]
Color 2 [15:11]	Color 2 Green [7:3]	[103:99]
Color 2 [10:08]	Color 2 Green [2:0]	[103:101]
Color 2 [07:03]	Color 2 Blue [7:3]	[98:94]
Color 2 [02:00]	Color 2 Blue [2:0]	[98:96]
Color 1 [23:17]	Color 1 Red [7:3]	[93:89]
Color 1 [18:16]	Color 1 Red [2:0]	[93:91]



Expanded Color Bit	Expanded Channel Bit	Encoded Block Source Bit
Color 1 [15:11]	Color 1 Green [7:3]	[88:84]
Color 1 [10:08]	Color 1 Green [2:0]	[88:86]
Color 1 [07:03]	Color 1 Blue [7:3]	[83:79]
Color 1 [02:00]	Color 1 Blue [2:0]	[83:81]
Color 0 [23:17]	Color 0 Red [7:3]	[78:74]
Color 0 [18:16]	Color 0 Red [2:0]	[78:76]
Color 0 [15:11]	Color 0 Green [7:3]	[73:69]
Color 0 [10:08]	Color 0 Green [2:0]	[73:71]
Color 0 [07:03]	Color 0 Blue [7:3]	[68:64]
Color 0 [02:00]	Color 0 Blue [2:0]	[68:66]

This table is then used as a 4-entry Lookup Table, where each 2-bit Texel n Select field of the encoded CC_CHROMA block is used to index into a 32-bit A8R8G8B8 color from the table (Alpha defaults to 0FFh) completing the decode of the CC_CHROMA block.

FXT CC_CHROMA Interpolated Color Table

Texel Select	Color ARGB
0	Color0.ARGB
1	Color1.ARGB
2	Color2.ARGB
3	Color3.ARGB

FXT1 CC_MIXED Format

In the CC_MIXED encoding format, four 15-bit R5G5B5 colors are included in the encoded block: Color 0 and Color 1 are used for Texels 0-15, and Color 2 and Color 3 are used for Texels 16-31.

Each pair of colors are then expanded (using high-order bit replication) to form 4-entry tables of 24-bit RGB colors. The encoded block contains a 2-bit index value per texel that is used to lookup a 24-bit RGB color from the table. The Alpha component defaults to fully opaque (0FFh).

CC_MIXED Block Encoding

The following table describes the encoding of the 128-bit (DQWord) CC_MIXED block format:

FXT CC_MIXED Block Encoding

Bit	Description
127	Mode = '1'b (CC_MIXED)
126	Color 3 Green [0]
125	Color 1 Green [0]



Bit	Description
124	Alpha [0]
123:119	Color 3 Red
118:114	Color 3 Green
113:109	Color 3 Blue
108:104	Color 2 Red
103:99	Color 2 Green
98:94	Color 2 Blue
93:89	Color 1 Red
88:84	Color 1 Green
83:79	Color 1 Blue
78:74	Color 0 Red
73:69	Color 0 Green
68:64	Color 0 Blue
63:62	Texel 31 Select
...	...
33:32	Texel 16 Select
31:30	Texel 15 Select
...	...
1:0	Texel 0 Select

CC_MIXED Block Decoding

The decode of the CC_MIXED block is modified by Bit 124 (Alpha [0]) of the encoded block.

Alpha[0] = 0 Decoding

When Alpha[0] = 0 the four colors are encoded as 16-bit R5G6B5 values, with the Green LSB defined as per the following table:

FXT CC_MIXED (Alpha[0]=0) Decoded Colors

Encoded Color Bit	Definition
Color 3 Green [0]	Encoded Bit [126]
Color 2 Green [0]	Encoded Bit [33] XOR Encoded Bit [126]
Color 1 Green [0]	Encoded Bit [125]
Color 0 Green [0]	Encoded Bit [1] XOR Encoded Bit [125]

The four colors (Color 0-3) are then converted from R5G5B6 to R8G8B8 by replicating the 3 MSBs into the 3 LSBs, as shown in the following table:



FXT CC_MIXED Decoded Colors (Alpha[0] = 0)

Expanded Color Bit	Expanded Channel Bit	Encoded Block Source Bit
Color 3 [23:17]	Color 3 Red [7:3]	[123:119]
Color 3 [18:16]	Color 3 Red [2:0]	[123:121]
Color 3 [15:11]	Color 3 Green [7:3]	[118:114]
Color 3 [10]	Color 3 Green [2]	[126]
Color 3 [09:08]	Color 3 Green [1:0]	[118:117]
Color 3 [07:03]	Color 3 Blue [7:3]	[113:109]
Color 3 [02:00]	Color 3 Blue [2:0]	[113:111]
Color 2 [23:17]	Color 2 Red [7:3]	[108:104]
Color 2 [18:16]	Color 2 Red [2:0]	[108:106]
Color 2 [15:11]	Color 2 Green [7:3]	[103:99]
Color 2 [10]	Color 2 Green [2]	[33] XOR [126]
Color 2 [09:08]	Color 2 Green [1:0]	[103:100]
Color 2 [07:03]	Color 2 Blue [7:3]	[98:94]
Color 2 [02:00]	Color 2 Blue [2:0]	[98:96]
Color 1 [23:17]	Color 1 Red [7:3]	[93:89]
Color 1 [18:16]	Color 1 Red [2:0]	[93:91]
Color 1 [15:11]	Color 1 Green [7:3]	[88:84]
Color 1 [10]	Color 1 Green [2]	[125]
Color 1 [09:08]	Color 1 Green [1:0]	[88:86]
Color 1 [07:03]	Color 1 Blue [7:3]	[83:79]
Color 1 [02:00]	Color 1 Blue [2:0]	[83:81]
Color 0 [23:17]	Color 0 Red [7:3]	[78:74]
Color 0 [18:16]	Color 0 Red [2:0]	[78:76]
Color 0 [15:11]	Color 0 Green [7:3]	[73:69]
Color 0 [10]	Color 0 Green [2]	[1] XOR [125]
Color 0 [09:08]	Color 0 Green [1:0]	[73:71]
Color 0 [07:03]	Color 0 Blue [7:3]	[68:64]
Color 0 [02:00]	Color 0 Blue [2:0]	[68:66]

The two sets of 24-bit colors (Color 0,1 and Color 2,3) are then used to create two tables of four interpolated colors (with Alpha = 0FFh). The Color0,1 table is used as a lookup table for texel 0-15 indices, and the Color2,3 table used for texels 16-31 indices, as shown in the following figures:

FXT CC_MIXED Interpolated Color Table (Alpha[0]=0, Texels 0-15)

Texel 0-15 Select	Color RGB	Alpha
0	Color0.RGB	0FFh



Texel 0-15 Select	Color RGB	Alpha
1	$(2 * \text{Color0.RGB} + \text{Color1.RGB} + 1) / 3$	0FFh
2	$(\text{Color0.RGB} + 2 * \text{Color1.RGB} + 1) / 3$	0FFh
3	Color1.RGB	0FFh

FXT CC_MIXED Interpolated Color Table (Alpha[0]=0, Texels 16-31)

Texel 16-31 Select	Color RGB	Alpha
0	Color2.RGB	0FFh
1	$(2/3) * \text{Color2.RGB} + (1/3) * \text{Color3.RGB}$	0FFh
2	$(1/3) * \text{Color2.RGB} + (2/3) * \text{Color3.RGB}$	0FFh
3	Color3.RGB	0FFh

Alpha[0] = 1 Decoding

When Alpha[0] = 1, Color0 and Color2 are encoded as 15-bit R5G5B5 values. Color1 and Color3 are encoded as RGB565 colors, with the Green LSB obtained as shown in the following table:

FXT CC_MIXED (Alpha[0]=0) Decoded Colors

Encoded Color Bit	Definition
Color 3 Green [0]	Encoded Bit [126]
Color 1 Green [0]	Encoded Bit [125]

All four colors are then expanded to 24-bit R8G8B8 colors by bit replication, as show in the following diagram.

FXT CC_MIXED Decoded Colors (Alpha[0] = 1)

Expanded Color Bit	Expanded Channel Bit	Encoded Block Source Bit
Color 3 [23:17]	Color 3 Red [7:3]	[123:119]
Color 3 [18:16]	Color 3 Red [2:0]	[123:121]
Color 3 [15:11]	Color 3 Green [7:3]	[118:114]
Color 3 [10]	Color 3 Green [2]	[126]
Color 3 [09:08]	Color 3 Green [1:0]	[118:117]
Color 3 [07:03]	Color 3 Blue [7:3]	[113:109]
Color 3 [02:00]	Color 3 Blue [2:0]	[113:111]
Color 2 [23:19]	Color 2 Red [7:3]	[108:104]
Color 2 [18:16]	Color 2 Red [2:0]	[108:106]
Color 2 [15:11]	Color 2 Green [7:3]	[103:99]
Color 2 [10:08]	Color 2 Green [2:0]	[103:101]
Color 2 [07:03]	Color 2 Blue [7:3]	[98:94]
Color 2 [02:00]	Color 2 Blue [2:0]	[98:96]



Expanded Color Bit	Expanded Channel Bit	Encoded Block Source Bit
Color 1 [23:17]	Color 1 Red [7:3]	[93:89]
Color 1 [18:16]	Color 1 Red [2:0]	[93:91]
Color 1 [15:11]	Color 1 Green [7:3]	[88:84]
Color 1 [10]	Color 1 Green [2]	[125]
Color 1 [09:08]	Color 1 Green [1:0]	[88:87]
Color 1 [07:03]	Color 1 Blue [7:3]	[83:79]
Color 1 [02:00]	Color 1 Blue [2:0]	[83:81]
Color 0 [23:19]	Color 0 Red [7:3]	[78:74]
Color 0 [18:16]	Color 0 Red [2:0]	[78:76]
Color 0 [15:11]	Color 0 Green [7:3]	[73:69]
Color 0 [10:08]	Color 0 Green [2:0]	[73:71]
Color 0 [07:03]	Color 0 Blue [7:3]	[68:64]
Color 0 [02:00]	Color 0 Blue [2:0]	[68:66]

The two sets of 24-bit colors (Color 0,1 and Color 2,3) are then used to create two tables of four colors. The Color0,1 table is used as a lookup table for texel 0-15 indices, and the Color2,3 table used for texels 16-31 indices. The color at index 1 is the linear interpolation of the base colors, while the color at index 3 is defined as Black (0,0,0) with Alpha = 0, as shown in the following figures:

FXT CC_MIXED Interpolated Color Table (Alpha[0]=1, Texels 0-15)

Texel 0-15 Select	Color RGB	Alpha
0	Color0.RGB	0FFh
1	$(\text{Color0.RGB} + \text{Color1.RGB}) / 2$	0FFh
2	Color1.RGB	0FFh
3	Black (0,0,0)	0

FXT CC_MIXED Interpolated Color Table (Alpha[0]=1, Texels 16-31)

Texel 16-31 Select	Color RGB	Alpha
0	Color2.RGB	0FFh
1	$(\text{Color2.RGB} + \text{Color3.RGB}) / 2$	0FFh
2	Color3.RGB	0FFh
3	Black (0,0,0)	0

These tables are then used as a 4-entry Lookup Table, where each 2-bit Texel n Select field of the encoded CC_MIXED block is used to index into the appropriate 32-bit A8R8G8B8 color from the table, completing the decode of the CC_CMIXED block.



FXT1 CC_ALPHA Format

In the CC_ALPHA encoding format, three A5R5G5B5 colors are provided in the encoded block. A control bit (LERP) is used to define the lookup table (or tables) used to dereference the 2-bit Texel Selects.

CC_ALPHA Block Encoding

The following table describes the encoding of the 128-bit (DQWord) CC_ALPHA block format:

FXT CC_ALPHA Block Encoding

Bit	Description
127:125	Mode = '011'b (CC_ALPHA)
124	LERP
123:119	Color 2 Alpha
118:114	Color 1 Alpha
113:109	Color 0 Alpha
108:104	Color 2 Red
103:99	Color 2 Green
98:94	Color 2 Blue
93:89	Color 1 Red
88:84	Color 1 Green
83:79	Color 1 Blue
78:74	Color 0 Red
73:69	Color 0 Green
68:64	Color 0 Blue
63:62	Texel 31 Select
...	...
33:32	Texel 16 Select
31:30	Texel 15 Select
...	...
1:0	Texel 0 Select

CC_ALPHA Block Decoding

Each of the three colors (Color 0-2) are converted from A5R5G5B5 to A8R8G8B8 by replicating the 3 MSBs into the 3 LSBs, as shown in the following tables:

**FXT CC_ALPHA Decoded Colors**

Expanded Color Bit	Expanded Channel Bit	Encoded Block Source Bit
Color 2 [31:27]	Color 2 Alpha [7:3]	[123:119]
Color 2 [26:24]	Color 2 Alpha [2:0]	[123:121]
Color 2 [23:17]	Color 2 Red [7:3]	[108:104]
Color 2 [18:16]	Color 2 Red [2:0]	[108:106]
Color 2 [15:11]	Color 2 Green [7:3]	[103:99]
Color 2 [10:08]	Color 2 Green [2:0]	[103:101]
Color 2 [07:03]	Color 2 Blue [7:3]	[98:94]
Color 2 [02:00]	Color 2 Blue [2:0]	[98:96]
Color 1 [31:27]	Color 1 Alpha [7:3]	[118:114]
Color 1 [26:24]	Color 1 Alpha [2:0]	[118:116]
Color 1 [23:17]	Color 1 Red [7:3]	[93:89]
Color 1 [18:16]	Color 1 Red [2:0]	[93:91]
Color 1 [15:11]	Color 1 Green [7:3]	[88:84]
Color 1 [10:08]	Color 1 Green [2:0]	[88:86]
Color 1 [07:03]	Color 1 Blue [7:3]	[83:79]
Color 1 [02:00]	Color 1 Blue [2:0]	[83:81]
Color 0 [31:27]	Color 0 Alpha [7:3]	[113:109]
Color 0 [26:24]	Color 0 Alpha [2:0]	[113:111]
Color 0 [23:17]	Color 0 Red [7:3]	[78:74]
Color 0 [18:16]	Color 0 Red [2:0]	[78:76]
Color 0 [15:11]	Color 0 Green [7:3]	[73:69]
Color 0 [10:08]	Color 0 Green [2:0]	[73:71]
Color 0 [07:03]	Color 0 Blue [7:3]	[68:64]
Color 0 [02:00]	Color 0 Blue [2:0]	[68:66]

LERP = 0 Decoding

When LERP = 0, a single 4-entry lookup table is formed using the three expanded colors, with the 4th entry defined as transparent black (ARGB=0,0,0,0). Each 2-bit Texel n Select field of the encoded CC_ALPHA block is used to index into a 32-bit A8R8G8B8 color from the table completing the decode of the CC_ALPHA block.



FXT CC_ALPHA Interpolated Color Table (LERP=0)

Texel Select	Color	Alpha
0	Color0.RGB	Color0.Alpha
1	Color1.RGB	Color1.Alpha
2	Color2.RGB	Color2.Alpha
3	Black (RGB=0,0,0)	0

LERP = 1 Decoding

When LERP = 1, the three expanded colors are used to create two tables of four interpolated colors. The Color0,1 table is used as a lookup table for texel 0-15 indices, and the Color1,2 table used for texels 16-31 indices, as shown in the following figures:

FXT CC_ALPHA Interpolated Color Table (LERP=1, Texels 0-15)

Texel 0-15 Select	Color ARGB
0	Color0.ARGB
1	$(2*Color0.ARGB + Color1.ARGB + 1) / 3$
2	$(Color0.ARGB + 2*Color1.ARGB + 1) / 3$
3	Color1.ARGB

FXT CC_ALPHA Interpolated Color Table (LERP=1, Texels 16-31)

Texel 16-31 Select	Color ARGB
0	Color2.ARGB
1	$(2*Color2.ARGB + Color1.ARGB + 1) / 3$
2	$(Color2.ARGB + 2*Color1.ARGB + 1) / 3$
3	Color1.ARGB

DXT/BC1-3 Texture Formats

Note that non-power-of-2 dimensioned maps may require the surface to be padded out to the next multiple of four texels – here the pad texels are not referenced by the device.

An 8-byte (QWord) block encoding can be used if the source texture contains no transparency (is opaque) or if the transparency can be specified by a one-bit alpha. A 16-byte (DQWord) block encoding can be used to support source textures that require more than one-bit alpha: here the 1st QWord is used to encode the texel alpha values, and the 2nd QWord is used to encode the texel color values.

These three types of format are discussed in the following sections:

- Opaque and One-bit Alpha Textures (DXT1)
- Opaque Textures (DXT1_RGB)
- Textures with Alpha Channels (DXT2-5)



DXT2 and DXT3 are equivalent compression formats from the perspective of the hardware. The only difference between the two is the use of pre-multiplied alpha encoding, which does not affect hardware.

Likewise, DXT4 and DXT5 are the same compression formats with the only difference being the use of pre-multiplied alpha encoding.

Note that the surface formats DXT1-5 are referred to in the DirectX Specification as BC1-3. The mapping between formats is shown below:

- DXT1 ⇒ BC1
- DXT2/DXT3 ⇒ BC2
- DXT4/DXT5 ⇒ BC3

Programming Note	
Context:	DXT Texture Formats
<ul style="list-style-type: none"> • Any single texture must specify that its data is stored as 64 or 128 bits per group of 16 texels. If 64-bit blocks—that is, format DXT1—are used for the texture, it is possible to mix the opaque and one-bit alpha formats on a per-block basis within the same texture. In other words, the comparison of the unsigned integer magnitude of color_0 and color_1 is performed uniquely for each block of 16 texels. • When 128-bit blocks are used, then the alpha channel must be specified in either explicit (format DXT2 or DXT3) or interpolated mode (format DXT4 or DXT5) for the entire texture. Note that as with color, once interpolated mode is selected then either 8 interpolated alphas or 6 interpolated alphas mode can be used on a block-by-block basis. Again the magnitude comparison of alpha_0 and alpha_1 is done uniquely on a block-by-block basis. 	

Opaque and One-bit Alpha Textures (DXT1/BC1)

Texture format DXT1 is for textures that are opaque or have a single transparent color. For each opaque or one-bit alpha block, two 16-bit R5G6B5 values and a 4x4 bitmap with 2-bits-per-pixel are stored. This totals 64 bits (1 QWord) for 16 texels, or 4-bits-per-texel.

In the block bitmap, there are two bits per texel to select between the four colors, two of which are stored in the encoded data. The other two colors are derived from these stored colors by linear interpolation.

The one-bit alpha format is distinguished from the opaque format by comparing the two 16-bit color values stored in the block. They are treated as unsigned integers. If the first color is greater than the second, it implies that only opaque texels are defined. This means four colors will be used to represent the texels. In four-color encoding, there are two derived colors and all four colors are equally distributed in RGB color space. This format is analogous to R5G6B5 format. Otherwise, for one-bit alpha transparency, three colors are used and the fourth is reserved to represent transparent texels. Note that the color blocks in DXT2-5 formats strictly use four colors, as the alpha values are obtained from the alpha block .



In three-color encoding, there is one derived color and the fourth two-bit code is reserved to indicate a transparent texel (alpha information). This format is analogous to A1R5G5B5, where the final bit is used for encoding the alpha mask.

The following piece of pseudo-code illustrates the algorithm for deciding whether three- or four-color encoding is selected:

```

if (color_0 > color_1)
{
    // Four-color block: derive the other two colors.
    // 00 = color_0, 01 = color_1, 10 = color_2, 11 = color_3
    // These two bit codes correspond to the 2-bit fields
    // stored in the 64-bit block.  color_2 = (2 * color_0 + color_1) / 3;
    color_3 = (color_0 + 2 * color_1) / 3;
}
else
{
    // Three-color block: derive the other color.  // 00 = color_0, 01 = color_1, 10 = color_2,
    // 11 = transparent.  // These two bit codes correspond to the 2-bit fields
    // stored in the 64-bit block.  color_2 = (color_0 + color_1) / 2;
    color_3 = transparent;
}

```

The following tables show the memory layout for the 8-byte block. It is assumed that the first index corresponds to the y-coordinate and the second corresponds to the x-coordinate. For example, Texel[1][2] refers to the texture map pixel at (x,y) = (2,1).

Here is the memory layout for the 8-byte (64-bit) block:

Word Address	16-bit Word
0	Color_0
1	Color_1
2	Bitmap Word_0
3	Bitmap Word_1

Color_0 and Color_1 (colors at the two extremes) are laid out as follows:

Bits	Color
15:11	Red color component
10:5	Green color component
4:0	Blue color component

Bits	Texel
1:0 (LSB)	Texel[0][0]
3:2	Texel[0][1]
5:4	Texel[0][2]
7:6	Texel[0][3]
9:8	Texel[1][0]
11:10	Texel[1][1]



Bits	Texel
13:12	Texel[1][2]
15:14	Texel[1][3]

Bitmap Word_1 is laid out as follows:

Bits	Texel
1:0 (LSB)	Texel[2][0]
3:2	Texel[2][1]
5:4	Texel[2][2]
7:6	Texel[2][3]
9:8	Texel[3][0]
11:10	Texel[3][1]
13:12	Texel[3][2]
15:14 (MSB)	Texel[3][3]

Example of Opaque Color Encoding

As an example of opaque encoding, we will assume that the colors red and black are at the extremes. We will call red color_0 and black color_1. There will be four interpolated colors that form the uniformly distributed gradient between them. To determine the values for the 4x4 bitmap, the following calculations are used:

```

00 ? color_0
01 ? color_1
10 ? 2/3 color_0 + 1/3 color_1
11 ? 1/3 color_0 + 2/3 color_1

```

Example of One-bit Alpha Encoding

This format is selected when the unsigned 16-bit integer, color_0, is less than the unsigned 16-bit integer, color_1. An example of where this format could be used is leaves on a tree to be shown against a blue sky. Some texels could be marked as transparent while three shades of green are still available for the leaves. Two of these colors fix the extremes, and the third color is an interpolated color.

The bitmap encoding for the colors and the transparency is determined using the following calculations:

```

00 ? color_0
01 ? color_1
10 ? 1/2 color_0 + 1/2 color_1
11 ? Transparent

```

Opaque Textures (DXT1_RGB)

Texture format DXT1_RGB is identical to DXT1, with the exception that the One-bit Alpha encoding is removed. Color 0 and Color 1 are not compared, and the resulting texel color is derived strictly from the Opaque Color Encoding. The alpha channel defaults to 1.0.



Programming Note	
Context:	Opaque Textures (DXT1_RGB)
The behavior of this format is not compliant with the OGL spec.	

Compressed Textures with Alpha Channels (DXT2-5 / BC2-3)

There are two ways to encode texture maps that exhibit more complex transparency. In each case, a block that describes the transparency precedes the 64-bit block already described for DXT1. The transparency is either represented as a 4x4 bitmap with four bits per pixel (explicit encoding), or with fewer bits and linear interpolation analogous to what is used for color encoding.

The transparency block and the color block are laid out as follows:

Word Address	64-bit Block
3:0	Transparency block
7:4	Previously described 64-bit block

Explicit Texture Encoding

For explicit texture encoding (DXT2 and DXT3 formats), the alpha components of the texels that describe transparency are encoded in a 4x4 bitmap with 4 bits per texel. These 4 bits can be achieved through a variety of means such as dithering or by simply using the 4 most significant bits of the alpha data. However they are produced, they are used just as they are, without any form of interpolation.

Note: DirectDraw's compression method uses the 4 most significant bits.

The following tables illustrate how the alpha information is laid out in memory, for each 16-bit word.

This is the layout for Word 0:

Bits	Alpha
3:0 (LSB)	[0][0]
7:4	[0][1]
11:8	[0][2]
15:12 (MSB)	[0][3]

This is the layout for Word 1:

Bits	Alpha
3:0 (LSB)	[1][0]
7:4	[1][1]
11:8	[1][2]
15:12 (MSB)	[1][3]



This is the layout for Word 2:

Bits	Alpha
3:0 (LSB)	[2][0]
7:4	[2][1]
11:8	[2][2]
15:12 (MSB)	[2][3]

This is the layout for Word 3:

Bits	Alpha
3:0 (LSB)	[3][0]
7:4	[3][1]
11:8	[3][2]
15:12 (MSB)	[3][3]

Three-Bit Linear Alpha Interpolation

The encoding of transparency for the DXT4 and DXT5 formats is based on a concept similar to the linear encoding used for color. Two 8-bit alpha values and a 4x4 bitmap with three bits per pixel are stored in the first eight bytes of the block. The representative alpha values are used to interpolate intermediate alpha values. Additional information is available in the way the two alpha values are stored. If alpha_0 is greater than alpha_1, then six intermediate alpha values are created by the interpolation. Otherwise, four intermediate alpha values are interpolated between the specified alpha extremes. The two additional implicit alpha values are 0 (fully transparent) and 255 (fully opaque).

The following pseudo-code illustrates this algorithm:

```
// 8-alpha or 6-alpha block?
if (alpha_0 > alpha_1) {
    // 8-alpha block: derive the other 6 alphas.
    // 000 = alpha_0, 001 = alpha_1, others are interpolated
    alpha_2 = (6 * alpha_0 + alpha_1) / 7; // Bit code 010
    alpha_3 = (5 * alpha_0 + 2 * alpha_1) / 7; // Bit code 011
    alpha_4 = (4 * alpha_0 + 3 * alpha_1) / 7; // Bit code 100
    alpha_5 = (3 * alpha_0 + 4 * alpha_1) / 7; // Bit code 101
    alpha_6 = (2 * alpha_0 + 5 * alpha_1) / 7; // Bit code 110
    alpha_7 = (alpha_0 + 6 * alpha_1) / 7; // Bit code 111
}
else {
    // 6-alpha block: derive the other alphas.
    // 000 = alpha_0, 001 = alpha_1, others are interpolated
    alpha_2 = (4 * alpha_0 + alpha_1) / 5; // Bit code 010
    alpha_3 = (3 * alpha_0 + 2 * alpha_1) / 5; // Bit code 011
    alpha_4 = (2 * alpha_0 + 3 * alpha_1) / 5; // Bit code 100
    alpha_5 = (alpha_0 + 4 * alpha_1) / 5; // Bit code 101
    alpha_6 = 0; // Bit code 110
    alpha_7 = 255; // Bit code 111
}
```

The memory layout of the alpha block is as follows:



Byte	Alpha
0	Alpha_0
1	Alpha_1
2	[0][2] (2 LSBs), [0][1], [0][0]
3	[1][1] (1 LSB), [1][0], [0][3], [0][2] (1 MSB)
4	[1][3], [1][2], [1][1] (2 MSBs)
5	[2][2] (2 LSBs), [2][1], [2][0]
6	[3][1] (1 LSB), [3][0], [2][3], [2][2] (1 MSB)
7	[3][3], [3][2], [3][1] (2 MSBs)

BC4

These formats (BC4_UNORM and BC4_SNORM) compresses single-component UNORM or SNORM data. An 8-byte compression block represents a 4x4 block of texels. The texels are labeled as texel[row][column] where both row and column range from 0 to 3. Texel[0][0] is the upper left texel.

The 8-byte compression block is laid out as follows:

Bit	Description
7:0	red_0
15:8	red_1
18:16	texel[0][0] bit code
21:19	texel[0][1] bit code
24:22	texel[0][2] bit code
27:25	texel[0][3] bit code
30:28	texel[1][0] bit code
33:31	texel[1][1] bit code
36:34	texel[1][2] bit code
39:37	texel[1][3] bit code
42:40	texel[2][0] bit code
45:43	texel[2][1] bit code
48:46	texel[2][2] bit code
51:49	texel[2][3] bit code
54:52	texel[3][0] bit code
57:55	texel[3][1] bit code
60:58	texel[3][2] bit code
63:61	texel[3][3] bit code

There are two interpolation modes, chosen based on which reference color is larger. The first mode has the two reference colors plus six equal-spaced interpolated colors between the reference colors, chosen based on the three-bit code for that texel. The second mode has the two reference colors plus four



interpolated colors, chosen by six of the three-bit codes. The remaining two codes select min and max values for the colors. The values of red_0 through red_7 are computed as follows:

```

red_0 = red_0; // bit code 000
red_1 = red_1; // bit code 001
if (red_0 > red_1) {
    red_2 = (6 * red_0 + 1 * red_1) / 7; // bit code 010
    red_3 = (5 * red_0 + 2 * red_1) / 7; // bit code 011
    red_4 = (4 * red_0 + 3 * red_1) / 7; // bit code 100
    red_5 = (3 * red_0 + 4 * red_1) / 7; // bit code 101
    red_6 = (2 * red_0 + 5 * red_1) / 7; // bit code 110
    red_7 = (1 * red_0 + 6 * red_1) / 7; // bit code 111
}
else {
    red_2 = (4 * red_0 + 1 * red_1) / 5; // bit code 010
    red_3 = (3 * red_0 + 2 * red_1) / 5; // bit code 011
    red_4 = (2 * red_0 + 3 * red_1) / 5; // bit code 100
    red_5 = (1 * red_0 + 4 * red_1) / 5; // bit code 101
    red_6 = UNORM ? 0.0 : -1.0; // bit code 110 (0 for UNORM, -1 for SNORM)
    red_7 = 1.0; // bit code 111
}

```

BC5

These formats (BC5_UNORM and BC5_SNORM) compresses dual-component UNORM or SNORM data. A 16-byte compression block represents a 4x4 block of texels. The texels are labeled as texel[row][column] where both row and column range from 0 to 3. Texel[0][0] is the upper left texel.

The 16-byte compression block is laid out as follows:

Bit	Description
7:0	red_0
15:8	red_1
18:16	texel[0][0] red bit code
21:19	texel[0][1] red bit code
24:22	texel[0][2] red bit code
27:25	texel[0][3] red bit code
30:28	texel[1][0] red bit code
33:31	texel[1][1] red bit code
36:34	texel[1][2] red bit code
39:37	texel[1][3] red bit code
42:40	texel[2][0] red bit code
45:43	texel[2][1] red bit code
48:46	texel[2][2] red bit code
51:49	texel[2][3] red bit code
54:52	texel[3][0] red bit code
57:55	texel[3][1] red bit code



Bit	Description
60:58	texel[3][2] red bit code
63:61	texel[3][3] red bit code
71:64	green_0
79:72	green_1
82:80	texel[0][0] green bit code
85:83	texel[0][1] green bit code
88:86	texel[0][2] green bit code
91:89	texel[0][3] green bit code
94:92	texel[1][0] green bit code
97:95	texel[1][1] green bit code
100:98	texel[1][2] green bit code
103:101	texel[1][3] green bit code
106:104	texel[2][0] green bit code
109:107	texel[2][1] green bit code
112:110	texel[2][2] green bit code
115:113	texel[2][3] green bit code
118:116	texel[3][0] green bit code
121:119	texel[3][1] green bit code
124:122	texel[3][2] green bit code
127:125	texel[3][3] green bit code

There are two interpolation modes, chosen based on which reference color is larger. The first mode has the two reference colors plus six equal-spaced interpolated colors between the reference colors, chosen based on the three-bit code for that texel. The second mode has the two reference colors plus four interpolated colors, chosen by six of the three-bit codes. The remaining two codes select min and max values for the colors. The values of red_0 through red_7 are computed as follows:

```

red_0 = red_0; // bit code 000
red_1 = red_1; // bit code 001
if (red_0 > red_1) {
    red_2 = (6 * red_0 + 1 * red_1) / 7; // bit code 010
    red_3 = (5 * red_0 + 2 * red_1) / 7; // bit code 011
    red_4 = (4 * red_0 + 3 * red_1) / 7; // bit code 100
    red_5 = (3 * red_0 + 4 * red_1) / 7; // bit code 101
    red_6 = (2 * red_0 + 5 * red_1) / 7; // bit code 110
    red_7 = (1 * red_0 + 6 * red_1) / 7; // bit code 111
}
else {
    red_2 = (4 * red_0 + 1 * red_1) / 5; // bit code 010
    red_3 = (3 * red_0 + 2 * red_1) / 5; // bit code 011
    red_4 = (2 * red_0 + 3 * red_1) / 5; // bit code 100
    red_5 = (1 * red_0 + 4 * red_1) / 5; // bit code 101
    red_6 = UNORM ? 0.0 : -1.0; // bit code 110 (0 for UNORM, -1 for SNORM)
    red_7 = 1.0; // bit code 111
}

```



The same calculations are done for green, using the corresponding reference colors and bit codes.

BC6H

These formats (BC6H_UF16 and BC6H_SF16) compresses 3-channel images with high dynamic range (> 8 bits per channel). BC6H supports floating point denorms but there is no support for INF and NaN, other than with BC6H_SF16 –INF is supported. The alpha channel is not included, thus alpha is returned at its default value.

The BC6H block is 16 bytes and represents a 4x4 block of texels. The texels are labeled as texel[row][column] where both row and column range from 0 to 3. Texel[0][0] is the upper left texel. BC6H has 14 different modes, the mode that the block is in is contained in the least significant bits (either 2 or 5 bits).

The basic scheme consists of interpolating colors along either one or two lines, with per-texel indices indicating which color along the line is chosen for each texel. If a two-line mode is selected, one of 32 partition sets is indicated which selects which of the two lines each texel is assigned to.

Field Definition

There are 14 possible modes for a BC6H block, the format of each is indicated in the 14 tables below. The mode is selected by the unique mode bits specified in each table. The first 10 modes use two lines ("TWO"), and the last 4 use one line ("ONE"). The difference between the various two-line and one-line modes is with the precision of the first endpoint and the number of bits used to store delta values for the remaining endpoints. Two modes (9 and 10) specify each endpoint as an original value rather than using the deltas (these are indicated as having no delta values).

The endpoints values and deltas are indicated in the tables using a two-letter name. The first letter is "r", "g", or "b" indicating the color channel. The second letter is "w", "x", "y", or "z" indicating which of the four endpoints. The first line has endpoints "w" and "x", with "w" being the endpoint that is fully specified (i.e. not as a delta). The second line has endpoints "y" and "z". Modes using ONE mode do not have endpoints "y" and "z" as they have only one line.

In addition to the mode and endpoint data, TWO blocks contain a 5-bit "partition" which selects one of the partition sets, and a 46-bit set of indices. ONE blocks contain a 63-bit set of indices. These are described in more detail below.

Mode 0: (TWO) Red, Green, Blue: 10-bit endpoint, 5-bit deltas

Bit	Description
1:0	mode = 00
2	gy[4]
3	by[4]
4	bz[4]
14:5	rw[9:0]
24:15	gw[9:0]



Bit	Description
34:25	bw[9:0]
39:35	rx[4:0]
40	gz[4]
44:41	gy[3:0]
49:45	gx[4:0]
50	bz[0]
54:51	gz[3:0]
59:55	bx[4:0]
60	bz[1]
64:61	by[3:0]
69:65	ry[4:0]
70	bz[2]
75:71	rz[4:0]
76	bz[3]
81:77	partition
127:82	indices

Mode 1: (TWO) Red, Green, Blue: 7-bit endpoint, 6-bit deltas

Bit	Description
1:0	mode = 01
2	gy[5]
3	gz[4]
4	gz[5]
11:5	rw[6:0]
12	bz[0]
13	bz[1]
14	by[4]
21:15	gw[6:0]
22	by[5]
23	bz[2]
24	gy[4]
31:25	bw[6:0]
32	bz[3]
33	bz[5]
34	bz[4]
40:35	rx[5:0]



Bit	Description
44:41	gy[3:0]
50:45	gx[5:0]
54:51	gz[3:0]
60:55	bx[5:0]
64:61	by[3:0]
70:65	ry[5:0]
76:71	rz[5:0]
81:77	partition
127:82	indices

Mode 2: (TWO) Red: 11-bit endpoint, 5-bit deltas

Green, Blue: 11-bit endpoint, 4-bit deltas

Bit	Description
4:0	mode = 00010
14:5	rw[9:0]
24:15	gw[9:0]
34:25	bw[9:0]
39:35	rx[4:0]
40	rw[10]
44:41	gy[3:0]
48:45	gx[3:0]
49	gw[10]
50	bz[0]
54:51	gz[3:0]
58:55	bx[3:0]
59	bw[10]
60	bz[1]
64:61	by[3:0]
69:65	ry[4:0]
70	bz[2]
75:71	rz[4:0]
76	bz[3]
81:77	partition
127:82	indices

Mode 3: (TWO) Red, Blue: 11-bit endpoint, 4-bit deltas

Green: 11-bit endpoint, 5-bit deltas



Bit	Description
4:0	mode = 00110
14:5	rw[9:0]
24:15	gw[9:0]
34:25	bw[9:0]
38:35	rx[3:0]
39	rw[10]
40	gz[4]
44:41	gy[3:0]
49:45	gx[4:0]
50	gw[10]
54:51	gz[3:0]
58:55	bx[3:0]
59	bw[10]
60	bz[1]
64:61	by[3:0]
68:65	ry[3:0]
69	bz[0]
70	bz[2]
74:71	rz[3:0]
75	gy[4]
76	bz[3]
81:77	partition
127:82	indices

Mode 4: (TWO) Red, Green: 11-bit endpoint, 4-bit deltas

Blue: 11-bit endpoint, 5-bit deltas

Bit	Description
4:0	mode = 01010
14:5	rw[9:0]
24:15	gw[9:0]
34:25	bw[9:0]
38:35	rx[3:0]
39	rw[10]
40	by[4]
44:41	gy[3:0]
48:45	gx[3:0]



Bit	Description
49	gw[10]
50	bz[0]
54:51	gz[3:0]
59:55	bx[4:0]
60	bw[10]
64:61	by[3:0]
68:65	ry[3:0]
69	bz[1]
70	bz[2]
74:71	rz[3:0]
75	bz[4]
76	bz[3]
81:77	partition
127:82	indices

Mode 5: (TWO) Red, Green, Blue: 9-bit endpoint, 5-bit deltas

Bit	Description
4:0	mode = 01110
13:5	rw[8:0]
14	by[4]
23:15	gw[8:0]
24	gy[4]
33:25	bw[8:0]
34	bz[4]
39:35	rx[4:0]
40	gz[4]
44:41	gy[3:0]
49:45	gx[4:0]
50	bz[0]
54:51	gz[3:0]
59:55	bx[4:0]
60	bz[1]
64:61	by[3:0]
69:65	ry[4:0]
70	bz[2]
75:71	rz[4:0]



Bit	Description
76	bz[3]
81:77	partition
127:82	indices

Mode 6: (TWO) Red: 8-bit endpoint, 6-bit deltas

Green, Blue: 8-bit endpoint, 5-bit deltas

Bit	Description
4:0	mode = 10010
12:5	rw[7:0]
13	gz[4]
14	by[4]
22:15	gw[7:0]
23	bz[2]
24	gy[4]
32:25	bw[7:0]
33	bz[3]
34	bz[4]
40:35	rx[5:0]
44:41	gy[3:0]
49:45	gx[4:0]
50	bz[0]
54:51	gz[3:0]
59:55	bx[4:0]
60	gz[1]
64:61	by[3:0]
70:65	ry[5:0]
76:71	rz[5:0]
81:77	partition
127:82	indices

Mode 7: (TWO) Red, Blue: 8-bit endpoint, 5-bit deltas

Green: 8-bit endpoint, 6-bit deltas

Bit	Description
4:0	mode = 10110
12:5	rw[7:0]
13	bz[0]



Bit	Description
14	by[4]
22:15	gw[7:0]
23	gy[5]
24	gy[4]
32:25	bw[7:0]
33	gz[5]
34	bz[4]
39:35	rx[4:0]
40	gz[4]
44:41	gy[3:0]
50:45	gx[5:0]
54:51	gz[3:0]
59:55	bx[4:0]
60	bz[1]
64:61	by[3:0]
69:65	ry[4:0]
70	bz[2]
75:71	rz[4:0]
76	bz[3]
81:77	partition
127:82	indices

Mode 8: (TWO) Red, Green: 8-bit endpoint, 5-bit deltas

Blue: 8-bit endpoint, 6-bit deltas

Bit	Description
4:0	mode = 11010
12:5	rw[7:0]
13	bz[1]
14	by[4]
22:15	gw[7:0]
23	by[5]
24	gy[4]
32:25	bw[7:0]
33	bz[5]
34	bz[4]
39:35	rx[4:0]



Bit	Description
40	gz[4]
44:41	gy[3:0]
49:45	gx[4:0]
50	bz[0]
54:51	gz[3:0]
60:55	bx[5:0]
64:61	by[3:0]
69:65	ry[4:0]
70	bz[2]
75:71	rz[4:0]
76	bz[3]
81:77	partition
127:82	indices

Mode 9: (TWO) Red, Green, Blue: 6-bit endpoints for all four, no deltas

Bit	Description
4:0	mode = 11110
10:5	rw[5:0]
11	gz[4]
12	bz[0]
13	bz[1]
14	by[4]
20:15	gw[5:0]
21	gy[5]
22	by[5]
23	bz[2]
24	gy[4]
30:25	bw[5:0]
31	gz[5]
32	bz[3]
33	bz[5]
34	bz[4]
40:35	rx[5:0]
44:41	gy[3:0]
50:45	gx[5:0]
54:51	gz[3:0]



Bit	Description
60:55	bx[5:0]
64:61	by[3:0]
70:65	ry[5:0]
76:71	rz[5:0]
81:77	partition
127:82	indices

Mode 10: (ONE) Red, Green, Blue: 10-bit endpoints for both, no deltas

Bit	Description
4:0	mode = 00011
14:5	rw[9:0]
24:15	gw[9:0]
34:25	bw[9:0]
44:35	rx[9:0]
54:45	gx[9:0]
64:55	bx[9:0]
127:65	indices

Mode 11: (ONE) Red, Green, Blue: 11-bit endpoints, 9-bit deltas

Bit	Description
4:0	mode = 00111
14:5	rw[9:0]
24:15	gw[9:0]
34:25	bw[9:0]
43:35	rx[8:0]
44	rw[10]
53:45	gx[8:0]
54	gw[10]
63:55	bx[8:0]
64	bw[10]
127:65	indices

Mode 12: (ONE) Red, Green, Blue: 12-bit endpoints, 8-bit deltas

Bit	Description
4:0	mode = 01011
14:5	rw[9:0]
24:15	gw[9:0]



Bit	Description
34:25	bw[9:0]
42:35	rx[7:0]
43	rw[11]
44	rw[10]
52:45	gx[7:0]
53	gw[11]
54	gw[10]
62:55	bx[7:0]
63	bw[11]
64	bw[10]
127:65	indices

Mode 13: (ONE) Red, Green, Blue: 16-bit endpoints, 4-bit deltas

Bit	Description
4:0	mode = 01111
14:5	rw[9:0]
24:15	gw[9:0]
34:25	bw[9:0]
38:35	rx[3:0]
39	rw[15]
40	rw[14]
41	rw[13]
42	rw[12]
43	rw[11]
44	rw[10]
48:45	gx[3:0]
49	gw[15]
50	gw[14]
51	gw[13]
52	gw[12]
53	gw[11]
54	gw[10]
58:55	bx[3:0]
59	bw[15]
60	bw[14]
61	bw[13]



Bit	Description
62	bw[12]
63	bw[11]
64	bw[10]
127:65	indices

Undefined mode values (10011, 10111, 11011, and 11111) return zero in the RGB channels.

The "indices" fields are defined as follows:

TWO mode *indices* field with fix-up index [1] at texel[3][3]

Bit	Description
83:82	texel[0][0] index
86:84	texel[0][1] index
89:87	texel[0][2] index
92:90	texel[0][3] index
95:93	texel[1][0] index
98:96	texel[1][1] index
101:99	texel[1][2] index
104:102	texel[1][3] index
107:105	texel[2][0] index
110:108	texel[2][1] index
113:111	texel[2][2] index
116:114	texel[2][3] index
119:117	texel[3][0] index
122:120	texel[3][1] index
125:123	texel[3][2] index
127:126	texel[3][3] index

TWO mode *indices* field with fix-up index [1] at texel[0][2]

Bit	Description
83:82	texel[0][0] index
86:84	texel[0][1] index
88:87	texel[0][2] index
91:89	texel[0][3] index
94:92	texel[1][0] index
97:95	texel[1][1] index
100:98	texel[1][2] index
103:101	texel[1][3] index



Bit	Description
106:104	texel[2][0] index
109:107	texel[2][1] index
112:110	texel[2][2] index
115:113	texel[2][3] index
118:116	texel[3][0] index
121:119	texel[3][1] index
124:122	texel[3][2] index
127:125	texel[3][3] index

TWO mode *indices* field with fix-up index [1] at texel[2][0]

Bit	Description
83:82	texel[0][0] index
86:84	texel[0][1] index
89:87	texel[0][2] index
92:90	texel[0][3] index
95:93	texel[1][0] index
98:96	texel[1][1] index
101:99	texel[1][2] index
104:102	texel[1][3] index
106:105	texel[2][0] index
109:107	texel[2][1] index
112:110	texel[2][2] index
115:113	texel[2][3] index
118:116	texel[3][0] index
121:119	texel[3][1] index
124:122	texel[3][2] index
127:125	texel[3][3] index

ONE mode *indices* field

Bit	Description
67:65	texel[0][0] index
71:68	texel[0][1] index
75:72	texel[0][2] index
79:76	texel[0][3] index
83:80	texel[1][0] index
87:84	texel[1][1] index
91:88	texel[1][2] index



Bit	Description
95:92	texel[1][3] index
99:96	texel[2][0] index
103:100	texel[2][1] index
107:104	texel[2][2] index
111:108	texel[2][3] index
115:112	texel[3][0] index
119:116	texel[3][1] index
123:120	texel[3][2] index
127:124	texel[3][3] index

Endpoint Computation

The endpoints can be defined in many different ways, as shown above. This section describes how the endpoints are computed from the bits in the compression block. The method used depends on whether the BC6H format is signed (BC6H_SF16) or unsigned (BC6H_UF16).

First, each channel (RGB) of each endpoint is extended to 16 bits. Each is handled identically and independently, however in some modes different channels have different incoming precision which must be accounted for. The following rules are employed:

- If the format is BC6H_SF16 or the endpoint is a delta value, the value is sign-extended to 16 bits
- For all other cases, the value is zero-extended to 16 bits

If there are no endpoints that are delta values, endpoint computation is complete. For endpoints that are delta values, the next step involves computing the absolute endpoint. The “w” endpoint is always absolute and acts as a base value for the other three endpoints. Each channel is handled identically and independently.

$$\begin{aligned}x &= w + x \\y &= w + y \\z &= w + z\end{aligned}$$

The above is performed using 16-bit integer arithmetic. Overflows beyond 16 bits are ignored (any resulting high bits are dropped).

Palette Color Computation

The next step involves computing the color palette values that provide the available values for each texel's color. The color palette for each line consists of the two endpoint colors plus 6 (TWO mode) or 14 (ONE mode) interpolated colors. Again each channel is processed independently.

First the endpoints are unquantized, with each channel of each endpoint being processed independently. The number of bits in the original base w value represents the precision of the endpoints. The input



endpoint is called e , and the resulting endpoints are represented as 17-bit signed integers and called e' below.

For the BC6H_UF16 format:

- if the precision is already 16 bits, $e' = e$
- if $e = 0$, $e' = 0$
- if e is the maximum representible in the precision, $e' = 0xFFFF$
- otherwise, $e' = ((e \ll 16) + 0x8000) \gg \text{precision}$

For the BC6H_SF16 format, the value is treated as sign magnitude. The sign is not changed, e' and e refer only to the magnitude portion:

- if the precision is already 16 bits, $e' = e$
- if $e = 0$, $e' = 0$
- if e is the maximum representible in the precision, $e' = 0x7FFF$
- otherwise, $e' = ((e \ll 15) + 0x4000) \gg (\text{precision} - 1)$

Next, the palette values are generated using predefined weights, using the tables below:

$$\text{palette}[i] = (w' * (64 - \text{weight}[i]) + x' * \text{weight}[i] + 32) \gg 6$$

TWO mode weights:

palette index	0	1	2	3	4	5	6	7
weight	0	9	18	27	37	46	55	64

ONE mode weights:

palette index	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
weight	0	4	9	13	17	21	26	30	34	38	43	47	51	55	60	64

The two end palette indices are equal to the two endpoints given that the weights are 0 and 64. In the above equation w' and x' represent the endpoints e' computed in the previous step corresponding to w and x , respectively. For the second line in TWO mode, w and x are replaced with y and z .

The final step in computing the palette colors is to rescale the final results. For BC6H_UF16 format, the values are multiplied by 31/64. For BC6H_SF16, the values are multiplied by 31/32, treating them as sign magnitude. These final 16-bit results are ultimately treated as 16-bit floats.

Texel Selection

The final step is to select the appropriate palette index for each texel. This index then selects the 16-bit per channel palette value, which is re-interpreted as a 16-bit floating point result for input into the filter. This procedure differs depending on whether the mode is TWO or ONE.



ONE Mode

In ONE mode, there is only one set of palette colors, but the “indices” field is 63 bits. This field consists of a 4-bit palette index for each of the 16 texels, with the exception of the texel at [0][0] which has only 3 bits, the missing high bit being set to zero.

TWO Mode

32 partitions are defined for TWO, which are defined below. Each of the 32 cases shows the 4x4 block of texels, and is indexed by adding its hexadecimal row number (00-1C) to its column number (0-3). Each texel in the 4x4 block indicates whether that texel is part of line 0 (endpoints w and x) or line 1 (endpoints y and z). Each case has one texel each of “[0]” and “[1]”, the index that this is at is termed the “fix-up index”. These texels have one less bit in the index.

	0				1				2				3			
00	[0]	0	1	1	[0]	0	0	1	[0]	1	1	1	[0]	0	0	1
	0	0	1	1	0	0	0	1	0	1	1	1	0	0	1	1
	0	0	1	1	0	0	0	1	0	1	1	1	0	0	1	1
	0	0	1	[1]	0	0	0	[1]	0	1	1	[1]	0	1	1	[1]
04	[0]	0	0	0	[0]	0	1	1	[0]	0	0	1	[0]	0	0	0
	0	0	0	1	0	1	1	1	0	0	1	1	0	0	0	1
	0	0	0	1	0	1	1	1	0	1	1	1	0	0	1	1
	0	0	1	[1]	1	1	1	[1]	1	1	1	[1]	0	1	1	[1]
08	[0]	0	0	0	[0]	0	1	1	[0]	0	0	0	[0]	0	0	0
	0	0	0	0	0	1	1	1	0	0	0	1	0	0	0	0
	0	0	0	1	1	1	1	1	0	1	1	1	0	0	0	1
	0	0	1	[1]	1	1	1	[1]	1	1	1	[1]	0	1	1	[1]
0C	[0]	0	0	1	[0]	0	0	0	[0]	0	0	0	[0]	0	0	0
	0	1	1	1	0	0	0	0	1	1	1	1	0	0	0	0
	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0
	1	1	1	[1]	1	1	1	[1]	1	1	1	[1]	1	1	1	[1]
10	[0]	0	0	0	[0]	1	[1]	1	[0]	0	0	0	[0]	1	[1]	1
	1	0	0	0	0	0	0	1	0	0	0	0	0	0	1	1
	1	1	1	0	0	0	0	0	[1]	0	0	0	0	0	0	1
	1	1	1	[1]	0	0	0	0	1	1	1	0	0	0	0	0
14	[0]	0	[1]	1	[0]	0	0	0	[0]	0	0	0	[0]	1	1	1
	0	0	0	1	1	0	0	0	0	0	0	0	0	0	1	1
	0	0	0	0	[1]	1	0	0	[1]	0	0	0	0	0	1	1
	0	0	0	0	1	1	1	0	1	1	0	0	0	0	0	[1]



18	[0]	0	[1]	1	[0]	0	0	0	[0]	1	[1]	0	[0]	0	[1]	1
	0	0	0	1	1	0	0	0	0	1	1	0	0	1	1	0
	0	0	0	1	[1]	0	0	0	0	1	1	0	0	1	1	0
	0	0	0	0	1	1	0	0	0	1	1	0	1	1	0	0
1C	[0]	0	0	1	[0]	0	0	0	[0]	1	[1]	1	[0]	0	[1]	1
	0	1	1	1	1	1	1	1	0	0	0	1	1	0	0	1
	[1]	1	1	0	[1]	1	1	1	1	0	0	0	1	0	0	1
	1	0	0	0	0	0	0	0	1	1	1	0	1	1	0	0

The 46-bit “indices” field consists of a 3-bit palette index for each of the 16 texels, with the exception of the bracketed texels that have only two bits each. The high bit of these texels is set to zero.

BC7

These formats (BC7_UNORM and BC7_UNORM_SRGB) compresses 3-channel and 4-channel fixed point images.

The BC7 block is 16 bytes and represents a 4x4 block of texels. The texels are labeled as texel[row][column] where both row and column range from 0 to 3. Texel[0][0] is the upper left texel. BC7 has 8 different modes, the mode that the block is in is contained in the least significant bits (1-8 bits depending on mode).

The basic scheme consists of interpolating colors and alpha in some modes along either one, two, or three lines, with per-texel indices indicating which color/alpha along the line is chosen for each texel. If a two- or three-line mode is selected, one of 64 partition sets is indicated which selects which of the two lines each texel is assigned to, although some modes are limited to the first 16 partition sets. In the color-only modes, alpha is always returned at its default value of 1.0.

Some modes contain the following fields:

- **P-bits.** These represent shared LSB for all components of the endpoint, which increases the endpoint precision by one bit. In some cases both endpoints of a line share a P-bit.
- **Rotation bits.** For blocks with separate color and alpha, this 2-bit field allows selection of which of the four components has its own indexes (scalar) vs. the other three components (vector).
- **Index selector.** This 1-bit field selects whether the scalar or vector components uses the 3-bit index vs. the 2-bit index.

Field Definition

There are 8 possible modes for a BC7 block, the format of each is indicated in the 8 tables below. The mode is selected by the unique mode bits specified in each table. Each mode has particular characteristics described at the top of the table.

Mode 0: Color only, 3 lines (THREE), 4-bit endpoints with one P-bit per endpoint, 3-bit indices, 16 partitions



Bit	Description
0	mode = 0
4:1	partition
8:5	R0
12:9	R1
16:13	R2
20:17	R3
24:21	R4
28:25	R5
32:29	G0
36:33	G1
40:37	G2
44:41	G3
48:45	G4
52:49	G5
56:53	B0
60:57	B1
64:61	B2
68:65	B3
72:69	B4
76:73	B5
77	P0
78	P1
79	P2
80	P3
81	P4
82	P5
127:83	indices

Mode 1: Color only, 2 lines (TWO), 6-bit endpoints with one shared P-bit per line, 3-bit indices, 64 partitions

Bit	Description
1:0	mode = 10
7:2	partition
13:8	R0
19:14	R1
25:20	R2



Bit	Description
31:26	R3
37:32	G0
43:38	G1
49:44	G2
55:50	G3
61:56	B0
67:62	B1
73:68	B2
79:74	B3
80	P0
81	P1
127:82	indices

Mode 2: Color only, 3 lines (THREE), 5-bit endpoints, 2-bit indices, 64 partitions

Bit	Description
2:0	mode = 100
8:3	partition
13:9	R0
18:14	R1
23:19	R2
28:24	R3
33:29	R4
38:34	R5
43:39	G0
48:44	G1
53:49	G2
58:54	G3
63:59	G4
68:64	G5
73:69	B0
78:74	B1
83:79	B2
88:84	B3
93:89	B4
98:94	B5
127:99	indices



Mode 3: Color only, 2 lines (TWO), 7-bit endpoints with one P-bit per endpoint, 2-bit indices, 64 partitions

Bit	Description
3:0	mode = 1000
9:4	partition
16:10	R0
23:17	R1
30:24	R2
37:31	R3
44:38	G0
51:45	G1
58:52	G2
65:59	G3
72:66	B0
79:73	B1
86:80	B2
93:87	B3
94	P0
95	P1
96	P2
97	P3
127:98	indices

Mode 4: Color and alpha, 1 line (ONE), 5-bit color endpoints, 6-bit alpha endpoints, 16 2-bit indices, 16 3-bit indices, 2-bit component rotation, 1-bit index selector

Bit	Description
4:0	mode = 10000
6:5	rotation
7	index selector
12:8	R0
17:13	R1
22:18	G0
27:23	G1
32:28	B0
37:33	B1
43:38	A0
49:44	A1



Bit	Description
80:50	2-bit indices
127:81	3-bit indices

Mode 5: Color and alpha, 1 line (ONE), 7-bit color endpoints, 8-bit alpha endpoints, 2-bit color indices, 2-bit alpha indices, 2-bit component rotation

Bit	Description
5:0	mode = 100000
7:6	rotation
14:8	R0
21:15	R1
28:22	G0
35:29	G1
42:36	B0
49:43	B1
57:50	A0
65:58	A1
96:66	color indices
127:97	alpha indices

Mode 6: Combined color and alpha, 1 line (ONE), 7-bit endpoints with one P-bit per endpoint, 4-bit indices

Bit	Description
6:0	mode = 1000000
13:7	R0
20:14	R1
27:21	G0
34:28	G1
41:35	B0
48:42	B1
55:49	A0
62:56	A1
63	P0
64	P1
127:65	indices



Mode 7: Combined color and alpha, 2 lines (TWO), 5-bit endpoints with one P-bit per endpoint, 2-bit indices, 64 partitions

Bit	Description
7:0	mode = 10000000
13:8	partition
18:14	R0
23:19	R1
28:24	R2
33:29	R3
38:34	G0
43:39	G1
48:44	G2
53:49	G3
58:54	B0
63:59	B1
68:64	B2
73:69	B3
78:74	A0
83:79	A1
88:84	A2
93:89	A3
94	P0
95	P1
96	P2
97	P3
127:98	indices

Undefined mode values (bits 7:0 = 00000000) return zero in the RGB channels.

The indices fields are variable in length and due to the different locations of the fix-up indices depending on partition set there are a very large number of possible configurations. Each mode above indicates how many bits each index has, and the fix-up indices (one in ONE mode, two in TWO mode, and three in THREE mode) each have one less bit than indicated. However, the indices are always packed into the index fields according to the table below, with the specific bit assignments of each texel following the rules just given.

Bit	Description
LSBs	texel[0][0] index
	texel[0][1] index
	texel[0][2] index



Bit	Description
	texel[0][3] index
	texel[1][0] index
	texel[1][1] index
	texel[1][2] index
	texel[1][3] index
	texel[2][0] index
	texel[2][1] index
	texel[2][2] index
	texel[2][3] index
	texel[3][0] index
	texel[3][1] index
	texel[3][2] index
MSBs	texel[3][3] index

Endpoint Computation

The endpoints can be defined with different precision depending on mode, as shown above. This section describes how the endpoints are computed from the bits in the compression block. Each component of each endpoint follows the same steps.

If a P-bit is defined for the endpoint, it is first added as an additional LSB at the bottom of the endpoint value. The endpoint is then bit-replicated to create an 8-bit fixed point endpoint value with a range from 0x00 to 0xFF.

Palette Color Computation

The next step involves computing the color palette values that provide the available values for each texel's color. The color palette for each line consists of the two endpoint colors plus 2, 6, or 14 interpolated colors, depending on the number of bits in the indices. Again each channel is processed independently.

The equation to compute each palette color with index i , given two endpoints is as follows, using the tables below to determine the weight for each palette index:

$$\text{palette}[i] = (E0 * (64 - \text{weight}[i]) + E1 * \text{weight}[i] + 32) \gg 6$$

2-bit index weights:

palette index	0	1	2	3
weight	0	21	43	64



3-bit index weights:

palette index	0	1	2	3	4	5	6	7
weight	0	9	18	27	37	46	55	64

4-bit index weights:

palette index	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
weight	0	4	9	13	17	21	26	30	34	38	43	47	51	55	60	64

The two end palette indices are equal to the two endpoints given that the weights are 0 and 64. In the above equation E0 and E1 represent the even-numbered and odd-numbered endpoints computed in the previous step for the component and line currently being computed.

Texel Selection

The final step is to select the appropriate palette index for each texel. This index then selects the 8-bit per channel palette value, which is interpreted as an 8-bit UNORM value for input into the filter (In BC7_UNORM_SRGB to UNORM values first go through inverse gamma conversion). This procedure differs depending on whether the mode is ONE, TWO, or THREE.

ONE Mode

In ONE mode, there is only one set of palette colors, thus there is only a single "partition set" defined, with all texels selecting line 0 and texel [0][0] being the "fix-up index" with one less bit in the index.

TWO Mode

64 partitions are defined for TWO, which are defined below. Each of the 64 cases shows the 4x4 block of texels, and is indexed by adding its hexadecimal row number (00-3C) to its column number (0-3). Each texel in the 4x4 block indicates whether that texel is part of line 0 (endpoints 0 and 1) or line 1 (endpoints 2 and 3). Each case has one texel each of "[0]" and "[1]", the index that this is at is termed the "fix-up index". These texels have one less bit in the index.

	0				1				2				3			
00	[0]	0	1	1	[0]	0	0	1	[0]	1	1	1	[0]	0	0	1
	0	0	1	1	0	0	0	1	0	1	1	1	0	0	1	1
	0	0	1	1	0	0	0	1	0	1	1	1	0	0	1	1
	0	0	1	[1]	0	0	0	[1]	0	1	1	[1]	0	1	1	[1]
04	[0]	0	0	0	[0]	0	1	1	[0]	0	0	1	[0]	0	0	0
	0	0	0	1	0	1	1	1	0	0	1	1	0	0	0	1
	0	0	0	1	0	1	1	1	0	1	1	1	0	0	1	1
	0	0	1	[1]	1	1	1	[1]	1	1	1	[1]	0	1	1	[1]
no	[0]	0	0	0	[0]	0	1	1	[0]	0	0	0	[0]	0	0	0



	0	0	0	0	0	1	1	1	0	0	0	1	0	0	0	0
	0	0	0	1	1	1	1	1	0	1	1	1	0	0	0	1
	0	0	1	[1]	1	1	1	[1]	1	1	1	[1]	0	1	1	[1]
0C	[0]	0	0	1	[0]	0	0	0	[0]	0	0	0	[0]	0	0	0
	0	1	1	1	0	0	0	0	1	1	1	1	0	0	0	0
	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0
10	1	1	1	[1]	1	1	1	[1]	1	1	1	[1]	1	1	1	[1]
	[0]	0	0	0	[0]	1	[1]	1	[0]	0	0	0	[0]	1	[1]	1
	1	0	0	0	0	0	0	1	0	0	0	0	0	0	1	1
14	1	1	1	0	0	0	0	0	[1]	0	0	0	0	0	0	1
	1	1	1	[1]	0	0	0	0	1	1	1	0	0	0	0	0
	[0]	0	[1]	1	[0]	0	0	0	[0]	0	0	0	[0]	1	1	1
18	0	0	0	1	1	0	0	0	0	0	0	0	0	0	1	1
	0	0	0	0	[1]	1	0	0	[1]	0	0	0	0	0	1	1
	0	0	0	0	1	1	1	0	1	1	0	0	0	0	0	[1]
1C	[0]	0	[1]	1	[0]	0	0	0	[0]	1	[1]	0	[0]	0	[1]	1
	0	0	0	1	1	0	0	0	0	1	1	0	0	1	1	0
	0	0	0	1	[1]	0	0	0	0	1	1	0	0	1	1	0
20	0	0	0	0	1	1	0	0	0	1	1	0	1	1	0	0
	[0]	0	0	1	[0]	0	0	0	[0]	1	[1]	1	[0]	0	[1]	1
	0	1	1	1	1	1	1	1	0	0	0	1	1	0	0	1
24	[1]	1	1	0	[1]	1	1	1	1	0	0	0	1	0	0	1
	1	0	0	0	0	0	0	0	1	1	1	0	1	1	0	0
	[0]	1	0	1	[0]	0	0	0	[0]	1	0	1	[0]	0	1	1
28	0	1	0	1	1	1	1	1	1	0	[1]	0	0	0	1	1
	0	1	0	1	0	0	0	0	0	1	0	1	[1]	1	0	0
	0	1	0	[1]	1	1	1	[1]	1	0	1	0	1	1	0	0
2C	[0]	0	[1]	1	[0]	1	0	1	[0]	1	1	0	[0]	1	0	1
	1	1	0	0	0	1	0	1	1	0	0	1	1	0	1	0
	0	0	1	1	[1]	0	1	0	0	1	1	0	1	0	1	0
2C	1	1	0	0	1	0	1	0	1	0	0	[1]	0	1	0	[1]
	[0]	1	[1]	1	[0]	0	0	1	[0]	0	[1]	1	[0]	0	[1]	1
	0	0	1	1	0	0	1	1	0	0	1	0	1	0	1	1
2C	1	1	0	0	[1]	1	0	0	0	1	0	0	1	1	0	1
	1	1	1	0	1	0	0	0	1	1	0	0	1	1	0	0
	[0]	1	[1]	0	[0]	0	1	1	[0]	1	1	0	[0]	0	0	0
2C	1	0	0	1	1	1	0	0	0	1	1	0	0	1	[1]	0



30	1	0	0	1	1	1	0	0	1	0	0	1	0	1	1	0
	0	1	1	0	0	0	1	[1]	1	0	0	[1]	0	0	0	0
	[0]	1	0	0	[0]	0	[1]	0	[0]	0	0	0	[0]	0	0	0
	1	1	[1]	0	0	1	1	1	0	0	[1]	0	0	1	0	0
	0	1	0	0	0	0	1	0	0	1	1	1	[1]	1	1	0
34	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0
	[0]	1	1	0	[0]	0	1	1	[0]	1	[1]	0	[0]	0	[1]	1
	1	1	0	0	0	1	1	0	0	0	1	1	1	0	0	1
	1	0	0	1	1	1	0	0	1	0	0	1	1	1	0	0
38	0	0	1	[1]	1	0	0	[1]	1	1	0	0	0	1	1	0
	[0]	1	1	0	[0]	1	1	0	[0]	1	1	1	[0]	0	0	1
	1	1	0	0	0	0	1	1	1	1	1	0	1	0	0	0
	1	1	0	0	0	0	1	1	1	0	0	0	1	1	1	0
3C	1	0	0	[1]	1	0	0	[1]	0	0	0	[1]	0	1	1	[1]
	[0]	0	0	0	[0]	0	[1]	1	[0]	0	[1]	0	[0]	1	0	0
	1	1	1	1	0	0	1	1	0	0	1	0	0	1	0	0
	0	0	1	1	1	1	1	1	1	1	1	0	0	1	1	1
3C	0	0	1	[1]	0	0	0	0	1	1	1	0	0	1	1	[1]

THREE Mode

64 partitions are defined for THREE, which are defined below. Each of the 64 cases shows the 4x4 block of texels, and is indexed by adding its hexadecimal row number (00-3C) to its column number (0-3). Each texel in the 4x4 block indicates whether that texel is part of line 0 (endpoints 0 and 1), line 1 (endpoints 2 and 3), or line 2 (endpoints 4 and 5). Each case has one texel each of "[0]", "[1]", and "[2]", the index that this is at is termed the "fix-up index". These texels have one less bit in the index.

	0				1				2				3			
00	[0]	0	1	[1]	[0]	0	0	[1]	[0]	0	0	0	[0]	2	2	[2]
	0	0	1	1	0	0	1	1	2	0	0	1	0	0	2	2
	0	2	2	1	[2]	2	1	1	[2]	2	1	1	0	0	1	1
	2	2	2	[2]	2	2	2	1	2	2	1	[1]	0	1	1	[1]
04	[0]	0	0	0	[0]	0	1	[1]	[0]	0	2	[2]	[0]	0	1	1
	0	0	0	0	0	0	1	1	0	0	2	2	0	0	1	1
	[1]	1	2	2	0	0	2	2	1	1	1	1	[2]	2	1	1
	1	1	2	[2]	0	0	2	[2]	1	1	1	[1]	2	2	1	[1]
08	[0]	0	0	0	[0]	0	0	0	[0]	0	0	0	[0]	0	1	2
	0	0	0	0	1	1	1	1	1	1	[1]	1	0	0	[1]	2



0C	[1]	1	1	1	[1]	1	1	1	2	2	2	2	0	0	1	2
	2	2	2	[2]	2	2	2	[2]	2	2	2	[2]	0	0	1	[2]
	[0]	1	1	2	[0]	1	2	2	[0]	0	1	[1]	[0]	0	1	[1]
	0	1	[1]	2	0	[1]	2	2	0	1	1	2	2	0	0	1
	0	1	1	2	0	1	2	2	1	1	2	2	[2]	2	0	0
10	0	1	1	[2]	0	1	2	[2]	1	2	2	[2]	2	2	2	0
	[0]	0	0	[1]	[0]	1	1	[1]	[0]	0	0	0	[0]	0	2	[2]
	0	0	1	1	0	0	1	1	1	1	2	2	0	0	2	2
	0	1	1	2	[2]	0	0	1	[1]	1	2	2	0	0	2	2
14	1	1	2	[2]	2	2	0	0	1	1	2	[2]	1	1	1	[1]
	[0]	1	1	[1]	[0]	0	0	[1]	[0]	0	0	0	[0]	0	0	0
	0	1	1	1	0	0	0	1	0	0	[1]	1	1	1	0	0
	0	2	2	2	[2]	2	2	1	0	1	2	2	[2]	2	[1]	0
18	0	2	2	[2]	2	2	2	1	0	1	2	[2]	2	2	1	0
	[0]	1	2	[2]	[0]	0	1	2	[0]	1	1	0	[0]	0	0	0
	0	[1]	2	2	0	0	1	2	1	2	[2]	1	0	1	[1]	0
	0	0	1	1	[1]	1	2	2	[1]	2	2	1	1	2	[2]	1
1C	0	0	0	0	2	2	2	[2]	0	1	1	0	1	2	2	1
	[0]	0	2	2	[0]	1	1	0	[0]	0	1	1	[0]	0	0	0
	1	1	0	2	0	[1]	1	0	0	1	2	2	2	0	0	0
	[1]	1	0	2	2	0	0	2	0	1	[2]	2	[2]	2	1	1
20	0	0	2	[2]	2	2	2	[2]	0	0	1	[1]	2	2	2	[1]
	[0]	0	0	0	[0]	2	2	[2]	[0]	0	1	[1]	[0]	1	2	0
	0	0	0	2	0	0	2	2	0	0	1	2	0	[1]	2	0
	[1]	1	2	2	0	0	1	2	0	0	2	2	0	1	[2]	0
24	1	2	2	[2]	0	0	1	[1]	0	2	2	[2]	0	1	2	0
	[0]	0	0	0	[0]	1	2	0	[0]	1	2	0	[0]	0	1	1
	1	1	[1]	1	1	2	0	1	2	0	1	2	2	2	0	0
	2	2	[2]	2	[2]	0	[1]	2	[1]	[2]	0	1	1	1	[2]	2
28	0	0	0	0	0	1	2	0	0	1	2	0	0	0	1	[1]
	[0]	0	1	1	[0]	1	0	[1]	[0]	0	0	0	[0]	0	2	2
	1	1	[2]	2	0	1	0	1	0	0	0	0	1	[1]	2	2
	2	2	0	0	2	2	2	2	[2]	1	2	1	0	0	2	2
2C	0	0	1	[1]	2	2	2	[2]	2	1	2	[1]	1	1	2	[2]
	[0]	0	2	[2]	[0]	2	2	0	[0]	1	0	1	[0]	0	0	0
	0	0	1	1	1	2	[2]	1	2	2	[2]	2	2	1	2	1
	0	0	2	2	0	2	2	0	2	2	2	2	[2]	1	2	1



	0	0	1	[1]	1	2	2	[1]	0	1	0	[1]	2	1	2	[1]
30	[0]	1	0	[1]	[0]	2	2	[2]	[0]	0	0	2	[0]	0	0	0
	0	1	0	1	0	1	1	1	1	[1]	1	2	2	[1]	1	2
	0	1	0	1	0	2	2	2	0	0	0	2	2	1	1	2
	2	2	2	[2]	0	1	1	[1]	1	1	1	[2]	2	1	1	[2]
34	[0]	2	2	2	[0]	0	0	2	[0]	1	1	0	[0]	0	0	0
	0	[1]	1	1	1	1	1	2	0	[1]	1	0	0	0	0	0
	0	1	1	1	[1]	1	1	2	0	1	1	0	2	1	[1]	2
	0	2	2	[2]	0	0	0	[2]	2	2	2	[2]	2	1	1	[2]
38	[0]	1	1	0	[0]	0	2	2	[0]	0	2	2	[0]	0	0	0
	0	[1]	1	0	0	0	1	1	1	1	2	2	0	0	0	0
	2	2	2	2	0	0	[1]	1	[1]	1	2	2	0	0	0	0
	2	2	2	[2]	0	0	2	[2]	0	0	2	[2]	2	[1]	1	[2]
3C	[0]	0	0	[2]	[0]	2	2	2	[0]	1	0	[1]	[0]	1	1	[1]
	0	0	0	1	1	2	2	2	2	2	2	2	2	0	1	1
	0	0	0	2	0	2	2	2	2	2	2	2	[2]	2	0	1
	0	0	0	[1]	[1]	2	2	[2]	2	2	2	[2]	2	2	2	0

Adaptive Scalable Texture Compression (ASTC)

This section describes the data structure of the Adaptive Scalable Texture Compression (ASTC) format, as well as the decoding flow of ASTC. Also described are the header format and mipmap layout in the compressed texture file of *.astc. This is based on the reference encoder and decoder from the Khronos committee, with an extension to support multiple miplevel texture.

ASTC is a new compressed texture format with following characteristics:

1. ASTC compression format is currently only used for static texture, due to the large amount of computation and high latency required to find the optimal configuration in compression. It cannot be used to compress dynamic textures such as a shadow map.
2. ASTC is a lossy compression technique that cannot be used to compress dynamic textures which do not tolerate quality degradation.
3. ASTC has a huge range of compression ratio and block size, but these choices are fixed for each texture for all blocks at all mipmap levels.
4. ASTC has options to support compression from 1 to 4 channels for texture data.
5. ASTC can support both high and low dynamic textures.
6. ASTC can support both 2D and 3D textures.

Supported Formats
2D LDR profile.
2D HDR profiles.



ASTC Fundamentals

This section describes some background details and new surface formats for ASTC.

Background

ASTC is a more advanced texture compression technique than the existing BC and ETC, and can reduce footprint & BW of static texture further in Graphics application by providing a texture compression solution at higher compression ratios. To best find the balance point of visual quality and compression, it provides a wide range of bit rate selection from 8bpp to 0.89 bpp in 2D, and 4.6bpp to 0.6 bpp in 3D at various block size of footprints. It also has flexibility to specify 1-4 components, selection of dual plane mode among the specified color components.

It extends the existing linear model on color distribution of each block in multiple partitions (up to 4), with flexible compact supporting on index/weight for color interpolation. ASTC also has a support of high dynamic range (HDR) image and 3D textures. The mixture of HDR and LDR data is within each block level allows a great flexibility to represent high dynamics variation at fine granularity. The support of 3D texture explores the data coherency in all 3 dimensions, without the need to mimic 3D map with 2D slices. On top of everything, void-extent regions are introduced for both 2D and 3D maps as further optimization on large constant region.

ASTC is a voted approved future texture format for OpenGL ES by Khronos Group, and is on projection to be accepted in D3D API. It provides less bandwidth, storage, lower power and high performance over existing techniques, and has been identified as a critical feature for Gen GPU to get future design win from desktop, laptop to tablet and handheld markets.

Due to the computational complexity and processing delay of the encoding process, ASTC compression encoding is always offline, and can only be used for static texture. It does not support auto mipmap generation and cannot be considered as a format for render target.

The ASTC provides a wide spectrum of bit per pixel for both 2D and 3D texture for both LDR and HDR images, hence a wide range of compression to any 2D and 3D texture.



LDR Compression Ratios:

2D Block Footprint	Bit Rate (bpp)	Compression ratio (LDR 32bpp)
4x4	8.00	4.0
5x4	6.40	5.0
5x5	5.12	6.3
6x5	4.27	7.5
6x6	3.56	9.0
8x5	3.20	10.0
8x6	2.67	12.0
10x5	2.56	12.5
10x6	2.13	15.0
8x8	2.00	16.0
10x8	1.60	20.0
10x10	1.28	25.0
12x10	1.07	29.9
12x12	0.89	36.0



HDR Compression Ratios:

2D Block Footprint	Bit Rate (bpp)	Compression ratio (LDR 32bpp)
4x4	8.00	8.0
5x4	6.40	10.0
5x5	5.12	12.5
6x5	4.27	15.0
6x6	3.56	18.0
8x5	3.20	20.0
8x6	2.67	24.0
10x5	2.56	25.0
10x6	2.13	30.0
8x8	2.00	32.0
10x8	1.60	40.0
10x10	1.28	50.0
12x10	1.07	59.8
12x12	0.89	71.9

Compared against fixed compression ratios of 4x or 8x on BC* formats, ASTC provides compression ratios from 4x to 36x for 2D LDR, 8x to 72x in 2D HDR maps, 7x to 54x on 3D LDR (32bpp) maps, and 14x to 108x in 3D HDR (64bpp). This can reduce bandwidth and footprint of a static 2D HDR or 3D textures to a small fractional of the existing BC formats, and greatly improve the performance on the graphic applications using these textures intensively.

Another benefit of ASTC is that, with the large range of selection of footprints and bpp, it can provide a good trade-off between quality degradation of the compressed texture and performance, due to the bandwidth and footprints reduction. This could not be achieved by any previously existing texture compression technologies.



Although ASTC has a huge benefit of bandwidth reduction, the expected performance gain in real 3D application from this technique depends on how much texture bandwidth bottleneck is relative to the throughput of computing in EU, Sampler, and other fixed function components.

New Surface Formats for ASTC Texture

The ASTC data format natively supports 14 2D block size, 10 3D block size, and each decoded format should support either UN8 (with sRGB conversion) or Float16 at each color component. Following is the full list of all different surface formats as the full combination of different block shapes and UN8 or Float16 options.

Programming Note	
Context:	Supported ASTC Formats
All 2D ASTC Formats (LDR and HDR) are supported.	

Value	[26] LDR/Full [25] 2D/3D [24] U8srgb /FLT16	Width 2D [23:21] 3D [23:22]	Height 2D [20:18] 3D [21:20]	Depth 2D: n/a 3D: [19:18]	Binary form	Name	(BPE)
000h	000	0	0		000 000 000	ASTC_LDR_2D_4x4_U8sRGB	8.00
008h	000	1	0		000 001 000	ASTC_LDR_2D_5x4_U8sRGB	6.40
009h	000	1	1		000 001 001	ASTC_LDR_2D_5x5_U8sRGB	5.12
011h	000	2	1		000 010 001	ASTC_LDR_2D_6x5_U8sRGB	4.27
012h	000	2	2		000 010 010	ASTC_LDR_2D_6x6_U8sRGB	3.56
021h	000	4	1		000 100 001	ASTC_LDR_2D_8x5_U8sRGB	3.20
022h	000	4	2		000 100 010	ASTC_LDR_2D_8x6_U8sRGB	2.67
031h	000	6	1		000 110 001	ASTC_LDR_2D_10x5_U8sRGB	2.56



Value	[26] LDR/Full [25] 2D/3D [24] U8srgb /FLT16	Width 2D [23:21] 3D [23:22]	Height 2D [20:18] 3D [21:20]	Depth 2D: n/a 3D: [19:18]	Binary form	Name	(BPE)
032h	000	6	2		000 110 010	ASTC_LDR_2D_10x6_U8sRGB	2.13
024h	000	4	4		000 100 100	ASTC_LDR_2D_8x8_U8sRGB	2.00
034h	000	6	4		000 110 100	ASTC_LDR_2D_10x8_U8sRGB	1.60
036h	000	6	6		000 110 110	ASTC_LDR_2D_10x10_U8sRGB	1.28
03eh	000	7	6		000 111 110	ASTC_LDR_2D_12x10_U8sRGB	1.07
03fh	000	7	7		000 111 111	ASTC_LDR_2D_12x12_U8sRGB	0.89
040h	001	0	0		001 000 000	ASTC_LDR_2D_4x4_FLT16	8.00
048h	001	1	0		001 001 000	ASTC_LDR_2D_5x4_FLT16	6.40
049h	001	1	1		001 001 001	ASTC_LDR_2D_5x5_FLT16	5.12
051h	001	2	1		001 010 001	ASTC_LDR_2D_6x5_FLT16	4.27
052h	001	2	2		001 010 010	ASTC_LDR_2D_6x6_FLT16	3.56
061h	001	4	1		001 100 001	ASTC_LDR_2D_8x5_FLT16	3.20
062h	001	4	2		001 100 010	ASTC_LDR_2D_8x6_FLT16	2.67
071h	001	6	1		001 110 001	ASTC_LDR_2D_10x5_FLT16	2.56



Value	[26] LDR/Full [25] 2D/3D [24] U8srgb /FLT16	Width 2D [23:21] 3D [23:22]	Height 2D [20:18] 3D [21:20]	Depth 2D: n/a 3D: [19:18]	Binary form	Name	(BPE)
072h	001	6	2		001 110 010	ASTC_LDR_2D_10x6_FLT16	2.13
064h	001	4	4		001 100 100	ASTC_LDR_2D_8x8_FLT16	2.00
074h	001	6	4		001 110 100	ASTC_LDR_2D_10x8_FLT16	1.60
076h	001	6	6		001 110 110	ASTC_LDR_2D_10x10_FLT16	1.28
07eh	001	7	6		001 111 110	ASTC_LDR_2D_12x10_FLT16	1.07
07fh	001	7	7		001 111 111	ASTC_LDR_2D_12x12_FLT16	0.89
080h	010	0	0	0	010 000 000	ASTC_LDR_3D_3x3x3_U8sRGB	4.74
090h	010	1	0	0	010 010 000	ASTC_LDR_3D_4x3x3_U8sRGB	3.56
094h	010	1	1	0	010 010 100	ASTC_LDR_3D_4x4x3_U8sRGB	2.67
095h	010	1	1	1	010 010 101	ASTC_LDR_3D_4x4x4_U8sRGB	2.00
0a5h	010	2	1	1	010 100 101	ASTC_LDR_3D_5x4x4_U8sRGB	1.60
0a9h	010	2	2	1	010 101 001	ASTC_LDR_3D_5x5x4_U8sRGB	1.28
0aah	010	2	2	2	010 101 010	ASTC_LDR_3D_5x5x5_U8sRGB	1.02
0bah	010	3	2	2	010 111 010	ASTC_LDR_3D_6x5x5_U8sRGB	0.85



Value	[26] LDR/Full [25] 2D/3D [24] U8srgb /FLT16	Width 2D [23:21] 3D [23:22]	Height 2D [20:18] 3D [21:20]	Depth 2D: n/a 3D: [19:18]	Binary form	Name	(BPE)
0beh	010	3	3	2	010 111 110	ASTC_LDR_3D_6x6x5_U8sRGB	0.71
0bfh	010	3	3	3	010 111 111	ASTC_LDR_3D_6x6x6_U8sRGB	0.59
140h	101	0	0	n/a	101 000 000	ASTC_FULL_2D_4x4_FLT16	8.00
148h	101	1	0	n/a	101 001 000	ASTC_FULL_2D_5x4_FLT16	6.40
149h	101	1	1	n/a	101 001 001	ASTC_FULL_2D_5x5_FLT16	5.12
151h	101	2	1	n/a	101 010 001	ASTC_FULL_2D_6x5_FLT16	4.27
152h	101	2	2	n/a	101 010 010	ASTC_FULL_2D_6x6_FLT16	3.56
161h	101	4	1	n/a	101 100 001	ASTC_FULL_2D_8x5_FLT16	3.20
162h	101	4	2	n/a	101 100 010	ASTC_FULL_2D_8x6_FLT16	2.67
171h	101	6	1	n/a	101 110 001	ASTC_FULL_2D_10x5_FLT16	2.56
172h	101	6	2	n/a	101 110 010	ASTC_FULL_2D_10x6_FLT16	2.13
164h	101	4	4	n/a	101 100 100	ASTC_FULL_2D_8x8_FLT16	2.00
174h	101	6	4	n/a	101 110 100	ASTC_FULL_2D_10x8_FLT16	1.60
176h	101	6	6	n/a	101 110 110	ASTC_FULL_2D_10x10_FLT16	1.28



Value	[26] LDR/Full [25] 2D/3D [24] U8srgb /FLT16	Width 2D [23:21] 3D [23:22]	Height 2D [20:18] 3D [21:20]	Depth 2D: n/a 3D: [19:18]	Binary form	Name	(BPE)
17eh	101	7	6	n/a	101 111 110	ASTC_FULL_2D_12x10_FLT16	1.07
17fh	101	7	7	n/a	101 111 111	ASTC_FULL_2D_12x12_FLT16	0.89
1c0h	111	0	0	0	111 000 000	ASTC_FULL_3D_3x3x3_FLT16	4.74
1d0h	111	1	0	0	111 010 000	ASTC_FULL_3D_4x3x3_FLT16	3.56
1d4h	111	1	1	0	111 010 100	ASTC_FULL_3D_4x4x3_FLT16	2.67
1d5h	111	1	1	1	111 010 101	ASTC_FULL_3D_4x4x4_FLT16	2.00
1e5h	111	2	1	1	111 100 101	ASTC_FULL_3D_5x4x4_FLT16	1.60
1e9h	111	2	2	1	111 101 001	ASTC_FULL_3D_5x5x4_FLT16	1.28
1eah	111	2	2	2	111 101 010	ASTC_FULL_3D_5x5x5_FLT16	1.02
1fah	111	3	2	2	111 111 010	ASTC_FULL_3D_6x5x5_FLT16	0.85
1feh	111	3	3	2	111 111 110	ASTC_FULL_3D_6x6x5_FLT16	0.71
1ffh	111	3	3	3	111 111 111	ASTC_FULL_3D_6x6x6_FLT16	0.59



ASTC File Format and Memory Layout

ASTC Header Data Structure and Amendment

The 1st block of an ASTC compression texture is a header file. Its byte layout in the original header structure in *.astc file is:

```
struct astc_header
{
    uint8_t magic[4];
    uint8_t blockdim_x;
    uint8_t blockdim_y;
    uint8_t blockdim_z;
    uint8_t xsize[3]; // x-size = xsize[0] + xsize[1] + xsize[2]
    uint8_t ysize[3]; // x-size, y-size and z-size are given in texels;
    uint8_t zsize[3]; // block count is inferred
};
```

Since there are limited ranges for block dimensions in x, y and z directions as described in following, we could store additional information in the unused upper bits of these byte fields

Block Dimension	2D	3D
blockdim_x	4, 5, 6, 8, 10, 12	3, 4, 5, 6
blockdim_y	4, 5, 6, 8, 10, 12	3, 4, 5, 6
blockdim_z	1	3, 4, 5, 6

Since blockdim_z is in the range of [1,6], only lower 3 bits of blockdim_z is used. We proposed the **Intel astc extension format** with *numLODs* stored in the upper 5 bits of the byte field used for blockdim_z. This new byte field can be defined as:

$$\text{numLODs_blockdim_z} = (\text{numLODs}-1) \ll 3 \mid (\text{blockdim_z} \& 0x7);$$

New header:

```
struct astc_header
{
    uint8_t magic[4];
    uint8_t blockdim_x;
    uint8_t blockdim_y;
    uint8_t numLODs_blockdim_z;
    uint8_t xsize[3]; // width = xsize[0] + (xsize[1]«8) + (xsize[2]«16)
    uint8_t ysize[3]; // height= ysize[0] + (ysize[1]«8) + (ysize[2]«16)
    uint8_t zsize[3]; // depth = zsize[0] + (zsize[1]«8) + (zsize[2]«16)
    // x_size, y_size and z_size are given in texels;

    // block count is inferred
};
```



The driver or the software responsible for managing the memory resource will get numLODs and blockdim_z in:

$$\text{numLODs} = ((\text{numLODs_blockdim_z} \gg 3) \& 0x1F) + 1;$$

$$\text{blockdim_z} = \text{numLODs_blockdim_z} \& 0x7;$$

Data Layout in ASTC Compression File

A number of parameters are useful to determine where given pixels are located on the 2D & 3D surface. First, the width and height for each LOD level "L" is computed as:

$$W_L = ((\text{width} \gg L) > 0) ? \text{width} \gg L : 1$$

$$H_L = ((\text{height} \gg L) > 0) ? \text{height} \gg L : 1$$

$$D_L = ((\text{depth} \gg L) > 0) ? \text{depth} \gg L : 1$$

The numbers of blocks in width, height and depth slab in each LOD are:

$$N_w(L) = \text{Ceil}(W_L / B_w);$$

$$N_h(L) = \text{Ceil}(H_L / B_h);$$

$$N_s(L) = \text{Ceil}(D_L / B_d),$$

Where B_w, B_h and B_d is the block width, height and depth respectively.

Since ASTC has a native tile format specified by the encoding block size, the total number of blocks in each LOD level of the mipmap is described by nBL = N_w(L) * N_h(L) * N_s(L), The total number of blocks in the entire texture map is a summation of nBL's from all mipmap levels and all slabs, which are all pre-compressed via ASTC encoder. All the blocks in each LOD are in raster sequenced in width, height and then depth slab order.

Total ASTC Data Block Layout in All Mipmap Levels

The entire layout of the compression texture file looks like:

Address	Data Description
Addr0 (Base Address)	Header structure
Addr0+16	1st Data Block in LOD ₀
Addr0+32	2nd Data Block in LOD ₀
...	...
Addr1 = Addr0+16*nB0	Last Data Block in LOD ₀



Address	Data Description
Addr1 +16	1st Data Block in LOD ₁
Addr1+32	2nd Data Block in LOD ₁
...	...
Addr2 = Addr1+16*nB1	Last Data Block in LOD ₁
Addr2+16	1st Data Block in LOD ₂
Addr2+32	2nd Data Block in LOD ₂
...	...
Addr3 = Addr2+16*nB2	Last Data Block in LOD ₂
...	...

Data Layout in Memory for All Mipmap Levels

The following equations for give the base address (U_offset , V_offset) in Cartesian coordinates for the starting point of each mip map at LOD L and depth slab q :

$LOD=0$:

$$U_offset(0, q) = 0;$$

$$V_offset(0, q) = q * h_0;$$

$LOD=1$:

$$U_offset(1, q) = (q\%2)*w_1;$$

$$V_offset(1, q) = D_0*h_0 + (q\gg 1)*h_1;$$

$LOD=2$:

$$U_offset(2, q) = (q\%4)*w_2;$$

$$V_offset(2, q) = D_0*h_0 + \text{ceil}(D_1/2) * h_1 + (q\gg 2)*h_2;$$

$LOD=3$:

$$U_offset(3, q) = (q\%8)*w_3;$$

$$V_offset(3, q) = D_0*h_0 + \text{ceil}(D_1/2) * h_1 + \text{ceil}(D_2/2) * h_2 + (q\gg 3)*h_3;$$

.....



Since ASTC has a native tile format specified by the encoding block size, the total number of blocks in each LOD level of the mipmap is described by $nBL = Nw(L) * Nh(L) * Ns(L)$. The memory layout for TileY format are considered with 512bit (16Bx4) in 1 cacheline granularity, the total number of blocks is: $4 * ((Ceil(HL / Bh) + 3) / 4 * Ceil(WL / Bw) * Ceil(DL / Bd)$;

Here is the full list describing the total number of rows and columns of data in each mipmap for texture in ASTC format:

Table for block dimension in 2D

Block Size	ASTC Block Height (in line)	ASTC Block Width (in Byte)
4	$((Ceil(HL / 4) + 3) / 4) * 4$	$Ceil(WL / 4) * 16$
5	$((Ceil(HL / 5) + 3) / 4) * 4$	$Ceil(WL / 5) * 16$
6	$((Ceil(HL / 6) + 3) / 4) * 4$	$Ceil(WL / 6) * 16$
8	$((Ceil(HL / 8) + 3) / 4) * 4$	$Ceil(WL / 8) * 16$
10	$((Ceil(HL / 10) + 3) / 4) * 4$	$Ceil(WL / 10) * 16$
12	$((Ceil(HL / 12) + 3) / 4) * 4$	$Ceil(WL / 12) * 16$

Table for block dimension in 3D

Block Size	ASTC Block Height (in line)	ASTC Block Width (in Byte)	ASTC Block Depth/slab (in slice)
3	$((Ceil(HL / 3) + 3) / 4) * 4$	$Ceil(WL / 3) * 16$	$Ceil(DL / 3)$
4	$((Ceil(HL / 4) + 3) / 4) * 4$	$Ceil(WL / 4) * 16$	$Ceil(DL / 4)$
5	$((Ceil(HL / 5) + 3) / 4) * 4$	$Ceil(WL / 5) * 16$	$Ceil(DL / 5)$
6	$((Ceil(HL / 6) + 3) / 4) * 4$	$Ceil(WL / 6) * 16$	$Ceil(DL / 6)$

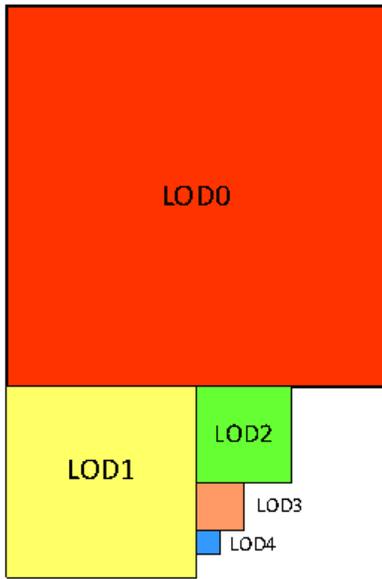
For example, an image of 64x64 with 5x5 block coding in LOD0 will have:

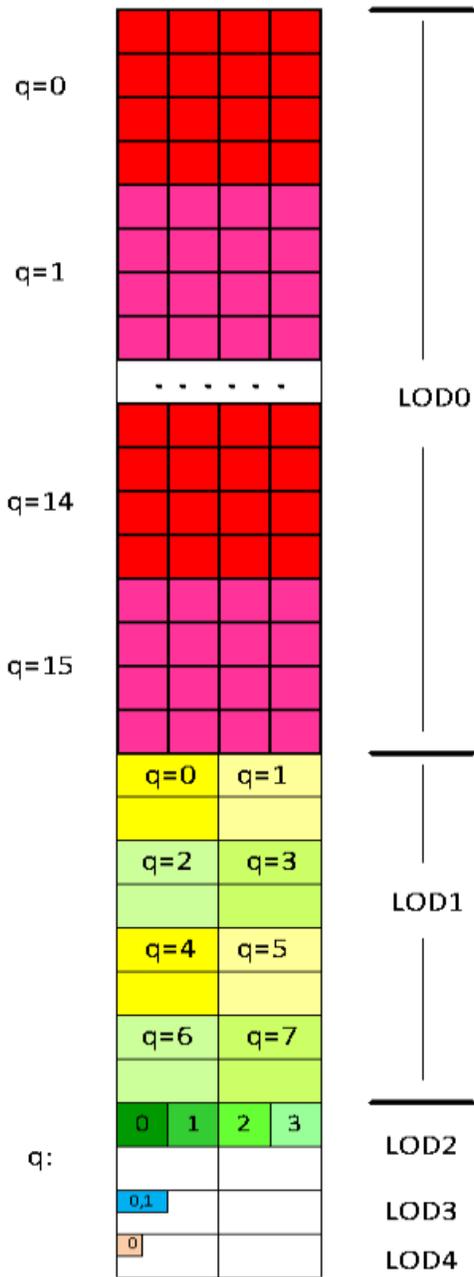
Block Height: $(13+3)/4*4=16$ (lines)

Block Width: $13 * 16 = 208$ (Bytes)

The following diagram illustrate the memory layout for 2D and 3D map respectively.

Memory Views





ASTC Data Structure

Layout and Description of Block Data

The block data structure is described in the following table in the categories of the block being partition enabled (2-4 partitions) or disabled (only 1 partition), as well as 1 plane or dual-plane mode. Where CEM refers to Color Endpoint Mode, and CCS stands for Color Channel Selection:



Layout of Partitioning Disabled (1 partition) and Enabled (multi-partition) blocks

Partition Disable	127:19			18:17	16:13	12:11	10:0	
(1 Plane)	Index Data		Color Endpoint Data		CEM	00	Index Mode	
(2 Planes)	Index Data		Color Endpoint Data	CCS	CEM	00	Index Mode	
Multi-partitions	127:29			28:23	22:13	12:11	10:0	
(1 Plane)	Index Data	Rest of CEM		Color Endpoint Data	CEM (Initial 6 bits)	Partition Index	Part	Index Mode
(2 Planes)	Index Data	CCS	Rest of CEM	Color Endpoint Data	CEM (Initial 6 bits)	Partition Index	Part	Index Mode

The 11 bit “Index mode” field specifies how the Texel Index Data is encoded. The bit encoding of this field is listed in next two tables, one for the 2D and one for the 3D.

The “Part” field specifies the number of partitions minus one. If dual plane mode is enabled, the number of partitions must be 3 or fewer. In case 4 partitions in such situation are specified, the error value is returned for all texels in the block. The size and layout of the extra configuration data depends on the number of partition, and the number of planes in the image.

Partitioning

For any non-void extend region, each block is subdivided into 1, 2, 3 or 4 partitions, with a separate color endpoint pair for each partition. The number of partitions is specified by the partition count-1 in bits [12:11] of block data. If 2 or more partitions are selected, partitioning is enabled, the 10 bit partition index is then used to select one from 1024 partitioning patterns, where the total set of patterns supported in ASTC depends on the partition count and block size. The partitioning patterns are produced generatively, which supports a very large set of partitioning patterns for different block sizes with a modest number of hardware gates implementation.

Index Mode

The “Index mode” field specifies how the Texel Index Data is encoded. The bit encoding of this field is listed in next two tables, one for the 2D and one for the 3D.

The Index Mode field specifies the width (N), height (M) and depth (Q) of the grid of indices, what range of values they use, and whether dual index planes are present. The index ranges are encoded using a 3 bit value R, which is interpreted together with a precision bit H, as follows:



Mode R(r2 r1 r0)	Low-precision (H=0)				High-precision (H=1)			
	Index Range	Trits	Quints	Bits	Index Range	Trits	Quints	Bits
0 0 0	Invalid				Invalid			
0 0 1	Invalid				Invalid			
0 1 0	[0,1]			1	[0,9]		1	1
0 1 1	[0,2]	1			[0,11]	1		2
1 0 0	[0,3]			2	[0,15]			4
1 0 1	[0,4]		1		[0,19]		1	2
1 1 0	[0,5]	1		1	[0,23]	1		3
1 1 1	[0,7]			3	[0,31]			5

Each index value is encoded using the specified number of Trits, Quints and Bits. The details of this encoding can be found in Section - *Integer Sequence Encoding*. Due to the encoding of the R field, bits r2 and r1 cannot both be zero,

The number of indices provided for a block is not tied to the block size in any way, instead, the indices form an N*M*Q ordered grid. N, M and Q are specified on a per-block basis rather than being a global texture property. For 2D blocks, N and M can be set to any value from 2 to 12 while Q is fixed at 1; for 3D blocks, N, M and Q can be set to any value from 2 to 5. The range used for each index can be set separately for each block. The Index Bit Mode field species the values of N, M, Q and the range; it also specifies whether Dual Index Planes are present or not as well.

The D bit in following tables is set to indicate dual-plane mode. In this mode, the maximum allowed number of partitions is 3. The size of the grid in each dimension must be less than or equal to the corresponding dimension of the block footprint. If the grid size is greater than the footprint dimension in any axis, then this is an illegal block encoding and all texels will decode to the error color.

For 2D blocks, the index mode field is laid out as follows:

The bit encoding of the index mode field for 2D Blocks

Bits									Width	Height	Notes
10	9	8	7	6	5	4	3:2	1:0	N	M	
D	H	B	A	r0	0 0	r2 r1			B+4	A+2	



Bits							Width	Height	Notes		
D	H	B		A	r0	0 1	r2 r1	B+8	A+2		
D	H	B		A	r0	1 0	r2 r1	A+2	B+8		
D	H	0	B	A	r0	1 1	r2 r1	A+2	B+6		
D	H	1	B	A	r0	1 1	r2 r1	B+2	A+2		
D	H	0	0	A	r0	r2 r1	0 0	12	A+2		
D	H	0	1	A	r0	r2 r1	0 0	A+2	12		
D	H	1	1	0	0	r0	r2 r1	0 0	6	10	
D	H	1	1	0	1	r0	r2 r1	0 0	10	6	
B		1	0	A	r0	r2 r1	0 0	A+6	B+6	D=0, H=0	
x	x	1	1	1	1	1	1 1	0 0	-	-	Void-Extent
x	x	1	1	1	x	x	x x	0 0	-	-	Reserve
x	x	x	x	x	x	x	0 0	0 0	-	-	Reserve

Note that, due to the encoding of the R field (r0, r1, r2), bits r2 and r1 cannot both be zero, which disambiguates the first five rows from the rest of the table. The penultimate row of the table is reserved only if bits [5:2] are not all 1, in which case it encodes a void-extent block (as shown in the previous row)

For 3D blocks, the index mode field is laid out as follows:

3D Index Mode Layout

Bits											Notes			
10	9	8	7	6	5	4	3	2	1	0	N	M	Q	(D, H)
D	H	B		A	r0	C		r2 r1	A+2	B+2	C+2			
B		0	0	A	r0	r2 r1	0	0	6	B+2	A+2	(0, 0)		
B		0	1	A	r0	r2 r1	0	0	A+2	6	B+2	(0, 0)		
B		1	0	A	r0	r2 r1	0	0	A+2	B+2	6	(0, 0)		



Bits											Notes			
D	H	1	1	0	0	r0	r2	r1	0	0	6	2	2	
D	H	1	1	0	1	r0	r2	r1	0	0	2	6	2	
D	H	1	1	1	0	r0	r2	r1	0	0	2	2	6	
x	x	1	1	1	1	1	1	1	0	0	-	-	-	Void-Extent
x	x	1	1	1	1	x	x	x	0	0	-	-	-	Reserve
x	x	x	x	x	x	x	0	0	0	0	-	-	-	Reserve

The D bit is set to indicate dual-plane mode:

- 1: dual index planes are used
- 0: single index plane is used

In this mode, the maximum allowed number of partitions is 3. The size of the grid in each dimension must be less than or equal to the corresponding dimension of the block footprint. If the grid size is greater than the footprint dimension in any axis, then this is an illegal block encoding and all texels will decode to the error color. The penultimate row of the table is reserved only if bits [4:2] are not all 1, in which case it encodes a void-extent block (as shown in the previous row).

H: Index Range Bit:

- 1: the High-Precision group is selected.
- 0: The Low-Precision group is selected.

Here is the detail description:

- The encoding of xx111111100 is for the void-extent block.
- The pattern xxxxxx0000 (the bottom 4 bits being 0000b) is reserved for future extension, and should result a NaN-vector when such a pattern is decoded.
- Any encodings not listed in the table are considered invalid and result in undened behavior if encountered by decoders.

Given the limitation of the fix length of 128 bits per block, there are restrictions that will not allow every possible encoding:

- The total number of indexes ($N \cdot M \cdot Q$ for single index plane, $2 \cdot N \cdot M \cdot Q$ for dual index planes) must not exceed 64.
- The length of the Index Integer Sequence must not exceed 96 bits.
- The length of the Index Integer Sequence must be at least 24 bits.



- The above restriction, combined with the other field widths of the format, implicitly restricts the Color Integer Sequence to a maximum of 75 bits.
- Blocks that violate these restrictions are not legally produced by the encoder, result a vector of NaNs if encountered by decoders.

Here is how the indices in each block are encoded and stored:

- They are encoded using the Integer Sequence Encoding method described in Appendix.
- The resulting bit-sequence is then bit-reversed, and stored from the top of the block downwards. The ordering of the indices in the Integer Sequence is a simple scan line-like ordering.

The indices are used in two steps to interpolate between two endpoint colors for each texel.

- First, they are scaled from whatever interval they were to the range [0,64];
- The resulting value is then used as a weight to interpolate between the two endpoints.

Index Planes

Depending on the Index Bits mode selected, an ASTC compressed block may offer 1 or 2 index planes. In the case of 2 index planes, two indices rather than just one are supplied for each texel that receives indices. Of these two indices, the first one is used for a weighted sum of three of the color components; the second is used for a weighted sum of the fourth color component. If only 1 index plane is present, it applies to all four color components.

If two index planes are used, then a 2-bit bit field is needed to indicate which of the color components the second index plane applies to. These two bits are stored just below the index bits, except in the case where leftover color endpoint type bits are present; in that case, these two bits are stored just below the leftover color endpoint type bits. This two-bit bit-field has the following layout:

Channel	Red	Green	Blue	Alpha
Value	0	1	2	3

If index infill is present while two index planes are being used, then index infill is performed on each index plane separately. If two index planes are used, the indexes are stored interleaved: the first index belongs to the first index plane, the second index belongs to the second index plane, the third index belongs to the first index plane, and so on.

Index Infill Procedure

In ASTC, each block has an $N \times M \times Q$ ordered grid of indices. N , M and Q may or may not match the dimensions of the actual block (e.g. it is possible to encode a 5×3 grid for an 8×8 block); if they don't match, then the grid is scaled so that its corner indexes align with the corner texels of the block, a bilinear index infill procedure is defined to interpolate an index for each texel. This procedure picks 1 to 4 indexes, and assigns each of them a weight; these weights are always a multiple of $1/16$. The exact details of this interpolation procedure are specified below.



Color Endpoint Mode

In single-partition mode, the Color Endpoint Mode (CEM) field stores one of 16 possible values. Each of these specifies how many raw data values are encoded, and how to convert these raw values into two RGBA color endpoints. They can be summarized as follows:

List of Color Endpoint Modes

CEM	Description	Class	# of integers to represent each pair of color end points
0	LDR Luminance or Alpha, direct	0	2
1	LDR Luminance, base+offset	0	2
2	HDR Luminance, large range	0	2
3	HDR Luminance, small range	0	2
4	LDR Luminance+Alpha, direct	1	4
5	LDR Luminance+Alpha, base+offset	1	4
6	LDR RGB, base+scale	1	4
7	HDR RGB, base+scale	1	4
8	LDR RGB, direct	2	6
9	LDR RGB, base+offset	2	6
10	LDR RGB, base+scale plus two A	2	6
11	HDR RGB, direct	2	6
12	LDR RGBA, direct	3	8: D=0; 6: D=1
13	LDR RGBA, base+offset	3	8: D=0; 6: D=1
14	HDR RGB, direct + LDR Alpha	3	8: D=0; 6: D=1
15	HDR RGB, direct + HDR Alpha	3	8: D=0; 6: D=1



Description
LDR modes are supported in ASTC LDR profile.
HDR modes are only supported in ASTC HDR mode.

In 2-4 partition modes, the encoding of Color Endpoint Modes are listed in following tables, where the endpoint mode representation may take from 6 to 14 bits, of which the first 6 bits are stored just after the partition indices, and the remaining bits are stored just below the index bits at variable position in the remaining space.

Partition / Class Types		High bits				[1:0]
Same Class	6b [5:0]	[5:2] Color Endpoint Mode				0 0
Different Classes	2-Partions	[7:6] Mode in P1	[5:4] Mode in P0	[3:3] Class Select for P1	[2:2] Class Select for P0	0 1 (Class 0 & 1)
	3-Partions			[10:9] Mode in P2	[8:7] Mode in P1	1 0 (Class 1 & 2)
			[6:5] Mode in P0	[4:4] Class Select for P2	[3:3] Class Select for P1	
	4-Partions	14b [13:0]	[13:12] Mode in P2	[11:10] Mode in P1	[9:8] Mode in P2	[7:6] Mode in P1
			[5:5] Class Select for P3	[4:4] Class Select for P2	[3:3] Class Select for P1	[2:2] Class Select for P0

More specifically, if the CEM selector value in bits [24:23] is not 00, then data layout is as follows:



List of Color Endpoint Class Types encoding under multi-partitions

Partitions							...	28	27	26	25	24	23
2	...	Index	M1				...	M0	C1	C0	CEM		
3	...	Index	M2	M1	M0		...	M0	C2	C1	C0	CEM	
4	...	Index	M3	M2	M1	M0	...	C3	C2	C1	C0	CEM	

In this view, each partition *i* has two fields. *C_i* is the class selector bit, choosing between the two possible CEM classes (0 indicates the lower of the two classes), and *M_i* is a two-bit field specifying the low bits of the color endpoint mode within that class. The additional bits appear at a variable bit position, immediately below the texel index data. The ranges used for the data values are not explicitly specified. Instead, they are derived from the number of available bits remaining after the configuration data and index data have been specified. Details of the decoding procedure for Color Endpoints can be found later.

Color Endpoint Data Size Determination

The size of the data used to represent color endpoints is not explicitly specified. Instead, it is determined from the index mode and number of partitions as follows:

```

config_bits = 17;
if (num_partitions>1)
if (single_CEM)
config_bits = 29;
else
config_bits = 24 + 3*num_partitions;

num_indices = M * N * Q; // size of index grid

if (dual_plane)
config_bits += 2;
num_indices *= 2;

index_bits = floor(num_indices*8*trits_in_index_range/5) +
floor(num_indices*7*quints_in_index_range/3) +
num_indices*bits_in_index_range;

remaining_bits = 128 - config_bits - index_bits;
num_CEM_pairs = base_CEM_class+1 + count_bits(extra_CEM_bits);

```

The CEM value range is then looked up from a table indexed by remaining bits and num_CEM_pairs. This table is initialized such that the range is as large as possible, consistent with the constraint that the number of bits required to encode num_CEM_pairs pairs of values is not more than the number of remaining bits. An equivalent iterative algorithm would be:



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```

num_CEM_values = num_CEM_pairs*2;
for(range = each possible CEM range in descending order of size)
{
    CEM_bits = floor(num_CEM_values*8*trits_in_CEM_range/5) +
        floor(num_CEM_values*7*quints_in_CEM_range/3) +
        num_CEM_values*bits_in_CEM_range;
    if (CEM_bits <= remaining_bits)
        break;
}
return range;

```

In cases where this procedure results in unallocated bits, these bits are not read by the decoding process and can have any value.

Void-Extent Blocks

As noted in the index mode, a specifically type of encoding is the void-extended type (2D), an efficient way to encode a constant color for large blocks of regions in texture. The data structure of a void extent is listed in following 2 tables as 2D and 3D blocks respectively.

Layout of 2D Void-Extend Block

127:112	111:96	95:80	79:64	63:51	50:38	37:25	24:12	11:10	9	8:0
A	B	G	R	T_high	T_low	S_high	S_low	Res:11	H	111111100

Layout of a 3D Void-Extent Block

127:112	111:96	95:80	79:64	63:55	54:46	45:37	36:28	27:19	18:10	9	8:0
A	B	G	R	R_high	R_low	T_high	T_low	S_high	S_low	H	111111100

Bit 9 H is the Dynamic Range flag, which indicates the format in which colors are stored. A 0 value indicates LDR, in which case the color components are stored as UNORM16 values. A 1 indicates HDR, in which case the color components are stored as FP16 values. If a void-extent block with HDR values is decoded in LDR mode, then the result will be the error color, opaque magenta, for all texels within the block. The low and height coordinate values are treated as unsigned integers and then normalized into the range 0..1 (by dividing by $2^{13}-1$ for 2D or 2^9-1 , for 3D respectively). The high values for each dimension must be greater than the corresponding low values, unless they are all all-1s. If all the coordinates are all-1s, then the void extent is ignored, and the block is simply a constant color block. The existence of single-color blocks with void extents must not produce results different from those obtained if these single-color blocks are defined without void-extents. Any situation in which the results would differ is invalid. Results from invalid void extents are undefined. If a void-extent appears in a MIPmap level other than the most detailed one, then the extent will apply to all of the more detailed levels too. This allows decoders to avoid sampling more detailed MIPmaps. If the more detailed MIPmap level is *not*



a constant color in this region, then the block may be marked as constant color, but without a void extent, as detailed above. If a void-extent extends to the edge of a texture, then filtered texture colors may not be the same color as that specified in the block, due to texture border colors, wrapping, or cube face wrapping. Care must be taken when updating or extracting partial image data that void-extents in the image do not become invalid.

Decoding Process

Content for this topic is currently under development.

Overview Decoding Flow

The goal for this feature is to reconstruct a cacheline (512b) of a target texture data at 4x4 region in UNORM8 A8R8G8B8 or 4x2 in FLT16 A16R16G16B16 with certain performance target, given the input texture coordinate (s,t,r). The scope of the u-architecture includes

- The additional surface format of the post decoding block, and the footprint (equivalent bpp). These are both global to each texture surface, and can be passed to the Sampler in the surface state via sampler messages.
- With post-scaled texture coordinate (u, v, p), the additional address calculation in FT to find the particular block location relative to the native block size specified in the surface state, as well as the relative texel position within that block. Assuming the block size for the block is Bu, Bv, Bp, the dimensions of a 2D surface as measured in block size tsize is:

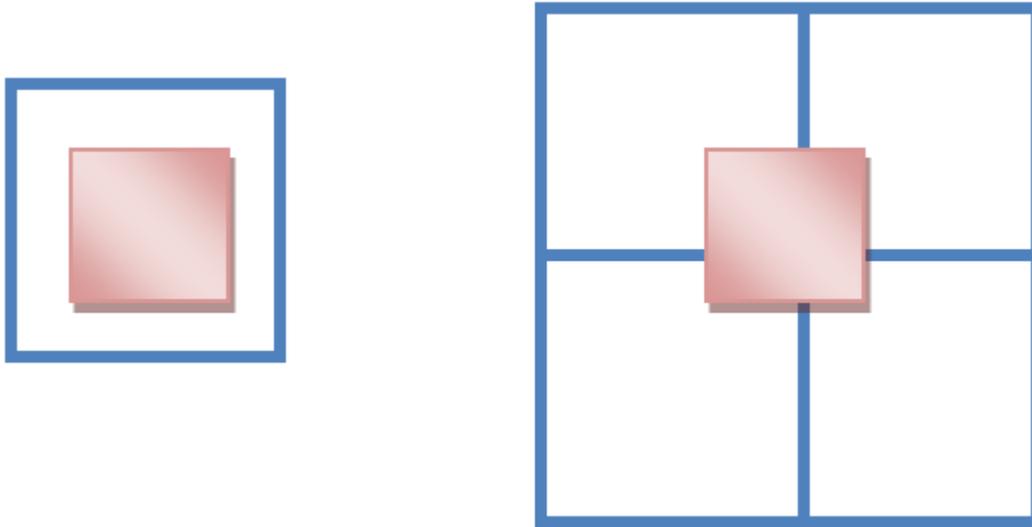
$$\begin{aligned}bw &= \text{MAX} (2, (w+ \text{tsize} -1)/ \text{tsize}) \\bh &= \text{MAX} (2, (h+ \text{tsize} -1)/ \text{tsize})\end{aligned}$$

Here the division is an integer division. The relationship between non-negative image coordinates [row,col] =[u, v] and block coordinates is

$$\begin{aligned}bu &= u / \text{tsize} \quad ; \quad buu = u \% \text{tsize}; \\bv &= v / \text{tsize} \quad ; \quad bvv = v \% \text{tsize}; \\bp &= p / \text{tsize} \quad ; \quad bpp = p \% \text{tsize};\end{aligned}$$

- With the selected sets of block size from 4x4 to 12x12 in 2D and 3x3x3 to 6x6x6 in 3D maps, 1~4 blocks of source texture needs to be fetched, depending on whether the destination tile size (4x2 in FLT16 or 4x4 in UNORM8888) is inclusive or come across a few source blocks, as shown in Fig.

Destination tile is inclusive within one tile or across up to 4 tiles in source texture region



- Decode 1 to 4 128-bit ASTC compressed blocks fetched from DRAM in Sampler from ASTC compression format to either UNORM8 (LDR) or FLT16(HDR), reconstruct the texels needed in the texture filtering stage. The total decoding processing include:

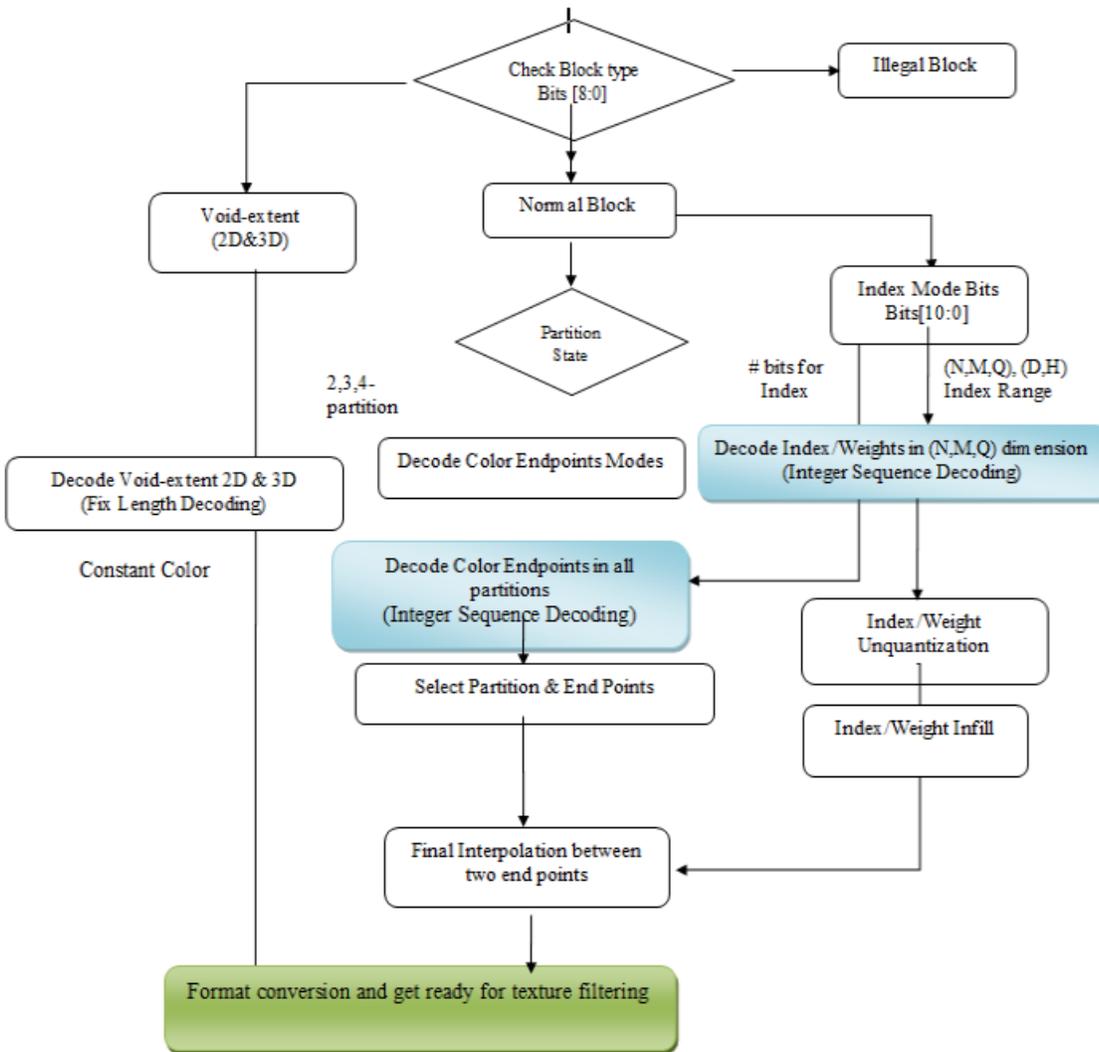
Front End Decoding Processing:

1. Detect if an ASTC block is a void-extent type, illegal type, or a normal non-void-extent type.
2. Decode the partition state – number of partitions in the current block.
3. Decode the index mode for the block include the partition seed and (N,M,Q) dimension of the compact sampling domain.
4. Decode the color endpoints modes in each partition.
5. Calculate the bit position and total # of bits used for Index.
6. Calculate the bit position and total # of bits and # of integers used in the Color endpoints in all partitions within the block.
7. With Integer Sequence Decoding, get all the indices in the compact domain defined by NxMxQ grid.
8. With Integer Sequence Decoding, get all the color end points from 16 modes in FLT16 for all partitions.

Back End Decoding Processing:

1. Reconstruct the indices at the selected sampling locations with infill scaling.
2. Find the partition from the partition seed at each sampling location.
3. Reconstruct the texture color value with the index and the pair of color end points at each sampling location.
4. If Block type is void extent, get the constant color from the high 64 bits and assign to the sampling location.
5. Convert the data to UNORM8 if LDR data is needed for the subsequent FL filtering process. Under void-extent block type,

Following is the flow diagram of the decoding process:





Integer Sequence Encoding

Both the index data and the endpoint color data are variable width, and are specified using a sequence of integer values. The range of each value in a sequence (e.g. a color index) is constrained. Since it is often the case that the most efficient range for these values is not a power of two, each value sequence is encoded using a technique known as “integer sequence encoding”. This allows efficient, hardware-friendly packing and unpacking of values with non-power-of-two ranges. In a sequence, each value has an identical range. The range is specified in one of the following forms:

Value range	MSB encoding	LSB encoding	Value	Block	Packed block size
$0 \dots 2^n - 1$	-	n bit value m ($n \leq 8$)	m	1	n
$0 \dots (3 * 2^n) - 1$	Base-3 “trit” value t	n bit value m ($n \leq 6$)	$t * 2^n + m$	5	$8 + 5*n$
$0 \dots (5 * 2^n) - 1$	Base-5 “quint” value q	n bit value m ($n \leq 5$)	$q * 2^n + m$	3	$7 + 3*n$

Since 3^5 is 243, it is possible to pack five trits into 8 bits (which has 256 possible values), so a trit can effectively be encoded as 1.6 bits. Similarly, since 5^3 is 125, it is possible to pack three quints into 7 bits (which has 128 possible values), so a quint can be encoded as 2.33 bits.

The encoding scheme packs the trits or quints, and then interleaves the n additional bits in positions that satisfy the requirements of an arbitrary length stream. This makes it possible to correctly specify lists of values whose length is not an integer multiple of 3 or 5 values. It also makes it possible to easily select a value at random within the stream. If there are insufficient bits in the stream to fill the final block, then unused (higher order) bits are assumed to be 0 when decoding.

To decode the bits for value number i in a sequence of bits b , both indexed from 0, perform the following:

If the range is encoded as n bits per value, then the value is bits $b[i*n:n-1:i*n]$ – a simple multiplexing operation.

If the range is encoded using a trit, then each block contains 5 values (v_0 to v_4), each of which contains a trit (t_0 to t_4) and a corresponding LSB value (m_0 to m_4). The first bit of the packed block is bit $\text{floor}(i/5)*(8+5*n)$. The bits in the block are packed as follows (in this example, n is 4):



Trit-based Packing

27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
T7		m4		T6		T5		m3		T4		m2		T3		T2		m1		T1		T0		m0			

The five trits t0 to t4 are obtained by bit manipulations of the 8 bits T[7:0] as follows:

```

if T[4:2] = 111
    C = { T[7:5], T[1:0] }; t4 = t3 = 2
else
    C = T[4:0]
    if T[6:5] = 11
        t4 = 2; t3 = T[7]
    else
        t4 = T[7]; t3 = T[6:5]
if C[1:0] = 11
    t2 = 2; t1 = C[4]; t0 = { C[3], C[2]&~C[3] }
else if C[3:2] = 11
    t2 = 2; t1 = 2; t0 = C[1:0]
else
    t2 = C[4]; t1 = C[3:2]; t0 = { C[1], C[0]&~C[1] }

```

Endpoint Unquantization

Each color endpoint is specified as a sequence of integers in a given range. These values are packed using integer sequence encoding, as a stream of bits stored from just above the configuration data, and growing upwards. Once unpacked, the values must be unquantized from their storage range, returning them to a standard range of 0..255. For bit-only representations, this is simple bit replication from the most significant bit of the value. For trit or quint-based representations, this involves a set of bit manipulations and adjustments to avoid the expense of full-width multipliers. This procedure ensures correct scaling, but scrambles the order of the decoded values relative to the encoded values. This must be compensated for using a table in the encoder.

The initial inputs to the procedure are denoted A, B, C and D and are decoded using the range as follows:

Range	Trits	Quints	Bits	Bit value	A (9 bits)	B (9 bits)	C (9 bits)	D (3 bits)
0..5	1		1	a	aaaaaaaaa	000000000	204	Trit value
0..9		1	1	a	aaaaaaaaa	000000000	113	Quint value
0..11	1		2	ba	aaaaaaaaa	b000b0bb0	93	Trit value



Range	Trits	Quints	Bits	Bit value	A (9 bits)	B (9 bits)	C (9 bits)	D (3 bits)
0..19		1	2	ba	aaaaaaaaa	b0000bb00	54	Quint value
0..23	1		3	cba	aaaaaaaaa	cb000cbcb	44	Trit value
0..39		1	3	cba	aaaaaaaaa	cb0000cbc	26	Quint value
0..47	1		4	dcba	aaaaaaaaa	dcb000dcb	22	Trit value
0..79		1	4	dcba	aaaaaaaaa	dcb0000dc	13	Quint value
0..95	1		5	edcba	aaaaaaaaa	edcb000ed	11	Trit value
0..159		1	5	edcba	aaaaaaaaa	edcb0000e	6	Quint value
0..191	1		6	fedcba	aaaaaaaaa	fedcb000f	5	Trit value

These are then processed as follows:

$$T = D * C + B;$$

$$T = T \wedge A;$$

$$T = (A \& 0x80) | (T \gg 2);$$

The multiply in the first line is nearly trivial as it only needs to multiply by 0, 1, 2, 3 or 4.

LDR Endpoint Decoding

The decoding method used depends on the Color Endpoint Mode (CEM) field, which specifies how many values are used to represent the endpoint. The CEM field also specifies how to take the n unquantized color endpoint values v_0 to v_{n-1} and convert them into two RGBA color endpoints e_0 and e_1 . The HDR Modes are more complex and do not fit neatly into the table. They are documented in following section. The LDR methods can be summarized as follows.



Color Endpoint Modes

CEM	Range	Description	# of end points	Endpoints Reconstruction
0	LDR	Luminance, direct	2	$e0=(v0,v0,v0,0xFF)$; $e1=(v1,v1,v1,0xFF)$;
1	LDR	Luminance, base+offset	2	$L0 = (v0 \gg 2) (v1 \& 0xC0)$; $L1=L0+(v1 \& 0x3F)$; if ($L1 > 0xFF$) { $L1=0xFF$; } $e0=(L0,L0,L0,0xFF)$; $e1=(L1,L1,L1,0xFF)$;
2	HDR	Luminance, large range	2	See next Section
3	HDR	Luminance, small range	2	See next Section
4	LDR	Luminance+Alpha, Direct	4	$e0=(v0,v0,v0,v2)$; $e1=(v1,v1,v1,v3)$;
5	LDR	Luminance+Alpha, base+offset	4	<code>bit_transfer_signed(v1,v0);</code> <code>bit_transfer_signed(v3,v2);</code> $e0=(v0,v0,v0,v2)$; $e1=(v0+v1,v0+v1,v0+v1,v2+v3)$; <code>clamp_unorm8(e0); clamp_unorm8(e1);</code>
6	LDR	RGB, base+scale	4	$e0=(v0*v3 \gg 8, v1*v3 \gg 8, v2*v3 \gg 8, 0xFF)$; $e1=(v0,v1,v2,0xFF)$;
7	HDR	RGB, base+scale	4	See next Section
8	LDR	RGB, Direct	6	$s0= v0+v2+v4$; $s1= v1+v3+v5$; if ($s1 >= s0$) { $e0=(v0,v2,v4,0xFF)$; $e1=(v1,v3,v5,0xFF)$; } else { $e0=blue_contract(v1,v3,v5,0xFF)$; $e1=blue_contract(v0,v2,v4,0xFF)$; }
9	LDR	RGB, base+offset	6	<code>bit_transfer_signed(v1,v0);</code> <code>bit_transfer_signed(v3,v2);</code> <code>bit_transfer_signed(v5,v4);</code> if ($v1+v3+v5 >= 0$) { $e0=(v0,v2,v4,0xFF)$; $e1=(v0+v1,v2+v3,v4+v5,0xFF)$; }



CEM	Range	Description	# of end points	Endpoints Reconstruction
				<pre>else { e0=blue_contract(v0+v1,v2+v3,v4+v5,0xFF); e1=blue_contract(v0,v2,v4,0xFF); } clamp_unorm8(e0); clamp_unorm8(e1);</pre>
10	LDR	RGB, base+scale plus two A	6	<pre>e0=(v0*v3>>8,v1*v3>>8,v2*v3>>8, v4); e1=(v0,v1,v2, v5);</pre>
11	HDR	RGB	6	See next Section
12	LDR	RGBA, direct	8	<pre>s0= v0+v2+v4; s1= v1+v3+v5; if (s1 >= s0){e0=(v0,v2,v4,v6); e1=(v1,v3,v5,v7); } else { e0=blue_contract(v1,v3,v5,v7); e1=blue_contract(v0,v2,v4,v6); }</pre>
13	LDR	RGBA, base+offset	8	<pre>bit_transfer_signed(v1,v0); bit_transfer_signed(v3,v2); bit_transfer_signed(v5,v4); bit_transfer_signed(v7,v6); if(v1+v3+v5 >= 0) { e0=(v0,v2,v4,v6); e1=(v0+v1,v2+v3,v4+v5,v6+v7); } else { e0=blue_contract(v0+v1,v2+v3,v4+v5,v6+v7); e1=blue_contract(v0,v2,v4,v6); } clamp_unorm8(e0); clamp_unorm8(e1);</pre>
14	HDR	RGB + LDR Alpha	8	See next Section
15	HDR	RGB + HDR Alpha	8	See next Section

Mode 14 is special in that the alpha values are interpolated linearly, but the color components are interpolated logarithmically. This is the only endpoint format with mixed-mode operation, and will return the error value if encountered in LDR mode. The `bit_transfer_signed` procedure transfers a bit from one signed byte value (a) to another (b). The result is an 8-bit signed integer value and a 6-bit integer value sign extended to 8 bits. Note that, as is often the case, this is easier to express in hardware than in C:

```
bit_transfer_signed(uint16_t& a, uint16_t& b)
```



```
{
    b »= 1;
    b |= a & 0x80;
    a »= 1;
    a &= 0x3F;
    if( (a&0x20)!=0 ) a-=0x40;
}
```

For the purposes of this pseudocode, the signed bytes are passed in as unsigned 16-bit integers because the semantics of a right shift on a signed value in C are undefined.

The `blue_contract` procedure is used to give additional precision to RGB colors near grey:

```
color blue_contract( int r, int g, int b, int a )
{
    color c;
    c.r = (r+b) » 1;
    c.g = (g+b) » 1;
    c.b = b;
    c.a = a;
    return c;
}
```

The `clamp_unorm8` procedure is used to clamp a color into the UNORM8 range:

```
void clamp_unorm8(color c)
{
    if(c.r < 0) {c.r=0;} else if(c.r > 255) {c.r=255;}
    if(c.g < 0) {c.g=0;} else if(c.g > 255) {c.g=255;}
    if(c.b < 0) {c.b=0;} else if(c.b > 255) {c.b=255;}
    if(c.a < 0) {c.a=0;} else if(c.a > 255) {c.a=255;}
}
```

HDR Endpoint Decoding

The 6 HDR CEM modes on color endpoints reconstruction and surface formats are only used in full-profile ASTC texture in float 16 bit.

- HDR Endpoint Mode 2: HDR Luminance, large range



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- HDR Endpoint Mode 3: HDR Luminance, small range
- HDR Endpoint Mode 7: HDR RGB, base + scale
- HDR Endpoint Mode 11: HDR RGB, direct
- HDR Endpoint Mode 14: HDR RGB, direct + LDR Alpha
- HDR Endpoint Mode 15: HDR RGB, direct + HDR Alpha

HDR Endpoint Mode 2 (HDR Luminance, Large Range)

Mode 2 represents luminance-only data with a large range. It encodes using two values (v0, v1). The complete decoding procedure is as follows:

```

If (v1 >= v0)
{
    y0 = (v0 << 4);
    y1 = (v1 << 4);
}
else {
    y0 = (v1 << 4) + 8;
    y1 = (v0 << 4) - 8;
}
// Construct RGBA result (0x780 is 1.0f)

e0 = (y0, y0, y0, 0x780);
e1 = (y1, y1, y1, 0x780);

```

HDR Endpoint Mode 3 (HDR Luminance, Small Range)

Mode 3 represents luminance-only data with a small range. It packs the bits for a base luminance value, together with an offset, into two values (v0, v1):

Value	Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
V0	M	L[6:0]						
V1	X[3:0]				D[3:0]			

The bit field marked as X allocates different bits to L or d depending on the value of the mode bit M. The complete decoding procedure is as follows:

```

// Check mode bit and extract.
If ((v0 & 0x80) != 0)
{
    y0 = ((v1 & 0xE0) << 4) | ((v0 & 0x7F) << 2);
    d = (v1 & 0x1F) << 2;
}

```



```

else {
    y0 = ((v1 & 0xF0) << 4) | ((v0 & 0x7F) << 1);
    d = (v1 & 0x0F) << 1;
}
// Add delta and clamp
y1 = y0 + d;
if(y1 > 0xFF) { y1 = 0xFF; }
// Construct RGBA result (0x780 is 1.0f)
e0 = (y0, y0, y0, 0x780);
e1 = (y1, y1, y1, 0x780);

```

HDR Endpoint Mode 7 (HDR RGB, Base+Scale)

Mode 7 packs the bits for a base RGB value, a scale factor, and some mode bits into the four values (v0, v1, v2, v3).

HDR Mode 7 Value Layout

Value	Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
V0	M[3]	M[2]	R[5:0]					
V1	M[1]	X0	X1	G[4:0]				
V2	M[0]	X2	X3	B[4:0]				
V3	X4	X5	X6	S[4:0]				

The mode bits M[0:3] are a packed representation of an endpoint bit mode, together with the major component index. For modes 0 to 4, the component (red, green, or blue) with the largest magnitude is identified, and the values are swizzled to ensure that it is decoded from the red channel. The endpoint bit mode is used to determine the number of bits assigned to each component of the endpoint, and the destination of each of the extra bits X0 to X6, as follows:

Endpoint Bit Mode

Mode	Number of bits				Description of Extra Bits							
	R	G	B	Scale	X0	X1	X2	X3	X4	X5	X6	
0	11	5	5	7	R[9]	R[8]	R[7]	R[10]	R[6]	S[6]	S[5]	
1	11	6	6	5	R[8]	G[5]	R[7]	B[5]	R[6]	R[10]	R[9]	
2	10	5	5	8	R[9]	R[8]	R[7]	R[6]	S[7]	S[6]	S[5]	



Mode	Number of bits				Description of Extra Bits							
3	9	6	6	7	R[8]	G[5]	R[7]	B[5]	R[6]	S[6]	S[5]	
4	8	7	7	6	G[6]	G[5]	B[6]	B[5]	R[6]	R[7]	S[5]	
5	7	7	7	7	G[6]	G[5]	B[6]	B[5]	R[6]	S[6]	S[5]	

The complete decoding procedure is as follows:

// Extract mode bits and unpack to major component and mode.

```
int modeval = ((v0 & 0xC0) » 6) | ((v1 & 0x80) » 5) | ((v2 & 0x80) » 4);
```

```
int majcomp;
```

```
int mode;
```

```
if( (modeval & 0xC) != 0xC ) { majcomp = modeval » 2; mode = modeval & 3; }
```

```
else if( modeval != 0xF ) { majcomp = modeval & 3; mode = 4; }
```

```
else { majcomp = 0; mode = 5; }
```

// Extract low-order bits of r, g, b, and s.

```
int red = v0 & 0x3f;
```

```
int green = v1 & 0x1f;
```

```
int blue = v2 & 0x1f;
```

```
int scale = v3 & 0x1f;
```

// Extract high-order bits, which may be assigned depending on mode

```
int x0 = (v1 » 6) & 1; int x1 = (v1 » 5) & 1;
```

```
int x2 = (v2 » 6) & 1; int x3 = (v2 » 5) & 1;
```

```
int x4 = (v3 » 7) & 1; int x5 = (v3 » 6) & 1; int x6 = (v3 » 5) & 1;
```

// Now move the high-order xs into the right place.

```
int ohm = 1 « mode;
```

```
if( ohm & 0x30 ) green |= x0 « 6;
```

```
if( ohm & 0x3A ) green |= x1 « 5;
```

```
if( ohm & 0x30 ) blue |= x2 « 6;
```

```
if( ohm & 0x3A ) blue |= x3 « 5;
```

```
if( ohm & 0x3D ) scale |= x6 « 5;
```

```
if( ohm & 0x2D ) scale |= x5 « 6;
```

```
if( ohm & 0x04 ) scale |= x4 « 7;
```

```
if( ohm & 0x3B ) red |= x4 « 6;
```



```
if( ohm & 0x04 ) red |= x3 << 6;
if( ohm & 0x10 ) red |= x5 << 7;
if( ohm & 0x0F ) red |= x2 << 7;
if( ohm & 0x05 ) red |= x1 << 8;
if( ohm & 0x0A ) red |= x0 << 8;
if( ohm & 0x05 ) red |= x0 << 9;
if( ohm & 0x02 ) red |= x6 << 9;
if( ohm & 0x01 ) red |= x3 << 10;
if( ohm & 0x02 ) red |= x5 << 10;
// Shift the bits to the top of the 12-bit result.
static const int shamts[6] = { 1,1,2,3,4,5 };
int shamt = shamts[mode];
red <<= shamt; green <<= shamt; blue <<= shamt; scale <<= shamt;
// Minor components are stored as differences
if( mode != 5 ) { green = red - green; blue = red - blue; }
// Swizzle major component into place
if( majcomp == 1 ) swap( red, green );
if( majcomp == 2 ) swap( red, blue );
// Clamp output values, set alpha to 1.0
e1.r = clamp( red, 0, 0xFFF );
e1.g = clamp( green, 0, 0xFFF );
e1.b = clamp( blue, 0, 0xFFF );
e1.alpha = 0x780;
e0.r = clamp( red - scale, 0, 0xFFF );
e0.g = clamp( green - scale, 0, 0xFFF );
e0.b = clamp( blue - scale, 0, 0xFFF );
e0.alpha = 0x780;
```

HDR Endpoint Mode 11 (HDR RGB, Direct)

Mode 11 specifies two RGB values, which it calculates from a number of bitfields (a, b0, b1, c, d0 and d1) which are packed together with some mode bits into the six values (v0, v1, v2, v3, v4, v5):



HDR Mode 11 Value Layout

Value	Bit[7]	Bit[6]	Bit[5]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
V0	a[7:0]						
V1	m[0]	a[8]	c[5:0]				
V2	m[1]	X0	b0[5:0]				
V3	m[2]	X1	b1[5:0]				
V4	mj[0]	X2	X4	d0[4:0]			
V5	mj[1]	X3	X5	d1[4:0]			

If the major component bits $mj[1:0] = b11$, then the RGB values are specified directly as

HDR Mode 11 Value Layout

Value	Bit[7]	Bit[6]	Bit[5]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
V0	R0[11:4]						
V1	R1[11:4]						
V2	G0 [11:4]						
V3	G1[11:4]						
V4	1	B0[11:5]					
V5	1	B1[11:5]					

The mode bits $m[2:0]$ specify the bit allocation for the different values, and the destinations of the extra bits X0 to X5:

Endpoint Bit Mode

Mode	Number of Bits				Description of Extra Bits					
	a	b	c	d	X0	X1	X2	X3	X4	X5
0	9	7	6	7	b0[6]	b1[6]	d0[6]	d1[6]	d0[5]	d1[5]
1	9	8	6	6	b0[6]	b1[6]	b0[7]	b1[7]	d0[5]	d1[5]
2	10	6	7	7	a[9]	c[6]	d0[6]	d1[6]	d0[5]	d1[5]
3	10	7	7	6	b0[6]	b1[6]	a[9]	c[6]	d0[5]	d1[5]



Mode	Number of Bits				Description of Extra Bits					
4	11	8	6	5	b0[6]	b1[6]	b0[7]	b1[7]	a[9]	a[10]
5	11	6	7	6	a[9]	a[10]	c[7]	c[6]	d0[5]	d1[5]
6	12	7	7	5	b0[6]	b1[6]	a[11]	c[6]	a[9]	a[10]
7	12	6	7	6	a[9]	a[10]	a[11]	c[6]	d0[5]	d1[5]

The complete decoding procedure is as follows:

```
// Find major component
int majcomp = ((v4 & 0x80) » 7) | ((v5 & 0x80) » 6);
// Deal with simple case first
if( majcomp == 3 )
{
    e0 = (v0 « 4, v2 « 4, (v4 & 0x7f) « 5, 0x780);
    e1 = (v1 « 4, v3 « 4, (v5 & 0x7f) « 5, 0x780);
return;
}
// Decode mode, parameters.
int mode = ((v1 & 0x80) » 7) | ((v2 & 0x80) » 6) | ((v3 & 0x80) » 5);
int va = v0 | ((v1 & 0x40) « 2);
int vb0 = v2 & 0x3f;
int vb1 = v3 & 0x3f;
int vc = v1 & 0x3f;
int vd0 = v4 & 0x7f;
int vd1 = v5 & 0x7f;
// Assign top bits of vd0, vd1.
static const int dbitstab[8] = {7,6,7,6,5,6,5,6};
vd0 = signextend( vd0, dbitstab[mode] );
vd1 = signextend( vd1, dbitstab[mode] );
// Extract and place extra bits
int x0 = (v2 » 6) & 1;
int x1 = (v3 » 6) & 1;
int x2 = (v4 » 6) & 1;
```



```
int x3 = (v5 » 6) & 1;
int x4 = (v4 » 5) & 1;
int x5 = (v5 » 5) & 1;
int ohm = 1 « mode;
if( ohm & 0xA4 ) va |= x0 « 9;
if( ohm & 0x08 ) va |= x2 « 9;
if( ohm & 0x50 ) va |= x4 « 9;
if( ohm & 0x50 ) va |= x5 « 10;
if( ohm & 0xA0 ) va |= x1 « 10;
if( ohm & 0xC0 ) va |= x2 « 11;
if( ohm & 0x04 ) vc |= x1 « 6;
if( ohm & 0xE8 ) vc |= x3 « 6;
if( ohm & 0x20 ) vc |= x2 « 7;
if( ohm & 0x5B ) vb0 |= x0 « 6;
if( ohm & 0x5B ) vb1 |= x1 « 6;
if( ohm & 0x12 ) vb0 |= x2 « 7;
if( ohm & 0x12 ) vb1 |= x3 « 7;
// Now shift up so that major component is at top of 12-bit value
int shamt = (modeval » 1) ^ 3;
va «= shamt; vb0 «= shamt; vb1 «= shamt;
vc «= shamt; vd0 «= shamt; vd1 «= shamt;
e1.r = clamp( va, 0, 0xFFFF );
e1.g = clamp( va - vb0, 0, 0xFFFF );
e1.b = clamp( va - vb1, 0, 0xFFFF );
e1.alpha = 0x780;
e0.r = clamp( va - vc, 0, 0xFFFF );
e0.g = clamp( va - vb0 - vc - vd0, 0, 0xFFFF );
e0.b = clamp( va - vb1 - vc - vd1, 0, 0xFFFF );
e0.alpha = 0x780;
if( majcomp == 1 )
{
```



```

swap( e0.r, e0.g ); swap( e1.r, e1.g );
}
else if( majcomp == 2 )
{
swap( e0.r, e0.b ); swap( e1.r, e1.b );
}

```

HDR Endpoint Mode 14 (HDR RGB, Direct + LDR Alpha)

Mode 14 specifies two RGBA values, using the eight values (v0, v1, v2, v3, v4, v5, v6, v7). First, the RGB values are decoded from (v0..v5) using the method from Mode 11. Then the alpha values are filled in from v6 and v7:

```

// Decode RGB as for mode 11
(e0,e1) = decode_mode_11(v0,v1,v2,v3,v4,v5)
// Now fill in the alphas
e0.alpha = v6;
e1.alpha = v7;

```

HDR Endpoint Mode 15 (HDR RGB, Direct + HDR Alpha)

Mode 15 specifies two RGBA values, using the eight values (v0, v1, v2, v3, v4, v5, v6, v7). First, the RGB values are decoded from (v0..v5) using the method from Mode 11. The alpha values are stored in values v6 and v7 as a mode and two values which are interpreted according to the mode:

HDR Mode 15 Alpha Value Layout

Value	Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]	
V6	M0	A[6:0]							
V7	M1	B[6:0]							

The alpha values are decoded from v6 and v7 as follows:

```

// Decode RGB as for mode 11
(e0,e1) = decode_mode_11(v0,v1,v2,v3,v4,v5)
// Extract mode bits
mode = ((v6 >> 7) & 1) | ((v7 >> 6) & 2);
v6 &= 0x7F;
v7 &= 0x7F;

```



```

if(mode==3)
{
// Directly specify alphas
    e0.alpha = v6 « 5;
    e1.alpha = v7 « 5;
}
else
{
    // Transfer bits from v7 to v6 and sign extend v7.
    v6 |= (v7 « (mode+1)) & 0x780;
    v7 &= (0x3F » mode);
    v7 ^= 0x20 » mode;
    v7 -= 0x20 » mode;
    v6 «= (4-mode);
    v7 «= (4-mode);
    // Add delta and clamp
    v7 += v6;
    v7 = clamp(v7, 0, 0xFFF);
    e0.alpha = v6;
    e1.alpha = v7;
}

```

Restrictions on Number of Partitions Per Block

Following table gives total number of partitions for each CEM mode given the restriction of total up to 16 integer values being decoded from the Integer Sequence Coding sequence.

Groups	Max Number of Partition	CEM Modes
(v0,v1)	4	0,1,2,3
(v0,v1,v2,v3)	4	4,5,6,7
(v0,v1,v2,v3,v4,v5)	3	8,9,10,11
(v0,v1,v2,v3,v4,v5,v6,v7)	2	12,13,14,15



Index Decoding

The index information is stored as a stream of bits, growing downwards from the most significant bit in the block. Bit n in the stream is thus bit $127-n$ in the block.

For each location in the index grid, a value (in the specified range) is packed into the stream. These are ordered in a raster pattern starting from location (0,0,0), with the X dimension increasing fastest, and the Z dimension increasing slowest. If dual-plane mode is selected, both indices are emitted together for each location, plane 0 first, then plane 1.

Index Unquantization

Each index plane is specified as a sequence of integers in a given range. These values are packed using integer sequence encoding.

Once unpacked, the values must be unquantized from their storage range, returning them to a standard range of 0..64. The procedure for doing so is similar to the color endpoint unquantization.

First, we unquantize the actual stored index values to the range 0..63.

For bit-only representations, this is simple bit replication from the most significant bit of the value.

For trit or quint-based representations, this involves a set of bit manipulations and adjustments to avoid the expense of full-width multipliers.

For representations with no additional bits, the results are as follows:

Index Unquantization Values

Range	0	1	2	3	4
0..2	0	32	63	-	-
0..4	0	16	32	47	63

For other values, we calculate the initial inputs to a bit manipulation procedure. These are denoted A, B, C and D and are decoded using the range as follows:

Index Unquantization Parameters

Range	Trits	Quints	Bits	Bit value	A (7 bits)	B (7 bits)	C (7 bits)	D (3 bits)
0..5	1		1	a	aaaaaaa	0000000	50	Trit
0..9		1	1	a	aaaaaaa	0000000	28	Quint
0..11	1		2	ba	aaaaaaa	b000b0b	23	Trit
0..19		1	2	ba	aaaaaaa	b0000b0	13	Quint



Range	Trits	Quints	Bits	Bit value	A (7 bits)	B (7 bits)	C (7 bits)	D (3 bits)
0..23	1		3	cba	aaaaaaa	cb000cb	11	Trit

These are then processed as follows:

$$T = D * C + B;$$

$$T = T \wedge A;$$

$$T = (A \& 0x20) | (T \gg 2);$$

The multiply in the first line is nearly trivial as it only needs to multiply by 0, 1, 2, 3 or 4. As a final step, for all types of value, the range is expanded from 0..63 up to 0..64 as follows:

```
if (T > 32) { T += 1; }
```

This allows the implementation to use 64 as a divisor during interpolation, which is much easier than using 63.

Infill Process

After unquantization, the indexes are subject to index selection and infill. The infill method is used to calculate the index for a texel position, based on the indices in the stored index grid array (which may be a different size). The procedure below must be followed exactly, to ensure bit exact results. The block size is specified as three dimensions along the s, t and r axes (Bs, Bt, Br). Texel coordinates within the block (s,t,r) can have values from 0 to one less than the block dimension in that axis.

For each block dimension, we compute scale factors (Ds, Dt, Dr)

$$Ds = \text{floor}((1024 + \text{floor}(Bs/2)) / (Bs-1));$$

$$Dt = \text{floor}((1024 + \text{floor}(Bt/2)) / (Bt-1));$$

$$Dr = \text{floor}((1024 + \text{floor}(Br/2)) / (Br-1));$$

Since the block dimensions are constrained, these are easily looked up in a table. These scale factors are then used to scale the (s,t,r) coordinates to a homogeneous coordinate (cs, ct, cr):

$$cs = Ds * s;$$

$$ct = Dt * t;$$

$$cr = Dr * r;$$

This homogeneous coordinate (cs, ct, cr) is then scaled again to give a coordinate (gs, gt, gr) in the index-grid space. The index-grid is of size (N, M, Q), as specified in the index mode field:

$$gs = (cs*(N-1)+32) \gg 6;$$

$$gt = (ct*(M-1)+32) \gg 6;$$

$$gr = (cr*(Q-1)+32) \gg 6;$$



The resulting coordinates may be in the range 0..176. These are interpreted as 4:4 unsigned fixed point numbers in the range 0.0 .. 11.0. If we label the integral parts of these (js, jt, jr) and the fractional parts (fs, ft, fr), then:

$$js = gs \gg 4; fs = gs \& 0x0F;$$

$$jt = gt \gg 4; ft = gt \& 0x0F;$$

$$jr = gr \gg 4; fr = gr \& 0x0F;$$

These values are then used to interpolate between the stored indices. This process differs for 2D and 3D.

For 2D, bilinear interpolation is used:

$$v0 = js + jt*N;$$

$$p00 = \text{decode_index}(v0);$$

$$p01 = \text{decode_index}(v0 + 1);$$

$$p10 = \text{decode_index}(v0 + N);$$

$$p11 = \text{decode_index}(v0 + N + 1);$$

The function `decode_index(n)` decodes the *n*th index in the stored index stream. The values `p00` to `p11` are the indices at the corner of the square in which the texel position resides. These are then weighted using the fractional position to produce the effective index *i* as follows:

$$w11 = (fs*ft+8) \gg 4;$$

$$w10 = ft - w11;$$

$$w01 = fs - w11;$$

$$w00 = 16 - fs - ft + w11;$$

$$i = (p00*w00 + p01*w01 + p10*w10 + p11*w11 + 8) \gg 4;$$

For 3D, simplex interpolation is used as it is cheaper than a naïve trilinear interpolation. First, we pick some parameters for the interpolation based on comparisons of the fractional parts of the texel position:

fs>ft	ft>fr	fs>fr	s1	s2	w0	w1	w2	w3
True	True	True	1	N	16-fs	fs-ft	ft-fr	fr
False	True	True	N	1	16-ft	ft-fs	fs-fr	fr
True	False	True	1	N*M	16-fs	fs-fr	fr-ft	ft
True	False	False	N*M	1	16-fr	fr-fs	fs-ft	ft
False	True	False	N	N*M	16-ft	ft-fr	fr-fs	fs
False	False	False	N*M	N	16-fr	fr-ft	ft-fs	fs



The effective index i is then calculated as:

```
v0 = js + jt*N + jr*N*M;
p0 = decode_index(v0);
p1 = decode_index(v0 + s1);
p2 = decode_index(v0 + s1 + s2);
p3 = decode_index(v0 + N*M + N + 1);
i = (p0*w0 + p1*w1 + p2*w2 + p3*w3 + 8) » 4;
```

Index Application

Once the effective index i for the texel has been calculated, the color endpoints are interpolated and expanded. For LDR endpoint modes, each color component C is calculated from the corresponding 8-bit endpoint components $C0$ and $C1$ as follows:

If sRGB conversion is not enabled, $C0$ and $C1$ are first expanded to 16 bits by bit replication:

```
C0 = (C0 << 8) | C0; C1 = (C1 << 8) | C1;
```

If sRGB conversion is enabled, $C0$ and $C1$ are expanded to 16 bits differently, as follows:

```
C0 = (C0 << 8) | 0x80; C1 = (C1 << 8) | 0x80;
```

$C0$ and $C1$ are then interpolated to produce a UNORM16 result C :

```
C = floor( (C0*(64-i) + C1*i + 32)/64 )
```

If sRGB conversion is enabled, the top 8 bits of the interpolation result are passed to the external sRGB conversion block. Otherwise, if $C = 65535$, then the final result is 1.0 (0x3C00) otherwise C is divided by 65536 and the infinite-precision result of the division is converted to FP16 with round-to-zero semantics. For HDR endpoint modes, color values are represented in a 12-bit logarithmic representation, and interpolation occurs in a piecewise-approximate logarithmic manner as follows:

In LDR mode, the error result is returned.

In HDR mode, the color components from each endpoint, $C0$ and $C1$, are initially shifted left 4 bits to become 16-bit integer values and these are interpolated in the same way as LDR. The 16-bit value C is then decomposed into the top five bits, E , and the bottom 11 bits M , which are then processed and recombined with E to form the final value C_f :

```
C = floor( (C0*(64-i) + C1*i + 32)/64 )
```

```
E = (C&0xF800) » 11; M = C&0x7FF;
```

```
if (M < 512) { Mt = 3*M; }
```

```
else if (M >= 1536) { Mt = 5*M - 2048; }
```

```
else { Mt = 4*M - 512; }
```

```
Cf = (E<<10) + (Mt>>3)
```



This final value C_f is interpreted as an IEEE FP16 value. If the result is $+\text{Inf}$ or NaN , it is converted to the bit pattern $0x7BFF$, which is the largest representable finite value.

Dual-Plane Decoding

If dual-plane mode is disabled, all of the endpoint components are interpolated using the same index value. If dual-plane mode is enabled, two indices are stored with each texel. One component is then selected to use the second index for interpolation, instead of the first index. The first index is then used for all other components.

The component to treat specially is indicated using the 2-bit Color Component Selector (CCS) field as follows:

Dual Plane Color Component Selector Values

Value	Index 0	Index 1
0	GBA	R
1	RBA	G
2	RGA	B
3	RGB	A

The CCS bits are stored at a variable position directly below the index bits and any additional CEM bits.

Partition Pattern Generation

When multiple partitions are active, each texel position is assigned a partition index. This partition index is calculated using a seed (the partition pattern index), the texel's x,y,z position within the block, and the number of partitions. An additional argument, `small_block`, is set to 1 if the number of texels in the block is less than 31, otherwise it is set to 0. The full partition selection algorithm is as follows:

```
int select_partition(int seed, int x, int y, int z,
int partitioncount, int small_block)
{
    if( small_block ){ x <<= 1; y <<= 1; z <<= 1; }
    seed += (partitioncount-1) * 1024;
    uint32_t rnum = hash52(seed);
    uint8_t seed1 = rnum & 0xF;
    uint8_t seed2 = (rnum >> 4) & 0xF;
    uint8_t seed3 = (rnum >> 8) & 0xF;
    uint8_t seed4 = (rnum >> 12) & 0xF;
    uint8_t seed5 = (rnum >> 16) & 0xF;
```



```

uint8_t seed6 = (rnum » 20) & 0xF;
uint8_t seed7 = (rnum » 24) & 0xF;
uint8_t seed8 = (rnum » 28) & 0xF;
uint8_t seed9 = (rnum » 18) & 0xF;
uint8_t seed10 = (rnum » 22) & 0xF;
uint8_t seed11 = (rnum » 26) & 0xF;
uint8_t seed12 = ((rnum » 30) | (rnum « 2)) & 0xF;
seed1 *= seed1; seed2 *= seed2; seed3 *= seed3; seed4 *= seed4;
seed5 *= seed5; seed6 *= seed6; seed7 *= seed7; seed8 *= seed8;
seed9 *= seed9; seed10 *= seed10; seed11 *= seed11; seed12 *= seed12;
int sh1, sh2, sh3;
if( seed & 1 )
{ sh1 = (seed & 2 ? 4 : 5); sh2 = (partitioncount == 3 ? 6 : 5); }
else
{ sh1 = (partitioncount == 3 ? 6 : 5); sh2 = (seed & 2 ? 4 : 5); }
sh3 = (seed & 0x10) ? sh1 : sh2;
seed1 »= sh1; seed2 »= sh2; seed3 »= sh1; seed4 »= sh2;
seed5 »= sh1; seed6 »= sh2; seed7 »= sh1; seed8 »= sh2;
seed9 »= sh3; seed10 »= sh3; seed11 »= sh3; seed12 »= sh3;
int a = seed1*x + seed2*y + seed11*z + (rnum » 14);
int b = seed3*x + seed4*y + seed12*z + (rnum » 10);
int c = seed5*x + seed6*y + seed9 *z + (rnum » 6);
int d = seed7*x + seed8*y + seed10*z + (rnum » 2);
a &= 0x3F; b &= 0x3F; c &= 0x3F; d &= 0x3F;
if( partitioncount < 4 ) d = 0;
if( partitioncount < 3 ) c = 0;
if( a >= b && a >= c && a >= d ) return 0;
else if( b >= c && b >= d ) return 1;
else if( c >= d ) return 2;
else return 3;
}

```



As has been observed before, the bit selections are much easier to express in hardware than in C.

The seed is expanded using a hash function hash52, which is defined as follows:

```
uint32_t hash52( uint32_t p )
{
    p ^= p >> 15; p -= p << 17; p += p << 7; p += p << 4; p ^= p >> 5;
    p += p << 16; p ^= p >> 7; p ^= p >> 3; p ^= p << 6; p ^= p >> 17;
    return p;
}
```

This assumes that all operations act on 32-bit values

Data Size Determination

The size of the data used to represent color endpoints is not explicitly specified. Instead, it is determined from the index mode and number of partitions as follows:

```
config_bits = 17;
if(num_partitions > 1)
if(single_CEM)
    config_bits = 29;
else
    config_bits = 24 + 3*num_partitions;
num_indices = M * N * Q; // size of index grid
if(dual_plane)
config_bits += 2;
num_indices *= 2;
index_bits = ceil(num_indices*8*trits_in_index_range/5) +
    ceil(num_indices*7*quints_in_index_range/3) +
    num_indices*bits_in_index_range;
remaining_bits = 128 - config_bits - index_bits;
num_CEM_pairs = base_CEM_class+1 + count_bits(extra_CEM_bits);
```

The CEM value range is then looked up from a table indexed by remaining bits and num_CEM_pairs. This table is initialized such that the range is as large as possible, consistent with the constraint that the number of bits required to encode num_CEM_pairs pairs of values is not more than the number of remaining bits.



An equivalent iterative algorithm would be:

```

num_CEM_values = num_CEM_pairs*2;
for(range = each possible CEM range in descending order of size)
{
    CEM_bits = ceil(num_CEM_values*8*trits_in_CEM_range/5) +
    ceil(num_CEM_values*7*quints_in_CEM_range/3) +
    num_CEM_values*bits_in_CEM_range;
    if(CEM_bits <= remaining_bits)
        break;
}
return range;

```

In cases where this procedure results in unallocated bits, these bits are not read by the decoding process and can have any value.

3D Void-Extent Blocks

The layout of a 3D Void-Extent block is as follows:

127:112	111:96	95:80	79:64	63:55	54:46	45:37	36:28	27:19	18:10	9:9	8:0
A	B	G	R	P_high	P_low	T_high	T_low	S_high	S_low	D	111111100

Bit 9 is the Dynamic Range flag, which indicates the format in which colors are stored. Value 0 indicates LDR, in which case the color components are stored as UNORM16 values, while value 1 indicates HDR, in which case the color components are stored as FP16 values.

The reason for the storage of UNORM16 values in the LDR case is due to the possibility that the value will need to be passed on to sRGB conversion. By storing the color value in the format which comes out of the interpolator, before the conversion to FP16, we avoid having to have separate versions for sRGB and linear modes.

If a void-extent block with HDR values is decoded in LDR mode, then the result will be the error color, opaque magenta, for all texels within the block.

The minimum and maximum coordinate values are treated as unsigned integers and then normalized into the range 0..1 (by dividing by $2^{13}-1$ or 2^9-1 , for 2D and 3D respectively). The maximum values for each dimension must be greater than the corresponding minimum values, unless they are all all-1s. If all the coordinates are all-1s, then the void extent is ignored, and the block is simply a constant-color block.



Illegal Encodings

In ASTC, there is a variety of ways to encode an illegal block. Decoders are required to recognize all illegal blocks and emit the standard Error Block color value upon encountering an illegal block. The standard Error Block color value is opaque magenta (R, G, B, A) = (0xFF, 0x00, 0xFF, 0xFF) in the LDR operation mode, and a vector of NaNs (**R, G, B, A**)=(NaN, NaN, NaN, NaN) in the HDR operation mode. It is recommended that the NaN be encoded as the bit-pattern 0xFFFF.

Here is a comprehensive list of situations that represent illegal block encodings:

- The index bit mode specified is one of the modes explicitly listed as Reserved.
- An index bit mode has been specified that would require more than 64 indexes total.
- An index bit mode has been specified that would require more than 96 bits for the Index Integer Sequence Encoding.
- An index bit mode has been specified that would require fewer than 24 bits for the Index Integer Sequence Encoding.
- The size of the index grid exceeds the size of the block footprint in any dimension.
- Color endpoint modes have been specified such that the Color Integer Sequence Encoding would require more than 18 integers.
- The number of bits available for color endpoint encoding after all the other fields have been counted is less than $\text{ceil}(13C/5)$ where C is the number of color endpoint integers (this would restrict color integers to a range smaller than 0.5, which is not supported).
- Dual Index Mode is enabled for a block with 4 partitions.
- Void-Extent blocks where the low coordinate for some texture axis is greater than or equal to the high coordinate.
- Under 3D mode, the depth (Q) is not 1

In LDR mode, a block which has both HDR and LDR endpoint modes assigned to different partitions is not an error block. Only those texels which belong to the HDR partition will result in the error color. Texels belonging to a LDR partition will be decoded as normal.

Profile Support

In order to ease verification and accelerate adoption, an LDR-only subset of the full ASTC specification has been made available.

Implementations of this LDR Profile must satisfy the following requirements:

- All textures with valid encodings for LDR Profile must decode identically using either a LDR Profile or Full Profile decoder.
- All features included only in the Full Profile must be treated as reserved in the LDR Profile, and return the error color on decoding.
- Any sequence of API calls valid for the LDR Profile must also be valid for the Full Profile and return identical results when given a texture encoded for the LDR Profile.



The feature subset for the LDR profile is:

- 2D textures only.
- Only those block sizes listed in Table 5 are supported.
- LDR operation mode only.
- Only LDR endpoint formats must be supported namely formats 0, 1, 4, 5, 6, 8, 9, 10, 12, 13.
- Decoding from a HDR endpoint results in the error color.
- Interpolation returns UNORM8 results when used in conjunction with sRGB.
- LDR void extent blocks must be supported, but void extents may not be checked.

Video Pixel/Texel Formats

This section describes the “video” pixel/texel formats with respect to memory layout. See the Overlay chapter for a description of how the Y, U, V components are sampled.

Packed Memory Organization

Color components are all 8 bits in size for YUV formats. For YUV 4:2:2 formats each DWord will contain two pixels and only the byte order affects the memory organization.

The following four YUV 4:2:2 surface formats are supported, listed with alternate names:

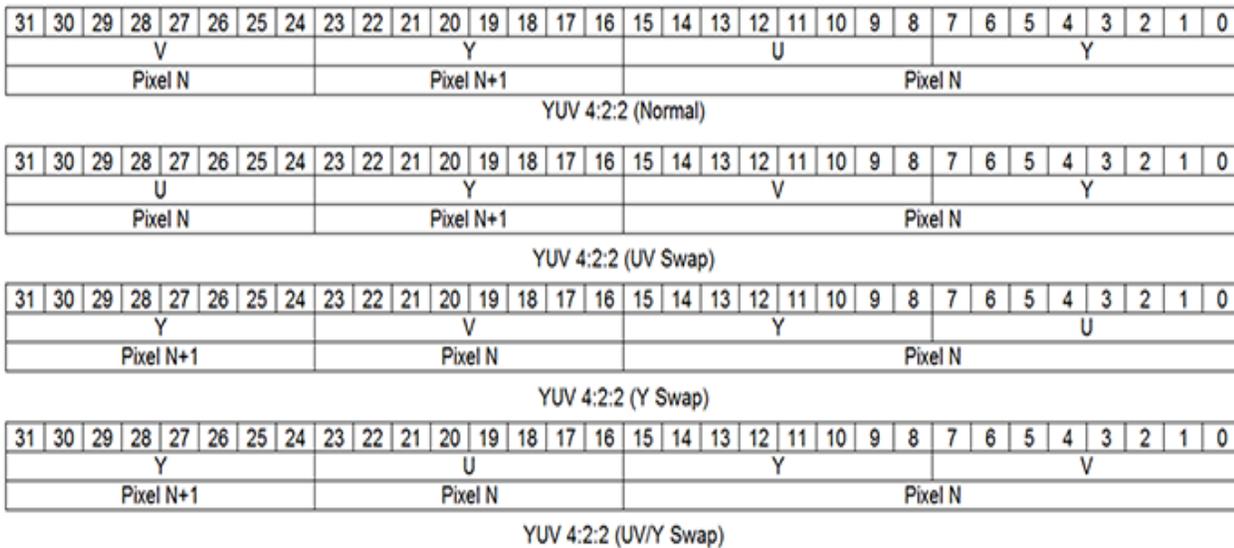
- YCRCB_NORMAL (YUYV/YUY2)
- YCRCB_SWAPUVY (VYUY) (R8G8_B8G8_UNORM)
- YCRCB_SWAPUV (YVYU) (G8R8_G8B8_UNORM)
- YCRCB_SWAPY (UYVY)

The channels are mapped as follows:

Cr (V)	Red
Y	Green
Cb (U)	Blue



Memory layout of packed YUV 4:2:2 formats



Planar Memory Organization

Planar formats use what could be thought of as separate buffers for the three color components. Because there is a separate stride for the Y and U/V data buffers, several memory footprints can be supported.

The 3D sampler supports direct sampling and filtering of planar video surfaces such as YV12 and NV12.

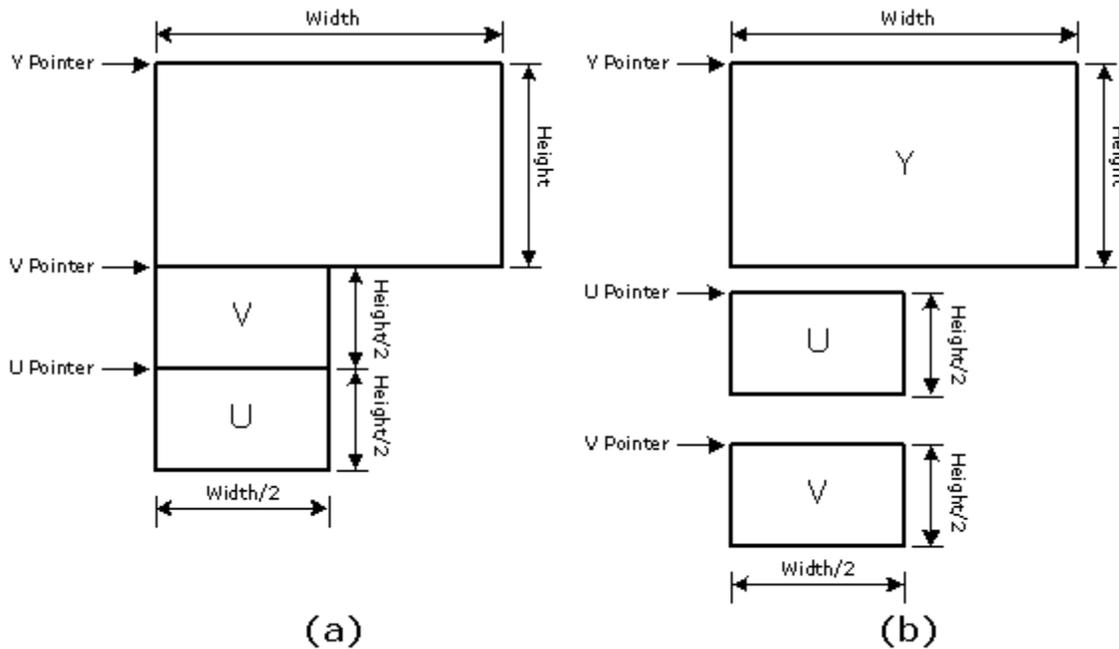
Programming Note	
Context:	Tiling of Planar Surface
Tiling of planar surfaces (tileX, tileY, tileYf, or tileYs) is only supported for planar surfaces where the chroma plane is full-pitch (e.g. NV21). In this case, the field Y Offset for U or UV Plane in the RENDER_SURFACE_STATE must be programmed to force the UV plane to be at the start of a tile.	

Programming Note	
Context:	NV21 Support
Sampling of NV21 surface format is supported by swapping the U and V channels when sampling the surface. This can be done by programming the Shader Channel Select in the RENDER_SURFACE_STATE for the Red and Blue Channels.	

The following figure shows two types of memory organization for the YUV 4:2:0 planar video data:

1. The memory organization of the common YV12 data, where all three planes are contiguous and the strides of U and V components are half of that of the Y component.
2. An alternative memory structure that the addresses of the three planes are independent but satisfy certain alignment restrictions.

YUV 4:2:0 Format Memory Organization



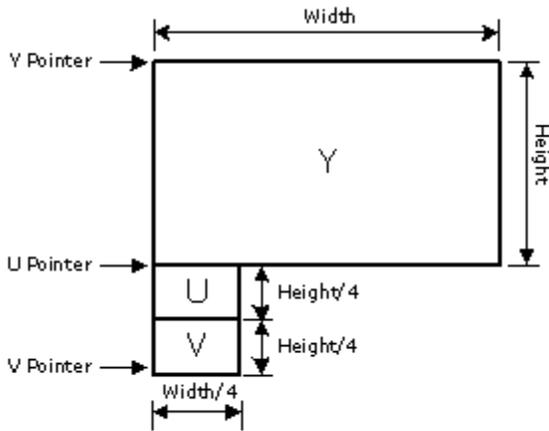
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The following figure shows memory organization of the planar YUV 4:1:0 format where the planes are contiguous.

Note: The chroma planes (U and V), when separate (case b above) are treated as half-pitch with respect to the Y plane.

Workaround
When using Planar formats for YUV with half-pitch chroma planes (e.g. YV12), and fenced tiling is not supported
LINEAR filtering of Planar YUV surfaces such as YV12 using the 3D sampler is done after the U and V have been replicated to form a YUV444 texels. This means that the U and V components will effectively be point-sampled rather than filtered. Acheive true filtering of the U and V components, the 3 planes of the YUV surface must be bound as separate surfaces, and the filtering must be done on each individually.

YUV 4:1:0 Format Memory Organization



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The table below shows how position within a Planar YUV surface chroma plane is calculated for various cases of U and V pitch and position. It also shows restrictions on the alignment of the chroma planes in memory for non-interleaved (YV12) and interleaved chroma (e.g. NV12) is used.

Case	Interleave Chroma	Pitch	Vertical U/V Offset
YUV with Half Pitch Chroma	No	Half	<u>When U is below Y</u> $Y_Uoffset = Y_Height * 2$ $Y_Voffset = Y_Height * 2 + V_Height$ <u>When V is below Y</u> $Y_Uoffset = Y_Height * 2 + V_Height$ $Y_Voffset = Y_Height * 2$
YUV with Full Pitch Chroma	Yes	Full	<u>When U is below Y</u> $Y_Uoffset = Y_Height$ $Y_Voffset = Y_Height + V_Height$ <u>When V is below Y</u> $Y_Uoffset = Y_Height + V_Height$ $Y_Voffset = Y_Height$
YUV for Media Sampling	Yes	Always Full	Same as 3D full pitch

Programming Note

Context: Planar YUV surfaces cannot be 1D surface types.

Because there is a requirement that the height of the Y plane of a planar surface must be a greater than 1, it cannot be programmed to be a **Surface Type** of SURFTYPE_1D.



Programming Note	
Context:	MIP Filtering
Surface state cannot have (MIP Mode Filter != NONE) for Planar YUV surfaces (e.g. PLANAR_420_8).	

Programming Note	
Context:	Standard Tiling
Planar YUV does not support MIP Tails as part of Standard Tiling. The MIP Tail Start field in RENDER_SURFACE_STATE must be programmed to 15.	

Raw Format

A format called "RAW" is available that is only supported with the untyped surface read/write, block, scattered, and atomic operation data port messages. It means that the surface has no inherent format. Surfaces of type RAW are addressed with byte-based offsets. The RAW surface format can be applied only to surface types of BUFFER and STRBUF.

Surface Memory Organizations

See *Memory Interface Functions* chapter for a discussion of tiled vs. linear surface formats.

Display, Overlay, Cursor Surfaces

These surfaces are memory image buffers (planes) used to refresh a display device in non-VGA mode. See the Display chapter for specifics on how these surfaces are defined/used.

2D Render Surfaces

These surfaces are used as general source and/or destination operands in 2D BLT operations.

Note that there is no coherency between 2D render surfaces and the texture cache. Software must explicitly invalidate the texture cache before using a texture that has been modified via the BLT engine.

See the 2D Instruction and 2D Rendering chapters for specifics on how these surfaces are used, restrictions on their size, placement, etc.



2D Monochrome Source

These 1 BPP (bit per pixel) surfaces are used as source operands to certain 2D BLT operations, where the BLT engine expands the 1 BPP source to the required color depth.

The texture cache stores any monochrome sources. There is no mechanism to maintain coherency between 2D render surfaces and texture-cached monochrome sources. Software must explicitly invalidate the texture cache before using a memory-based monochrome source that has been modified via the BLT engine. (Here the assumption is that SW enforces memory-based monochrome source surfaces as read-only surfaces.)

See the 2D Instruction and 2D Rendering chapters for specifics on how these surfaces are used, restrictions on their size, placement, coherency rules, etc.

2D Color Pattern

Color pattern surfaces are used as special pattern operands in 2D BLT operations.

The device uses the texture cache to store color patterns. There is no mechanism to maintain coherency between 2D render surfaces and (texture)-cached color patterns. Software is required to explicitly invalidate the texture cache before using a memory-based color pattern that has been modified via the BLT engine. (Here the assumption is that SW enforces memory-based color pattern surfaces as read-only surfaces.)

See the *2D Instruction* and *2D Rendering* chapters for specifics on how these surfaces are used, restrictions on their size, placement, etc.

3D Color Buffer (Destination) Surfaces

3D Color Buffer surfaces hold per-pixel color values for use in the 3D Pipeline. The 3D Pipeline always requires a Color Buffer to be defined.

See the Non-Video Pixel/Texel Formats section in this chapter for details on the Color Buffer pixel formats. See the 3D Instruction and 3D Rendering chapters for Color Buffer usage details.

The Color Buffer is defined as the BUFFERID_COLOR_BACK memory buffer via the 3DSTATE_BUFFER_INFO instruction. That buffer can be mapped to LM or SM (snooped or unsnooped), and can be linear or tiled. When both the Depth and Color Buffers are tiled, the respective Tile Walk directions must match.

When a linear Color Buffer and a linear Depth Buffer are used together:

- The buffers may have different pitches, though both pitches must be a multiple of 32 bytes.
- The buffers must be co-aligned with a 32-byte region.



3D Depth Buffer Surfaces

Depth Buffer surfaces hold per-pixel depth values and per-pixel stencil values for use in the 3D Pipeline. The 3D Pipeline does not require a Depth Buffer in general, though a Depth Buffer is required to perform non-trivial Depth Test and Stencil Test operations.

The Depth Buffer is specified via the 3DSTATE_DEPTH_BUFFER command. See the description of that instruction in *Windower* for restrictions.

See *Depth Buffer Formats* below for a summary of the possible depth buffer formats. See the Depth Buffer Formats section in this chapter for details on the pixel formats. See the *Windower* and *DataPort* chapters for details on the usage of the Depth Buffer.

Depth Buffer Formats

DepthBufferFormat / DepthComponent	BPP (Bits Per Pixel)	Description
D32_FLOAT_S8X24_UINT	64	32-bit floating point Z depth value in first DWord, 8-bit stencil in lower byte of second DWord
D32_FLOAT	32	32-bit floating point Z depth value
D24_UNORM_S8_UINT	32	24-bit fixed point Z depth value in lower 3 bytes, 8-bit stencil value in upper byte
D16_UNORM	16	16-bit fixed point Z depth value

3D Separate Stencil Buffer Surfaces

Separate Stencil Buffer surfaces hold per-pixel stencil values for use in the 3D Pipeline. Note that the 3D Pipeline does not require a Stencil Buffer to be allocated, though a Stencil Buffer is required to perform non-trivial Stencil Test operations.

UNRESOLVED CROSS-REFERENCE, Depth Buffer Formats summarizes Stencil Buffer formats. Refer to the Stencil Buffer Formats section in this chapter for details on the pixel formats. Refer to the *Windower* chapters for Stencil Buffer usage details.

The Stencil buffer is specified via the 3DSTATE_STENCIL_BUFFER command. See that instruction description in *Windower* for restrictions.

Depth Buffer Formats

DepthBufferFormat / DepthComponent	BPP (bits per pixel)	Description
R8_UNIT	8	8-bit stencil value in a byte



Surface Layout and Tiling

This section explains how various surface types (1D, 2D, 3D, and Cube) are laid out in memory. Most of the information in this section is independent of tiling. The concept of tiling can be laid on top of information. Wherever there is a specific difference it will be called out.

For Tiling (TileY, TileYs etc.), see the Address Tiling Function Introduction section which provides detailed information on how tiles are organized and laid out.

Maximum Surface Size in Bytes

In addition to restrictions on maximum height, width, and depth, surfaces are also restricted to a maximum size of 2^{38} bytes. All pixels within the surface must be contained within 2^{38} bytes of the base address.

Tiling

To improve efficiency in memory accesses, most surfaces can be laid out using a tiling scheme.

Supported Legacy Tiling Modes:

- **TileY**
- **TileX**
- **TileW**

Supported Tiled Resource Modes

- **TileYF:** 4KB tiling mode based on TileY
- **TileYS:** 64KB tiling mode based on TileY

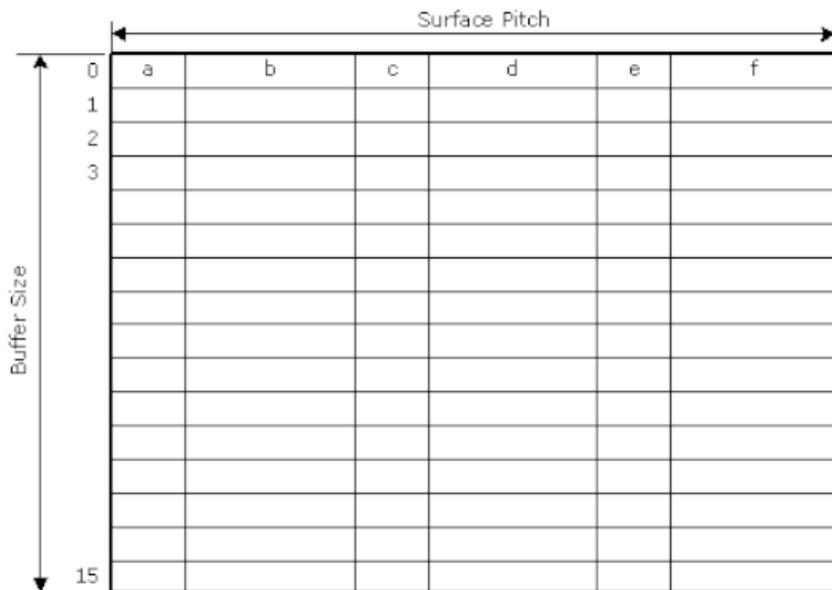
These modes are described in the Address Tiling Function Introduction volume.



Typed Buffers

A typed buffer is an array of structures. Each structure contains up to 2048 bytes of elements. Each element is a single surface format using one of the supported surface formats depending on how the surface is being accessed. The surface pitch state for the surface specifies the size of each structure in bytes.

The buffer is stored in memory contiguously with each element in the structure packed together, and the first element in the next structure immediately following the last element of the previous structure. Buffers are supported only in linear memory.



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Typed buffers are accessed using a surface state for each structure element (a,b,c, etc. in the diagram above). The surface state for element "b" (for example) contains the surface format of element "b" (which may differ from other elements), the base address points to element "b" in the first structure (slice 0 of the array). The pitch for all of the elements in the buffer is the same value, and the surface type of each element is SURFTYPE_BUFFER.

The offset into the typed buffer is given by the following equation:

$$\text{Offset} = (V * \text{Pitch}) + U$$



MIP Layout

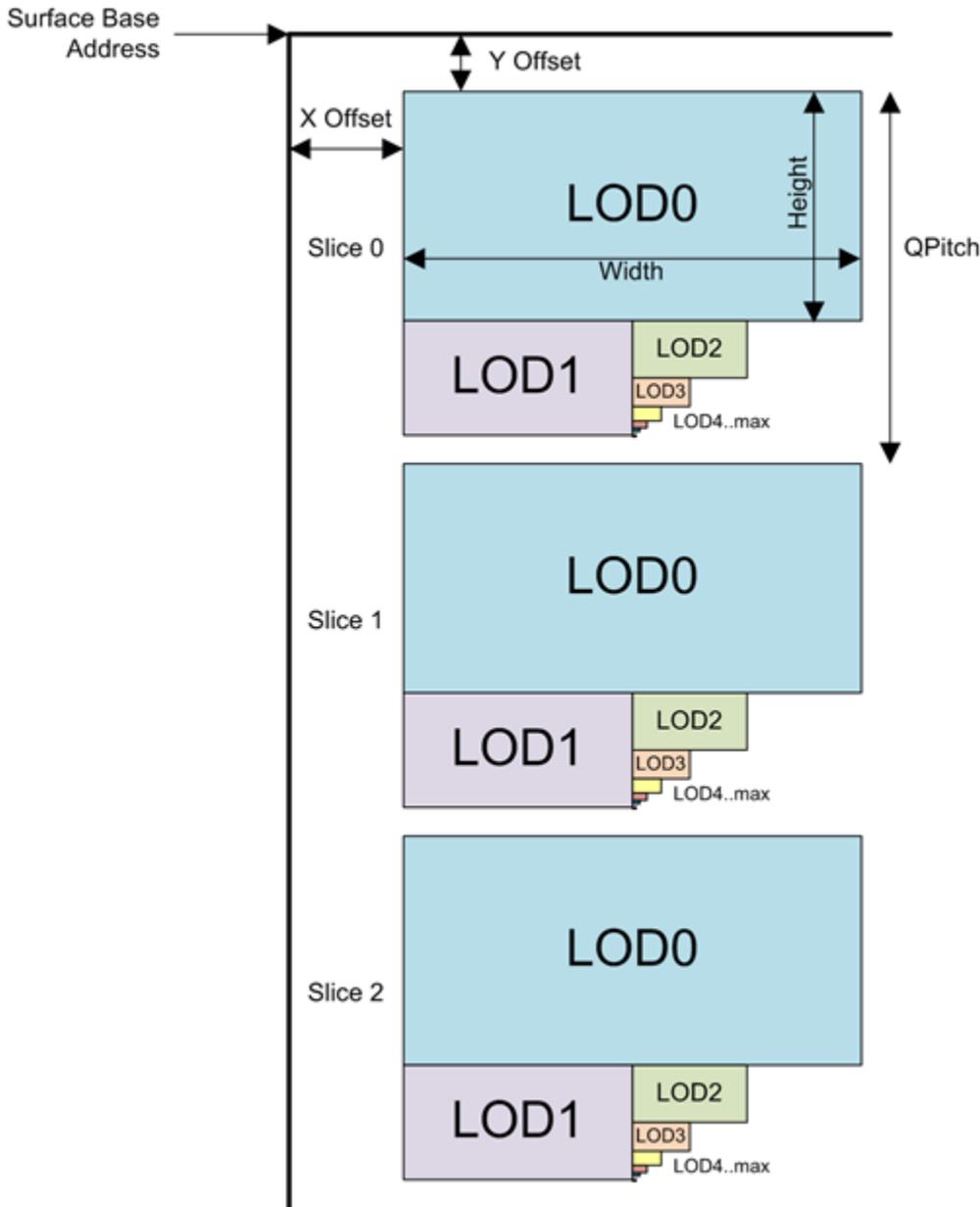
A surface can support multiple levels of details (LODs) or MIPs. The MIPCOUNT field in the RENDER_SURFACE_STATE defines how many MIPs a surface contains.

MIP0 or LOD0 is the largest, highest-detail MIP. The height, width and depth of this LOD is what is defined in the RENDER_SURFACE_STATE for that surface. Each subsequent

MIP is exactly one-half the height and width of the previous, making it 1/4th the size in memory.

The MIPs of a surface are laid out in memory using a 2-dimensional method as shown below. Volumetric and arrayed surfaces use multiple "slices" of this MIP layout, with each slice separated by QPITCH number of rows.

The diagram below shows many of the parameters of a 2D,2D Arrayed and 3D surface.



This 2-dimensional layout implies that there is padding required on the rows below LOD0 in order to ensure each row is the same number of texels.

If Tiling is enabled, then each MIP is laid out using one or more tiles. If TileYf or TileYs tiling is enabled (TR_MODE != NONE), then some of the MIPs may actually be stored in a MIPTail which fits in a single 64K or 4K tile. The layout above, then only applied to MIPs which are not packed in the MIP Tail.



Raw (Untyped) Buffers

Raw buffers also use the surface type of SURFTYPE_BUFFER, but the surface format is RAW. These buffers are one-dimensional. They are accessed with a single U parameter which is a byte offset into the buffer. Raw buffers are also supported only in linear memory.

The offset into the raw buffer is given directly by the U parameter.

`Offset = U`

Structured Buffers

A structured buffer is a surface type that is accessed by a 2-dimensional coordinate. It can be thought of as an array of structures, where each structure is a predefined number of DWords in size. The first coordinate (U) defines the array index, and the second coordinate (V) is a byte offset into the structure which must be a multiple of 4 (DWord-aligned). A structured buffer must be defined with **Surface Format RAW**.

The structured buffer has only one dimension programmed in SURFACE_STATE which indicates the array size. The byte offset dimension (V) is assumed to be bounded only by the **Surface Pitch**.

The two dimensional offset into the surface is defined directly by the U and V parameters. Structured buffers are linear.

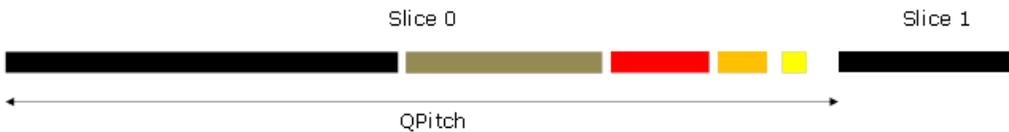
1D Surfaces

One-dimensional surfaces use a tiling mode of linear. Technically, they are not tiled resources, but the Tiled Resource Mode field in RENDER_SURFACE_STATE is still used to indicate the alignment requirements

for this linear surface (See 1D Alignment requirements for how 4K and 64KB Tiled Resource Modes impact alignment). Alternatively, a 1D surface can be defined as a 2D tiled surface (e.g. TileY or TileX) with

a height of 0.

Linear 1D surfaces are stored in a one-dimensional view of memory as follows:



Surface Pitch is ignored for 1D surfaces. **Surface QPitch** specifies the distance in pixels between array slices. QPitch should allow at least enough space for any mips that may be present.

A number of parameters are useful to determine where given pixels will be located on the 1D surface. First, the width for each LOD "L" is computed:

$$W_L = ((width >> L) > 0 ? width >> L : 1$$



Next, the aligned width parameter for each LOD “L” is computed. The “i” parameter is the horizontal alignment parameter set by a state field or defined as a constant, depending on the surface. The alignment parameter may change at one point in the mip chain based on **Mip Tail Start LOD**. The equation uses the I value that applies to the LOD being computed.

$$w_L = i * \text{ceil}\left(\frac{W_L}{i}\right)$$

Next, the offset to each LOD is determined. The offset has one dimension for 1D surfaces. The single element in the LOD_L vector is named $LODUL$.

$$\begin{aligned} LOD_0 &= (0) \\ LOD_1 &= (w_0) \\ LOD_2 &= (w_0 + w_1) \\ LOD_3 &= (w_0 + w_1 + w_2) \\ LOD_4 &= (w_0 + w_1 + w_2 + w_3) \\ &\dots \end{aligned}$$

Based on the above parameters and the U and R (pixel address and array index, respectively), and the bytes per pixel of the surface format (Bpp), the offset “u” in bytes from the base address of the surface is given by:

$$u = [(R * QPitch) + LODUL + U] * Bpp$$

The layout documented in this section does not apply to sampler 1D surfaces if the tile mode is set to TileY or TileW.

Tiling and Mip Tail for 1D Surfaces

If tiling is enabled and **Tiled Resource Mode** is set to TRMODE_NONE, the above sequence applies throughout the full range of LODs. For other settings of Tiled Resource Mode, the mip tail offset is given by the following, where S is the **Mip Tail Start LOD**:

$$LOD_S = (w_0 + w_1 + w_2 + w_3 + \dots + w_{S-1})$$

The mip tail exhibits a different arrangement than the rest of the surface. LODs are aligned to the left side of the space available.

The offsets *into the mip tail block* are given by the following table for each LOD in the mip tail. The offsets given here need to be added to the LOD_S offset computed earlier to obtain the offset into the surface LOD_L .

TRMODE_64KB LOD	TRMODE_4KB LOD	128 bpe	64 bpe	32 bpe	16 bpe	8 bpe
s		(2048)	(4096)	(8192)	(16384)	(32768)
s+1		(1024)	(2048)	(4096)	(8192)	(16384)
s+2		(512)	(1024)	(2048)	(4096)	(8192)
s+3		(256)	(512)	(1024)	(2048)	(4096)
s+4	s	(128)	(256)	(512)	(1024)	(2048)



TRMODE_64KB LOD	TRMODE_4KB LOD	128 bpe	64 bpe	32 bpe	16 bpe	8 bpe
s+5	s+1	(64)	(128)	(256)	(512)	(1024)
s+6	s+2	(48)	(96)	(192)	(384)	(768)
s+7	s+3	(32)	(64)	(128)	(256)	(512)
s+8	s+4	(28)	(56)	(112)	(224)	(448)
s+9	s+5	(24)	(48)	(96)	(192)	(384)
s+10	s+6	(20)	(40)	(80)	(160)	(320)
s+11	s+7	(16)	(32)	(64)	(128)	(256)
s+12	s+8	(12)	(24)	(48)	(96)	(192)
s+13	s+9	(8)	(16)	(32)	(64)	(128)
s+14	s+10	(4)	(8)	(16)	(32)	(64)
s+15	s+11	(0)	(0)	(0)	(0)	(0)

1D Alignment Requirements

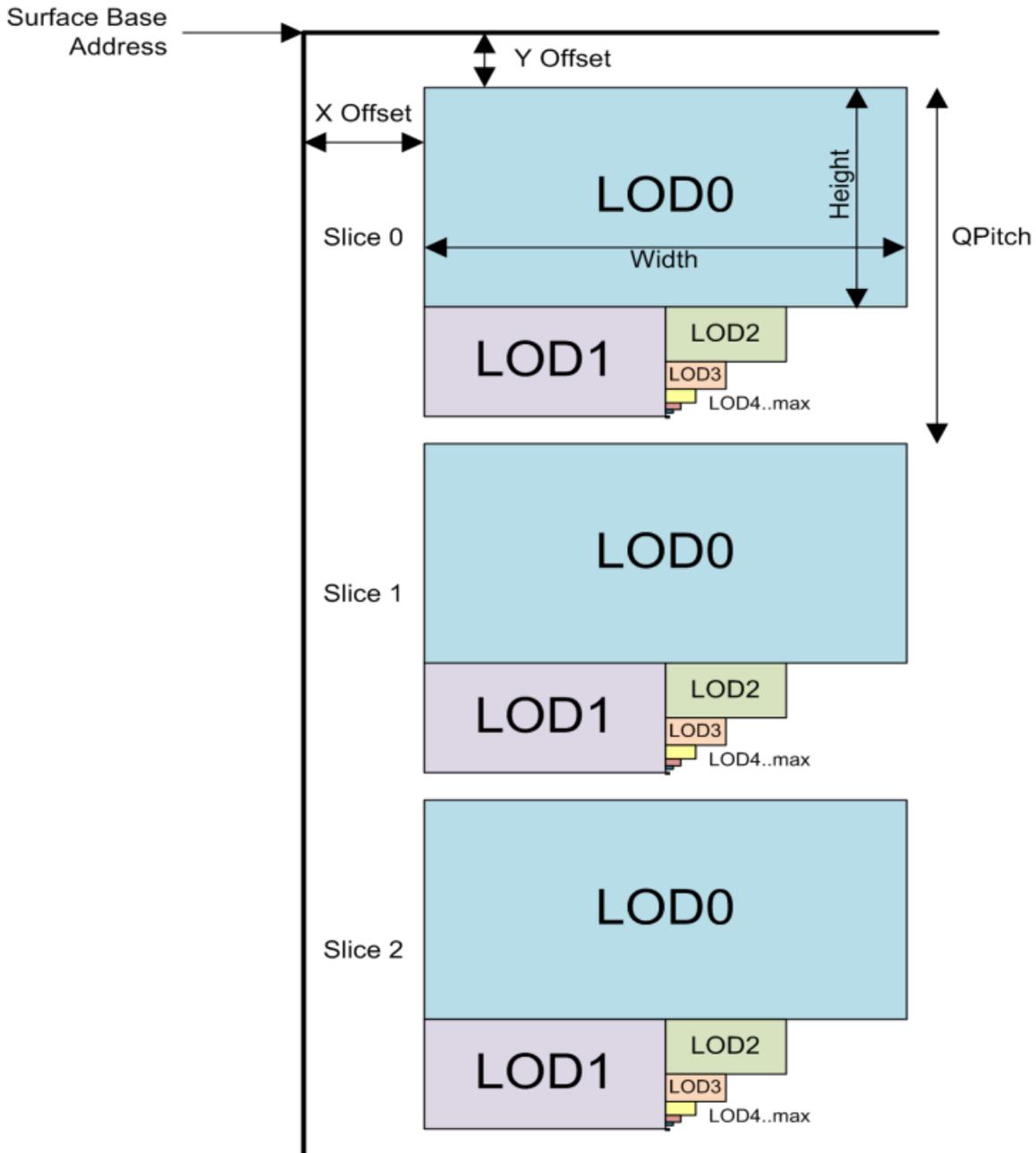
The horizontal alignment field in the RENDER_SURFACE_STATE are ignored for standard tiling formats (TRMODE = NONE). In the case of standard tiling formats the alignment requirements are fixed and are provided for by the tables below for 1D surfaces.

Tiled Resource Mode	Bits per Element	Horizontal Alignment
TRMODE_64KB	128	4096
	64	8192
	32	16384
	16	32768
	8	65536
TRMODE_4KB	128	256
	64	512
	32	1024
	16	2048
	8	4096
TRMODE_NONE	Any	64



2D Surfaces

2D surfaces represent two-dimensional bitmaps, which can also be mip-mapped and/or consist of array slices, effectively representing multiple 2D sub-surfaces within a single surface. The diagram below shows many of the parameters of a 2D surface or Arrayed 2D Surface and what they mean.



All surface parameters are defined in terms of texels (agnostic to the surface format).



Surface Pitch defines the distance in bytes between rows of the surface and is a function of the **Width** of LOD. **QPitch** specifies the distance in rows between array slices and is a function of the **Height**. **QPitch** should allow at least enough space for any Mips that may be present.

There can also be non-zero offsets (**X_Offset** and **Y_Offset**) defined from the base address which can be used to provide padding or provide an offset to a lower-detail LOD.

There are limitations to the physical size of an LOD in the sampler texture cache. An LOD must be aligned to a cache-line except for some special cases related to Planar YUV surfaces. In general, the cache-alignment restriction implies there is a minimum height for an LOD of 4 texels. So, LODs which are smaller than 4 high are padded. For tiled surfaces with **TR_MODE** != TR_NONE this restriction is not significant because the MIP tail will be used for smaller MIPs and the slots are a minimum of 64B. For non-tiled surface or surfaces where **TR_MODE** == **TR_NONE**, Mips smaller than 4 high start at the top of the region, and they are padded. This padding leads to a case where the smallest LOD starts "below" LOD1 vertically.

Calculating Texel Location

This section describes how the texel location is calculated once the Surface State and LOD are known. A number of parameters are useful to determine where given pixels are located on the 2D surface. The width (**W_L**) and height (**H_L**) for each LOD "L" is computed by the formula:

$$W_L = ((width \gg L) > 0 ? width \gg L : 1)$$

$$H_L = ((height \gg L) > 0 ? height \gg L : 1)$$

The LOD width and height for each subsequent LOD is one-half the previous LOD, with the minimum dimension being 1 texel. If the surface is multisampled and it is a depth or stencil surface or **Multisampled Surface Storage Format** in SURFACE_STATE is MSFMT_DEPTH_STENCIL, **W_L** and **H_L** must be adjusted as follows:

Number of Multisamples	WL =	HL =
2	ceiling(W _L / 2) * 4	H _L [no adjustment]
4	ceiling(W _L / 2) * 4	ceiling(H _L / 2) * 4
8	ceiling(W _L / 2) * 8	ceiling(H _L / 2) * 4
16	ceiling(W _L / 2) * 8	ceiling(H _L / 2) * 8

Next, aligned width, height, and depth parameters for each LOD "L" must be computed. The "i" and "j" parameters are horizontal and vertical alignment parameters set by state fields or defined as constants, depending on the surface. Depth has no alignment parameter (effectively it is 1).

The equation uses the i and j values that apply to the LOD being computed. The "p" and "q" parameters define the width and height in texels of the compression block for compressed surface formats. Both p and q are defined to equal 1 for uncompressed surface formats.



$$w_L = i * p * \text{ceil}\left(\frac{W_L}{i * p}\right)$$

$$h_L = j * q * \text{ceil}\left(\frac{H_L}{j * q}\right)$$

Once the height (h_i) and width (w_i) of each LOD is computed, the offset to each LOD can be determined. The offset is a vector with two dimensions. The elements in the LOD_L vector are named in order LODU_L , LODV_L .

LOD offset computation for **TR_MODE** == TR_NONE or when $L < \text{Mip Tail Start LOD}$:

$$\text{LOD}_0 = (0,0)$$

$$\text{LOD}_1 = (0, h_0)$$

$$\text{LOD}_2 = (w_1, h_0)$$

$$\text{LOD}_3 = (w_1, h_0 + h_2)$$

$$\text{LOD}_4 = (w_1, h_0 + h_2 + h_3)$$

...

$$\text{LOD}_N = (w_1, h_0 + h_2 + h_3 \dots + h_{N-1})$$

Where $N = \text{MIP_COUNT}$ for the surface. As noted previous in this section, the value of $h_2 + h_3 \dots + h_{N-1}$ may be greater than h_1 due to alignment requirements.

Based on the above parameters and the U, V, and R (two dimensional pixel address U/V and array index R), and the *bytes* per pixel of the surface format (Bpp), the offsets u in bytes and v in rows are given by:

$$u = (U + \text{LODU}_L) * \text{Bpp}$$

$$v = (R * \text{QPitch}) + \text{LODV}_L + V$$

For a description of how the Mip Tail is laid out and offsets into the Mip Tail are calculated see the sub-section on 2D Surface Layout for Mip Tails.

The two dimensional offset into the surface (for non-MipTail cases) is defined by the u and v values computed above. The lower virtual address bits are determined by the following table, based on the bits of u and v . An *element* is defined as a pixel for uncompressed surface formats and a compression block for compressed surface formats. Empty bit positions indicate that the bit is not part of the tile swizzle and is filled in with equations given next (note that linear mode has all bits empty—there is no swizzling in linear mode).



Tile Mode	Bits per Element	TileID constants		Virtual Address Bits															
		Cv	Cu	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TileYS	64 & 128	6	10	u9	v5	u8	v4	u7	v3	u6	v2	u5	u4	v1	v0	u3	u2	u1	u0
	16 & 32	7	9	u8	v6	u7	v5	u6	v4	u5	v3	u4	v2	v1	v0	u3	u2	u1	u0
	8	8	8	u7	v7	u6	v6	u5	v5	u4	v4	v3	v2	v1	v0	u3	u2	u1	u0
TileYF	64 & 128	4	8					u7	v3	u6	v2	u5	u4	v1	v0	u3	u2	u1	u0
	16 & 32	5	7					u6	v4	u5	v3	u4	v2	v1	v0	u3	u2	u1	u0
	8	6	6					u5	v5	u4	v4	v3	v2	v1	v0	u3	u2	u1	u0
TileY	all	5	7					u6	u5	u4	v4	v3	v2	v1	v0	u3	u2	u1	u0
TileX	all	3	9					v2	v1	v0	u8	u7	u6	u5	u4	u3	u2	u1	u0
TileW	all	6	6					u5	u4	u3	v5	v4	v3	v2	u2	v1	u1	v0	u0
Linear	all	0	0																

The TileID fills the upper bits of the virtual address (starting with the lowest blank bit in the above table):

$$\text{TileID} = (v \gg Cv) * (\text{Pitch} \gg Cu) + (u \gg Cu)$$

Where Pitch is the **Surface_Pitch** field from RENDER_SURFACE_STATE.

Note: Multisampled CMS and UMS surfaces use a modified address bit swizzling table rather than the one above. Refer to the *Multisampled2D Surfaces* section for details.

Tiling and Mip Tails for 2D Surfaces

When surface is Tiled (Tile_Mode=YMAJOR) and Tile Resources are enabled (TR_MODE != TR_NONE), a 2D surface can contain a Mip Tail for smaller Mip sizes.

When LOD (L) is less than the **Mip Tail Start LOD** (S) declared in the Surface State the offset to the start of LOD is calculated as shown above.

If the LOD is greater than or equal to **Mip Tail Start LOD** field in the surface state then the MIP Tail layout below is used..

For tiled resources, the mip tail offset is given by the following, where s is the Mip Tail Start LOD:



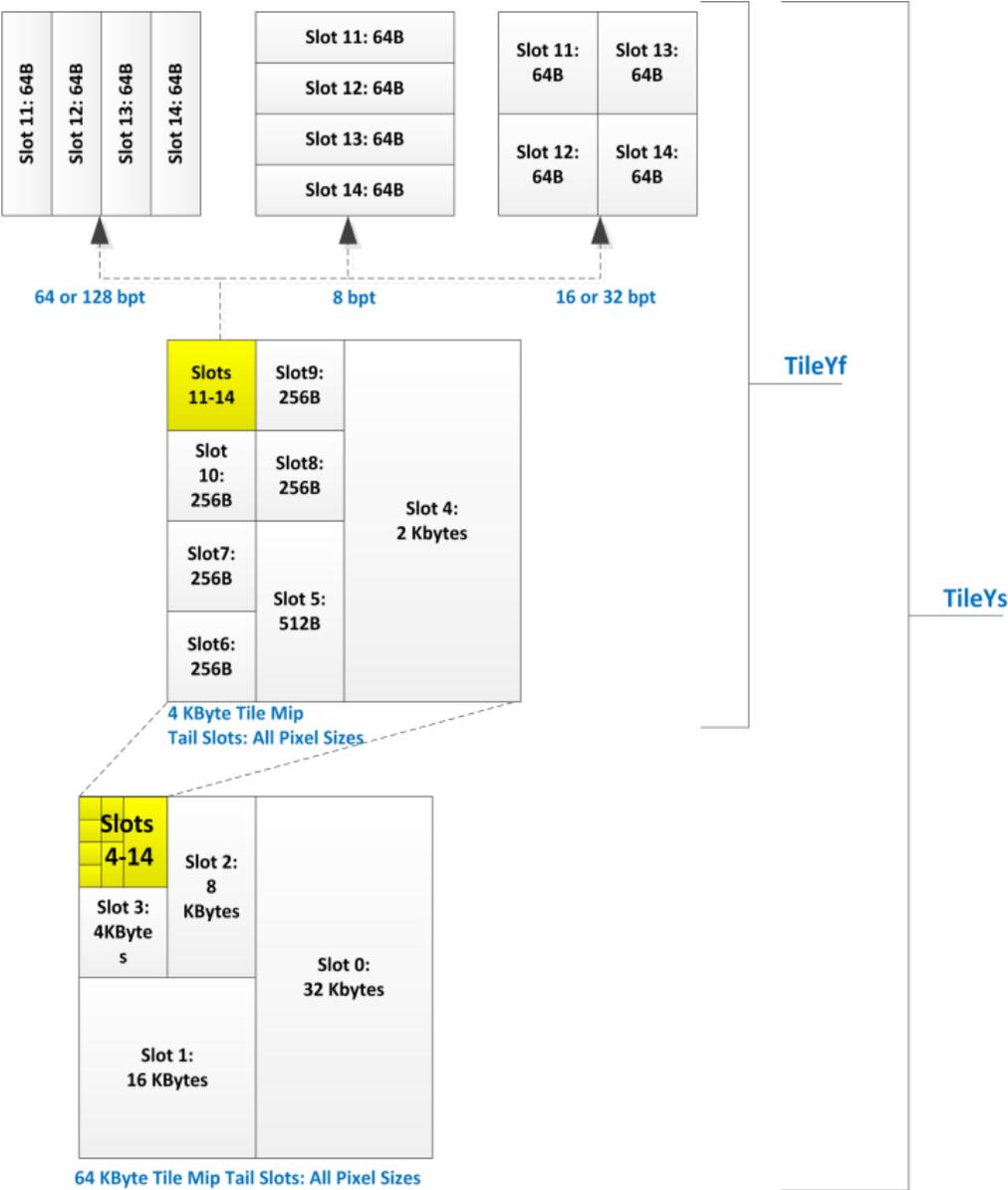
Memory Views

$$LOD_s = (w_1, h_0 + h_2 + h_3 + \dots + h_{s-1})$$

The LOD's in the Mip Tail are arranged differently than the other LOD's.

The diagram below shows the 64KB TileYS Mip Tail layout of LODs within it, with "slots" indicating the LOD contained within (slot 0 corresponds to LOD_s above). LOD's are aligned to the upper left corner of the space available. The block marked "Slots 4-14" is a 4KB tile arrangement as shown. Within this 4KB tile slots 11 thru 14 are arranged differently depending on the number bits per texel (bpt).

A TileYf (4KByte) Mip Tail will start with the 4KByte tile shown, but the slots will be renumbered to start at Slot0 rather than Slot4. The layout of slots 11 through 14 remain the same. Note that Slots 12-14 are NOT 256-Byte aligned which is not compliant with the standard MIP Tail layout. These slots are not supported for Standard Tiling.





The offsets *into the Mip Tail tile* are given by the following table for each LOD in the Mip tail. Each entry in the table is a horizontal (M_U) and vertical (M_V) position (in texels) from the upper left corner of the Mip Tail. If $LOD \geq S$ (starting LOD for MIP Tail), then these Mip Tail offsets must be added to the LOD_U_L and LOD_V_L calculated above.

Note that many of the higher LODs are not possible given surface size constraints, but they are listed here for reference. The offsets given here need to be added to the LODs offset computed earlier to obtain the offset into the surface LOD_L .

TileYS LOD					TileYF LOD	128 bpe	64 bpe	32 bpe	16 bpe	8 bpe
1x	2x	4x	8x	16x		(M_U, M_V)				
s						(32,0)	(64,0)	(64,0)	(128,0)	(128,0)
s+1	s					(0,32)	(0,32)	(0,64)	(0,64)	(0,128)
s+2	s+1	s				(16,0)	(32,0)	(32,0)	(64,0)	(64,0)
s+3	s+2	s+1	s			(0,16)	(0,16)	(0,32)	(0,32)	(0,64)
s+4	s+3	s+2	s+1	s	s	(8,0)	(16,0)	(16,0)	(32,0)	(32,0)
s+5	s+4	s+3	s+2	s+1	s+1	(4, 8)	(8, 8)	(8, 16)	(16, 16)	(16, 32)
s+6	s+5	s+4	s+3	s+2	s+2	(0, 12)	(0, 12)	(0, 24)	(0, 24)	(0, 48)
s+7	s+6	s+5	s+4	s+3	s+3	(0, 8)	(0, 8)	(0, 16)	(0, 16)	(0, 32)
s+8	s+7	s+6	s+5	s+4	s+4	(4, 4)	(8, 4)	(8, 8)	(16, 8)	(16, 16)
s+9	s+8	s+7	s+6	s+5	s+5	(4, 0)	(8, 0)	(8, 0)	(16, 0)	(16, 0)
s+10	s+9	s+8	s+7	s+6	s+6	(0, 4)	(0, 4)	(0, 8)	(0, 8)	(0, 16)
s+11	s+10	s+9	s+8	s+7	s+7	(3, 0)	(6, 0)	(4, 4)	(8, 4)	(0, 12)
s+12	s+11	s+10	s+9	s+8	s+8	(2, 0)	(4, 0)	(4, 0)	(8, 0)	(0, 8)
s+13	s+12	s+11	s+10	s+9	s+9	(1, 0)	(2, 0)	(0, 4)	(0, 4)	(0, 4)
s+14	s+13	s+12	s+11	s+10	s+10	(0, 0)	(0, 0)	(0, 0)	(0, 0)	(0, 0)

If the LOD is located in the MIP Tail then the equation for calculating the byte positions for u and v become:

$$u = (U + LODU_s + M_U) * Bpp$$

$$v = (R * QPitch) + LODV_s + M_V + V$$

where M_U and M_V are the offset parameters from the table above for the given slot in the MIP Tail.

Programming Note	
Context:	Lossless Compression and MIP Tail
Lossless compression must not be used on surfaces which have MIP Tail which contains MIPs for Slots greater than 11.	



2D/CUBE Alignment Requirement

The vertical and horizontal alignment fields in the RENDER_SURFACE_STATE are ignored for standard tiling formats (TRMODE = NONE). In the case of standard tiling formats the alignment requirements are fixed and are provided for by the tables below for 2D and CUBE surface.

Tile Mode	Bits per Element	Horizontal Alignment	Vertical Alignment
TileYS	128	64	64
	64	128	64
	32	128	128
	16	256	128
	8	256	256
TileYF	128	16	16
	64	32	16
	32	32	32
	16	64	32
	8	64	64

For MSFMT_MSS type multi-sampled TileYS surfaces, the alignments given above must be divided by the appropriate value from the table below.

Number of Multisamples	Horizontal Alignment is divided by	Vertical Alignment is divided by
2	2	1
4	2	2
8	4	2
16	4	4

Multisampled 2D Surfaces

There are three types of multisampled surface layouts designated as follows:

- **IMS** Interleaved Multisampled Surface



- **CMS** Compressed Multisampled Surface
- **UMS** Uncompressed Multisampled Surface

These surface layouts are described in the following sections.

Interleaved Multisampled Surfaces

IMS surfaces are supported in all generations for depth and stencil surfaces. These surfaces contain the samples in an interleaved fashion, with the underlying surface in memory having a height and width that is larger than the non-multisampled surface as follows:

- 4x MSAA: 2x width and 2x height of non-multisampled surface.
- 8x MSAA: 4x width and 2x height of non-multisampled surface.
- 16x MSAA: 4x width and 4x height of the non-multisampled surface.

When sampling from an IMS surface (e.g. Id2dms), the coordinates are automatically scaled to handle the increased physical size of the map.

Compressed Multisampled Surfaces

Multisampled render targets can be compressed. If **Auxiliary Surface Mode** in SURFACE_STATE is set to AUX_CCS, hardware handles the compression using a software-invisible algorithm. However, performance optimizations in the multisample resolve kernel using the sampling engine are possible if the internal format of these surfaces is understood by software. This section documents the formats of the Multisample Control Surface (MCS) and Multisample Surface (MSS).

MCS Surface

The MCS surface consists of one element per pixel, with the element size being an 8-bit unsigned integer value for 4x multisampled surfaces, a 32-bit unsigned integer value for 8x multisampled surfaces and a 64-bit unsigned integer value for 16x multisampled surfaces. Each field within the element indicates which sample slice (SS) the sample resides on.

2x MCS

The 2x MCS is 8 bits per pixel. The 8 bits are encoded as follows:

7:2	1	0
reserved	sample 1 SS	sample 0 SS

Each 1-bit field indicates which sample slice (SS) the sample's color value is stored. An MCS value of 0x00 indicates that both samples are stored in sample slice 0 (thus have the same color). This is the fully compressed case. An MCS value of 0x03 indicates that all samples in the pixel are in the clear state, and none of the sample slices are valid. The pixel's color must be replaced with the surface's clear value.

4x MCS

The 4x MCS is 8 bits per pixel. The 8 bits are encoded as follows:



7:6	5:4	3:2	1:0
sample 3 SS	sample 2 SS	sample 1 SS	sample 0 SS

Each 2-bit field indicates which sample slice (SS) the sample's color value is stored. An MCS value of 0x00 indicates that all four samples are stored in sample slice 0 (thus all have the same color). This is the fully compressed case. An MCS value of 0xff indicates that all samples in the pixel are in the clear state, and none of the sample slices are valid. The pixel's color must be replaced with the surface's clear value. See the section below on Clear Pixel Conditions for additional encoding information.

8x MCS

Extending the mechanism used for the 4x MCS to 8x requires 3 bits per sample times 8 samples, or 24 bits per pixel. The 24-bit MCS value per pixel is placed in a 32-bit footprint, with the upper 8 bits unused as shown below. See the section below on Clear Pixel Conditions for additional encoding information.

31:24	23:21	20:18	17:15	14:12	11:9	8:6	5:3	2:0
reserved (MBZ)	sample 7 SS	sample 6 SS	sample 5 SS	sample 4 SS	sample 3 SS	sample 2 SS	sample 1 SS	sample 0 SS

16x MCS

The 16x MCS is 64 bits per pixel. The 64 bits are encoded as follows:

63:60	59:56	55:52	51:48	47:44	43:40	39:36	35:32
sample 15 SS	sample 14 SS	sample 13 SS	sample 12 SS	sample 11 SS	sample 10 SS	sample 9 SS	sample 8 SS

31:28	27:24	23:20	19:16	15:12	11:8	7:4	3:0
sample 7 SS	sample 6 SS	sample 5 SS	sample 4 SS	sample 3 SS	sample 2 SS	sample 1 SS	sample 0 SS

Other than this, the 16x algorithm is the same as the 8x algorithm. The MCS value indicating clear state is 0xffffffff_ffffffff. See the section below on Clear Pixel Conditions for additional encoding information.

Clear Pixel Conditions

The MCS format allows for the encoding of clear value for one or more planes of the multi-sampled surface. A value of all 1's for defined MCS bits indicates that all planes of the multi-sampled surface are clear. For example, a value of 0x3 for 2X MSAA MCS byte means that both planes of the pixel are clear. Likewise a value of 0xff for X4, 0xffffffff for X8 and 0xffffffff_ffffffff for X16 MSAA means that all planes of the pixel are clear.

In the case where not all planes are clear, but at least 2 planes are clear the encoding of the MCS given above is changed. If the MCS value for plane 0 is non-zero, then all planes which are at all 1's are clear and all other planes are referencing the plane indicated by their respective MCS value minus 1. For example, a 4X MSAA MCS value of 01 10 01 11 means that MCS 0 and 2 are referencing plane 0, and MCS 1 is referencing plane 1, and MCS 3 is clear.

MSS Surface



The physical MSS surface is stored identically to a 2D array surface, with the height and width matching the pixel dimensions of the logical multisampled surface. The number of array slices in the physical surface is 2, 4, 8, or 16 times that of the logical surface (depending on the number of multisamples). Sample slices belonging to the same logical surface array slice are stored in adjacent physical slices. The sampling engine Id2dss message gives direct access to a specific sample slice.

Tiling for CMS and UMS Surfaces

Multisampled CMS and UMS use a modified table from non-multisampled 2D surfaces.

TileY, TileX, TileW, and Linear: Treat as 2D array, with the array index “R” modified as follows. “n” is the number of multisamples, “ss” is the sample slice index with range 0..n-1.

$$R(new) = (R(old) \ll \log_2(n)) | ss$$

TileYS: In addition to u and v, the sample slice index “ss” is included in the address swizzling according to the following table. Because of this, the mip tail holds one less LOD for each successive number of multisamples. Refer to the mip tail table in the previous section for behavior of the mip tail for each number of multisamples.

Number of Multisamples	Bits per Element	TileID constants		Virtual Address Bits									
		Cv	Cu	15	14	13	12	11	10	9	8	7	6
2x	64 & 128	6	9	ss0	v5	u8	v4	u7	v3	u6	v2	u5	u4
	16 & 32	7	8	ss0	v6	u7	v5	u6	v4	u5	v3	u4	v2
	8	8	7	ss0	v7	u6	v6	u5	v5	u4	v4	v3	v2
4x	64 & 128	5	9	ss1	ss0	u8	v4	u7	v3	u6	v2	u5	u4
	16 & 32	6	8	ss1	ss0	u7	v5	u6	v4	u5	v3	u4	v2
	8	7	7	ss1	ss0	u6	v6	u5	v5	u4	v4	v3	v2
8x	64 & 128	5	8	ss2	ss1	ss0	v4	u7	v3	u6	v2	u5	u4
	16 & 32	6	7	ss2	ss1	ss0	v5	u6	v4	u5	v3	u4	v2
	8	7	6	ss2	ss1	ss0	v6	u5	v5	u4	v4	v3	v2
16x	64 & 128	4	8	ss3	ss2	ss1	ss0	u7	v3	u6	v2	u5	u4
	16 & 32	5	7	ss3	ss2	ss1	ss0	u6	v4	u5	v3	u4	v2
	8	6	6	ss3	ss2	ss1	ss0	u5	v5	u4	v4	v3	v2

Note that Cv and Cu are also different that the values for non-multisampled 2D surfaces.

Uncompressed Multisampled Surfaces

UMS surfaces similar to CMS, except that the **Auxiliary Surface Mode** is set to AUX_NONE, meaning that there is no MCS surface. UMS contains only an MSS surface, where each sample is stored on its sample slice (SS) of the same index.



Quilted Textures

A quilted texture is a 2D texture made up of quilt slices, each of which is a portion of the surface up to 16k x 16k texels in size. The quilt slices themselves are organized in a matrix up to 32 x 32. "Quilt Width" and "Quilt Height" fields indicate the dimensions of the surface in quilt slices. "Height" and "Width" fields indicate the size of each quilt slice in texels. The total size of the quilted texture can be up to 512k x 512k texels.

In addition, arrays of quilted textures are supported. The total number of array slices is limited to 2048 / (QuiltWidth * QuiltHeight).

A surface is defined as a "Quilted Texture" if either the "Quilt Width" or "Quilt Height" field in SURFACE_STATE is nonzero. A quilted texture is stored in the storage format as a 2D array, with each quilt square occupying one array slice. The following equation indicates how the array slice is computed from the Qx, Qy, and R parameters, where Qx and Qy are the quilt slice coordinates and R is the array index.

$$\text{ArraySliceIndex} = (R * \text{QuiltWidth} * \text{QuiltHeight}) + Qy * \text{QuiltWidth} + Qx$$

Quilted textures do NOT support wrapping. U and V coordinates must be in the range of [0.0,1.0).

Quilted textures can only be supported on tiled surfaces (e.g. TileY, TileYs, TileYf).

Cube Surfaces

The 3D Pipeline supports *cubic environment maps*, conceptually arranged as a cube surrounding the origin of a 3D coordinate system aligned to the cube faces. These maps can be used to supply texel (color/alpha) data of the environment in any direction from the enclosed origin, where the direction is supplied as a 3D "vector" texture coordinate. These cube maps can also be mipmapped.

Each texture map level is represented as a group of six, square *cube face* texture surfaces. The faces are identified by their relationship to the 3D texture coordinate system. The subsections below describe the cube maps as described at the API as well as the memory layout dictated by the hardware.

The diagram below describes the cube map faces as they are defined at the DirectX API. It shows the axes on the faces as they would be seen from the inside (at the origin).

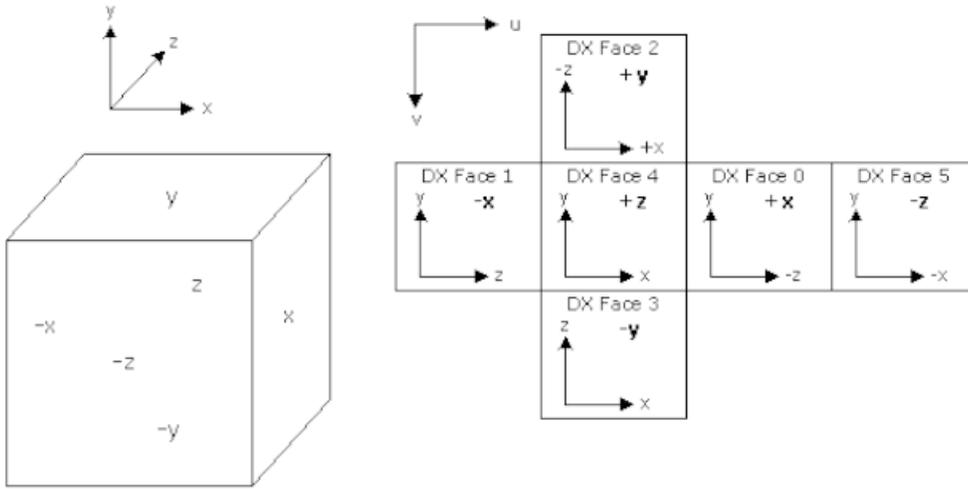
Programming Note	
Context:	Cube Maps and Tiling
Cube Maps with linear (non-tiled) layout are allowed ONLY with Texture Coordinate Mode of TEXCOORDMODE_CUBE or TEXCOORDMODE_CLAMP.	

The origin of the U,V texel grid is at the top left corner of each face.

This will be looking directly at face 4, the +z -face. Y is up by default.



DirectX Cube Map Definition



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Each face has a corresponding face identifier "f" as indicated in the following table:

face	face identifier "f"
+x	0
-x	1
+y	2
-y	3
+z	4
-z	5

A cube surface is stored in memory the same as a 2D array, with the face identifier "f" and array index "ai" being transformed into the "R" coordinate used in storing 2D arrays using the following equation:

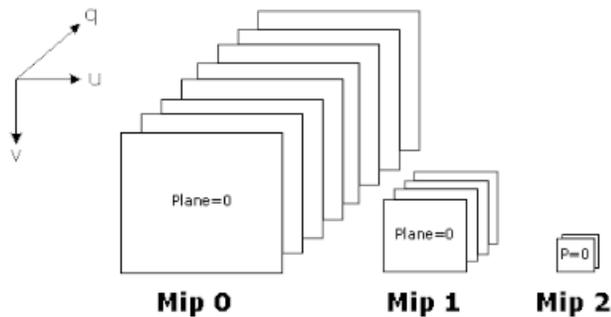
$$R = (ai * 6) + f$$

Refer to the "2D Surfaces" section for details on how 2D arrays are stored.

3D Surfaces

Multiple texture map surfaces (and their respective mipmap chains) can be arranged into a structure known as a Texture3D (volume) texture. A volume texture map consists of many *planes* of 2D texture maps. See *Sampler* for a description of how volume textures are used.

Volume Texture Map



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Surface Pitch defines the distance in bytes between rows of the surface. **Surface QPitch** specifies the distance in rows between R-slices. QPitch should allow at least enough space for any mips that may be present.

A number of parameters are useful to determine where given pixels are located on the 3D surface. First, the width, height, and depth for each LOD "L" is computed:

$$W_L = ((width \gg L) > 0 ? width \gg L : 1)$$

$$H_L = ((height \gg L) > 0 ? height \gg L : 1)$$

$$D_L = ((depth \gg L) > 0 ? depth \gg L : 1)$$

Next, aligned width, height, and depth parameters for each LOD "L" are computed. The "i", "j", and "k" parameters are the horizontal, vertical, and depth alignment parameters set by state fields or defined as constants. The alignment parameters may change at one point in the mip chain based on **Mip Tail Start LOD**. The equation uses the i/j values that apply to the LOD being computed. The "p", "q", and "s" parameters define the width, height, and depth in texels of the compression block for compressed surface formats. These are all defined to equal 1 for uncompressed surface formats.

$$w_L = i * \text{ceil}\left(\frac{W_L}{i}\right)$$

$$h_L = j * \text{ceil}\left(\frac{H_L}{j}\right)$$

$$d_L = D_L$$

$$d_L = k * s * \text{ceil}\left(\frac{D_L}{k * s}\right)$$

Next, the offset to each LOD is determined. The offset is a vector with three dimensions. The elements in the LOD_L vector are named in order $LODU_L$, $LODV_L$, $LODR_L$.



LOD offset computation for **Tiled Resource Mode** == TR_NONE or when L < **Mip Tail Start LOD**:

$$\begin{aligned}
 LOD_0 &= (0,0,0) \\
 LOD_1 &= (0, h_0, 0) \\
 LOD_2 &= (w_1, h_0, 0) \\
 LOD_3 &= (w_1, h_0 + h_2, 0) \\
 LOD_4 &= (w_1, h_0 + h_2 + h_3, 0) \\
 &\dots
 \end{aligned}$$

For the Primary Surface

Based on the above parameters and the U, V, and R (three dimensional pixel address), and the bytes per pixel of the surface format (Bpp), the offsets u in bytes, v in rows, and r in slices are given by:

$$\begin{aligned}
 u &= [U + LODUL] * Bpp \\
 v &= LODVL + V \\
 r &= LODRL + R
 \end{aligned}$$

The three dimensional offset into the surface is defined by the u, v, and r values computed above. The lower virtual address bits are determined by the following table, based on the bits of u, v, and r. An *element* is defined as a pixel for uncompressed surface formats and a compression block for compressed surface formats.

Empty bit positions indicate that the bit is not part of the tile swizzle and is filled in with the equations given next (note that linear mode has all bits empty—there is no swizzling in linear mode).

The TileID fills the upper bits of the virtual address (starting with the lowest blank bit in the above table):

$$\text{TileID} = [(r \gg Cr) * (QPitch \gg Cv) + (v \gg Cv)] * (Pitch \gg Cu) + (u \gg Cu)$$

For the CCS Auxiliary Surface

The CCS is stored differently for the 3D surface type. CCS supports only TileY tile mode, which does not have a three dimensional offset. Instead, the 3D CCS follows a scheme similar to 2D surfaces. Based on the above parameters and the U, V, and R (three dimensional pixel address, shifted to adjust for control block size in bytes), the offsets u in bytes and v in rows are given by:

$$\begin{aligned}
 u &= [U + LODUL] \\
 v &= (R * QPitch) + LODVL + V
 \end{aligned}$$

The two dimensional offset into the surface is defined by the u and v values computed above. The lower virtual address bits are determined by the following table, based on the bits of u and v.

Empty bit positions indicate that the bit is not part of the tile swizzle and is filled in with equations given next.

Tile Mode	Bits per Element	TileID constants			Virtual Address Bits																
		Cr	Cv	Cu	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
TileY	5	7								u6	u5	u4	v4	v3	v2	v1	v0	u3	u2	u1	u0

The TileID fills the upper bits of the virtual address (starting with the lowest blank bit in the above table):

$$\text{TileID} = (v \gg Cv) * (Pitch \gg Cu) + (u \gg Cu)$$

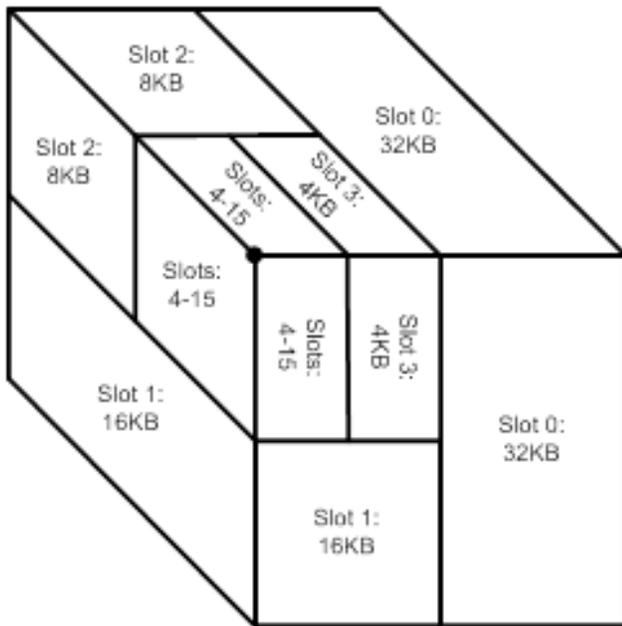


Tiling and Mip Tails for 3D Surfaces

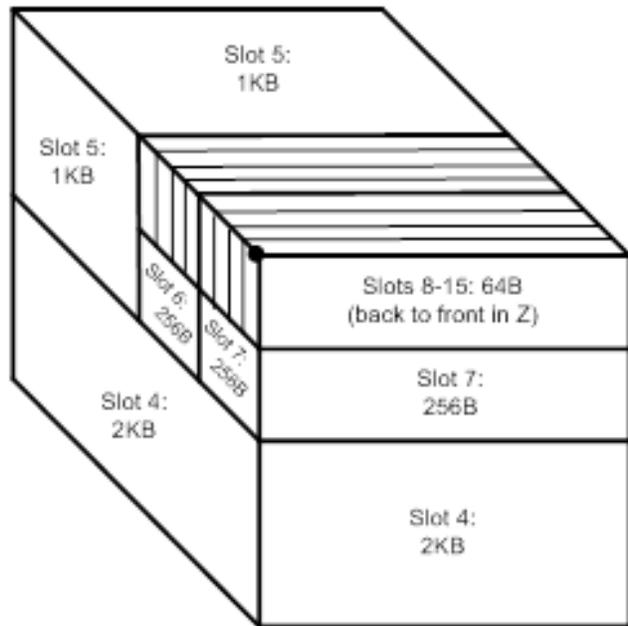
For tiled surfaces where Tiled Resource Mode \neq TR_NONE, the surface may contain a mip tail. The Mip tail offset is given by the following, where S is the Mip Tail Start LOD:

$$\text{LOD}_S = (w_1, h_0 + h_2 + h_3 + \dots + h_{S-1}, 0)$$

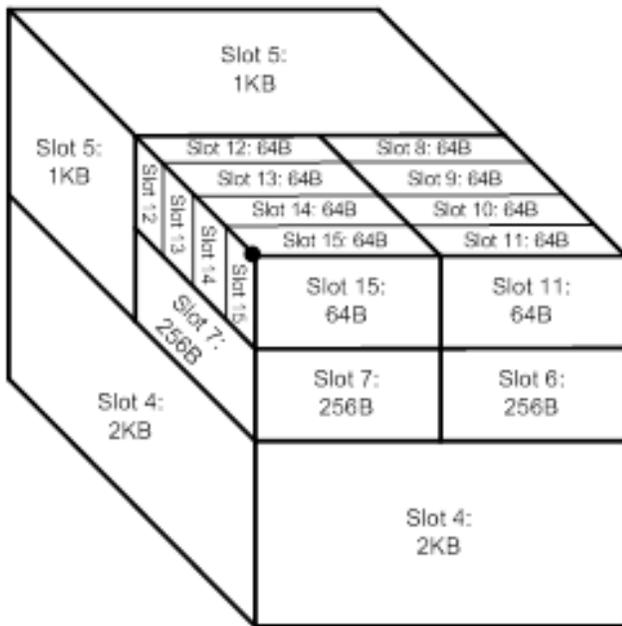
The mip tail exhibits a different arrangement than the rest of the surface. The diagram below shows the 64KB TileYS mip tail and the arrangement of LODs within it, with "slots" indicating the LOD contained within (slot 0 corresponds to LOD s). LODs are aligned to the front upper left corner of the space available. The block marked "Slots 4-15" contains one of the 4KB tile arrangements within, depending on the surface format bits per element. For TileYF, only the 4KB tile exists, with 4 subtracted from each slot number.



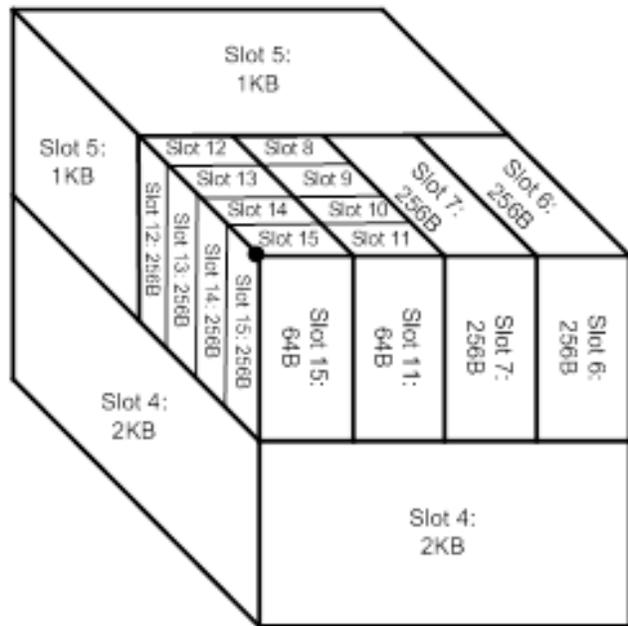
64KB Tile Mip Tail Slots:
All Pixel Depths



4KB Tile Mip Tail Slots:
8-bit & 16-bit Pixels



4KB Tile Mip Tail Slots:
32-bit Pixels



4KB Tile Mip Tail Slots:
64-bit & 128-bit Pixels

The offsets into the mip tail tile are given by the following table for each LOD in the mip tail. Note that many of the higher LODs are not possible given surface size constraints, but they are listed here for reference. The offsets given here need to be added to the LODs offset computed earlier to obtain the offset into the surface LOD.



TileYS LOD	TileYF LOD	128 bpe	64 bpe	32 bpe	16 bpe	8 bpe
s		(8, 0, 0)	(16, 0, 0)	(16, 0, 0)	(16, 0, 0)	(32, 0, 0)
s+1		(0, 8, 0)	(0, 8, 0)	(0, 16, 0)	(0, 16, 0)	(0, 16, 0)
s+2		(0, 0, 8)	(0, 0, 8)	(0, 0, 8)	(0, 0, 16)	(0, 0, 16)
s+3		(4, 0, 0)	(8, 0, 0)	(8, 0, 0)	(8, 0, 0)	(16, 0, 0)
s+4	s	(0, 4, 0)	(0, 4, 0)	(0, 8, 0)	(0, 8, 0)	(0, 8, 0)
s+5	s+1	(0, 0, 4)	(0, 0, 4)	(0, 0, 4)	(0, 0, 8)	(0, 0, 8)
s+6	s+2	(3, 0, 0)	(6, 0, 0)	(4, 4, 0)	(0, 4, 4)	(0, 4, 4)
s+7	s+3	(2, 0, 0)	(4, 0, 0)	(0, 4, 0)	(0, 4, 0)	(0, 4, 0)
s+8	s+4	(1, 0, 3)	(2, 0, 3)	(4, 0, 3)	(0, 0, 7)	(0, 0, 7)
s+9	s+5	(1, 0, 2)	(2, 0, 2)	(4, 0, 2)	(0, 0, 6)	(0, 0, 6)
s+10	s+6	(1, 0, 1)	(2, 0, 1)	(4, 0, 1)	(0, 0, 5)	(0, 0, 5)
s+11	s+7	(1, 0, 0)	(2, 0, 0)	(4, 0, 0)	(0, 0, 4)	(0, 0, 4)
s+12	s+8	(0, 0, 3)	(0, 0, 3)	(0, 0, 3)	(0, 0, 3)	(0, 0, 3)
s+13	s+9	(0, 0, 2)	(0, 0, 2)	(0, 0, 2)	(0, 0, 2)	(0, 0, 2)
s+14	s+10	(0, 0, 1)	(0, 0, 1)	(0, 0, 1)	(0, 0, 1)	(0, 0, 1)
s+15	s+11	(0, 0, 0)	(0, 0, 0)	(0, 0, 0)	(0, 0, 0)	(0, 0, 0)

3D Alignment Requirements

The vertical and horizontal alignment fields in the RENDER_SURFACE_STATE are ignored for standard tiling formats (TRMODE = NONE). In the case of standard tiling formats the alignment requirements are fixed and are provided for by the tables below for 3D (volumetric) surfaces.

Tile Mode	Bits per Element	Horizontal Alignment	Vertical Alignment	Depth Alignment
TileYS	128	16	16	16
	64	32	16	16
	32	32	32	16
	16	32	32	32
	8	64	32	32
TileYF	128	4	8	8
	64	8	8	8
	32	8	16	8



Tile Mode	Bits per Element	Horizontal Alignment	Vertical Alignment	Depth Alignment
	16	8	16	16
	8	16	16	16

Surface Padding Requirements

This section covers the requirements for padding around surfaces stored in memory, as there are cases where the device will overfetch beyond the bounds of the surface due to implementation of caches and other hardware structures.

Alignment Unit Size

This section documents the alignment parameters *i* and *j* to use, depending on the surface.

Alignment Parameters

Surface Defined By	Surface Format	Alignment Unit Width “ <i>i</i> ”	Alignment Unit Height “ <i>j</i> ”
3DSTATE_DEPTH_BUFFER	D16_UNORM	8	4
	not D16_UNORM	4	4
3DSTATE_STENCIL_BUFFER	N/A	8	8
SURFACE_STATE	BC*, ETC*, EAC*	4	4
	FXT1	8	4
	all others	set by Surface Horizontal Alignment	set by Surface Vertical Alignment

Surface Defined By	Surface Format	Alignment Unit Width “ <i>i</i> ”	Alignment Unit Height “ <i>j</i> ”
SURFACE_STATE	ASTC	Value of ASTC_2DBlockWidth (4, 5, 6, 8, 10, or 12)	ASTC_2DBlockHeight*4



Sampling Engine Surfaces

The sampling engine accesses texels outside of the surface if they are contained in the same cache line as texels that are within the surface. These texels will not participate in any calculation performed by the sampling engine and will not affect the result of any sampling engine operation, however if these texels lie outside of defined pages in the GTT, a GTT error will result when the cache line is accessed. In order to avoid these GTT errors, “padding” at the bottom and right side of a sampling engine surface is sometimes necessary.

It is possible that a cache line will straddle a page boundary if the base address or pitch is not aligned. All pages included in the cache lines that are part of the surface must map to valid GTT entries to avoid errors. To determine the necessary padding on the bottom and right side of the surface, refer to the table in Alignment Unit Size section for the i and j parameters for the surface format in use. The surface must then be extended to the next multiple of the alignment unit size in each dimension, and all texels contained in this extended surface must have valid GTT entries.

For example, suppose the surface size is 15 texels by 10 texels and the alignment parameters are $i=4$ and $j=2$. In this case, the extended surface would be 16 by 10. Note that these calculations are done in texels, and must be converted to bytes based on the surface format being used to determine whether additional pages need to be defined.

Buffer Padding Requirements

For compressed textures (BC*, FXT1, ETC*, and EAC* surface formats), padding at the bottom of the surface is to an even compressed row. This is equivalent to a multiple of $2q$, where q is the compression block height in texels. Thus, for padding purposes, these surfaces behave as if $j = 2q$ only for surface padding purposes. The value of j is still equal to q for mip level alignment and QPitch calculation. For cube surfaces, an additional two rows of padding are required at the bottom of the surface. This must be ensured regardless of whether the surface is stored tiled or linear. This is due to the potential rotation of cache line orientation from memory to cache.

The above comments also apply to the ASTC* surface format.

For packed YUV, 96 bpt, 48 bpt, and 24 bpt surface formats, additional padding is required. These surfaces require an extra row plus 16 bytes of padding at the bottom in addition to the general padding requirements.

For linear surfaces, additional padding of 64 bytes is required at the bottom of the surface. This is in addition to the padding required above.

Programming Note	
Context:	Sampling Engine Surfaces.
For SURFTYPE_BUFFER, SURFTYPE_1D, and SURFTYPE_2D non-array, non-MSAA, non-mip-mapped surfaces in linear memory, the only padding requirement is to the next aligned 64-byte boundary beyond the end of the surface. The rest of the padding requirements documented above do not apply to these surfaces.	



Render Target and Media Surfaces

The data port accesses data (pixels) outside of the surface if they are contained in the same cache request as pixels that are within the surface. These pixels will not be returned by the requesting message, however if these pixels lie outside of defined pages in the GTT, a GTT error will result when the cache request is processed. In order to avoid these GTT errors, "padding" at the bottom of the surface is sometimes necessary.

Device2 PASID Capability Structures

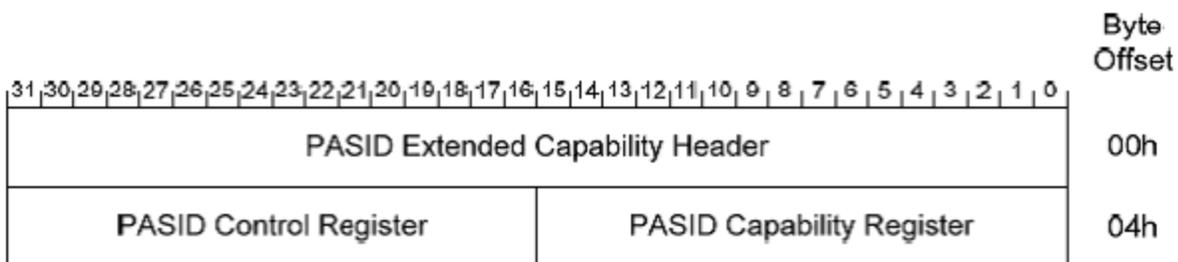
This part of the document describes the PCI-Express Extended Capability registers required on Processor Graphics (Device 2) device to enumerate Shared Virtual Memory (SVM) related capabilities.

SVM feature support on Device-2 is exposed through three distinct capability structures:

- **Process Address Space ID (PASID) Extended Capability.** PASID capability reports support for Process Address Space ID (PASID) on Device-2 compliant to PCI-Express PASID ECN.
- **Address Translation Services (ATS) Extended Capability.** ATS capability reports support for Device-TLBs on Device-2, compliant to PCI-Express ATS specification.
- **Page Request Extended Capability.** Page Request capability reports support for page-faults on Device-2, compliant to PCIExpress ATS 1.1 specification.

The following sections describe each of these capability structures and their implementation details.

PASID Extended Capability



Refer to PCI Express PASID ECN for more details.

Following sections describe the registers in the PASID Extended Capability structure.



PASID Extended Capability Header

Bits	Access	Default	Field
31:20	RO	Xh	Next Capability Offset (NCO): Offset to the next capability; Value 'X' in this field provides the offset for ATS Capability described in later sections
19:16	RO	1h	Version (V): Capability Version
15:0	RO	001Bh	Capability ID (CAPID): PASID Extended Capability ID.



PASID Capability Register

Bits	Access	Default	Field
15:13	RO	0h	Reserved.
12:8	RO	14h	<p>Maximum PASID Width (MPW): Indicates the width of the PASID field supported by the Endpoint. The value n indicates support for PASID values 0 through $2n-1$ (inclusive). The value 0 indicates support for a single PASID (0). The value 20 indicates support for all PASID values (20 bits). This field must be between 0 and 20 (inclusive).</p> <p>Processor Graphics supports PASID width of 20-bits.</p>
7:3	RO	0h	Reserved.
2	RO	1h	<p>Privilege Mode Supported (PMS): If Set, the Endpoint supports operating in privileged and non-privileged modes, and requests-with-PASID can request privileged mode.</p> <p>If Clear, the Endpoint supports operating in non-privileged mode only, and will never request privileged mode in requests-with-PASID.</p> <p>On Processor Graphics, privileged and non-privileged mode are mapped to an attribute of the advanced context. Advanced contexts created for use by user-mode applications/drivers are considered non-privileged. Advanced context created for used by kernel mode software/drivers can be treated as privileged contexts. The privilege mode maps to the user/Supervisor (U/S) privilege checking in the first-level (IA-32e) paging.</p> <p>Advanced contexts supports a privileged/non-privileged attribute (part of context-state). Software is expected to create advanced-contexts with this attribute as non-privileged, for use by user-mode drivers/applications. For advanced contexts created for use by kernel mode software/drivers, this bit is configured can be privileged. Advanced-contexts configured as non-privileged function exactly the same as advanced contexts (i.e. restricted to user-mode virtual-addresses only). Advanced contexts configured as privileged can access both user-mode and kernel-mode virtual addresses, if Supervisor Request Enable field in extended-context-entry is Set.</p>
1	RO	1h	<p>Execute Permission Supported (EPS): If Set, the Endpoint supports requests-with-PASID that request Execute permission. If Clear, the Endpoint will never request Execute permission for requests-with-PASID.</p> <p>On Processor Graphics, accesses by advanced contexts that fetch and execute graphics instructions are normally treated as requests that require execute permission. These maps to requests from GT Instruction Cache (IC) for advanced contexts.</p> <p>Advanced context accesses from Instruction Cache (IC) are checked for execute permission, if Execute Request Enable in extended-context-entry is Set.</p>
0	RO	0h	Reserved.

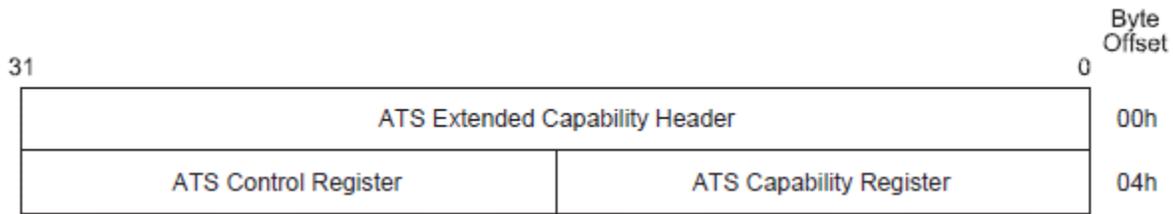


PASID Control Register

Bits	Access	Default	Field
15:3	RO	0h	Reserved.
2	R/W	0b	<p>Privilege Mode Enable (PME): When Set, the endpoint is permitted to request privileged mode in requests-with-PASID. If Clear, the Endpoint is not permitted to do so. Behavior is undefined if this bit changes value when ATS Enable field in ATS Capability is Set. If Privileged Mode Supported field in PASID Capability register is Clear, this field is treated as Reserved (0).</p> <p>Processor graphics does not use this field. Software is expected to Set this field before configuring extended-context-entry for Device-2 with Supervisor Request Enable field Set.</p> <p>For compatibility reasons, this field is implemented as RW.</p>
1	R/W	0b	<p>Execute Permission Enable (EPE): If Set, the Endpoint is permitted to request execute permission in requests-with-PASID. If Clear, the Endpoint is not permitted to do so. Behavior is undefined if this bit changes value when ATS Enable field in ATS Capability is Set. If Execute Permission Supported field in PASID Capability register is Clear, this field is treated as Reserved (0).</p> <p>Processor graphics does not use this field. Software is expected to Set this field before configuring extended-context-entry for Device-2 with Execute Request Enable field Set.</p> <p>For compatibility reasons, this field is implemented as RW.</p>
0	R/W	0b	<p>PASID Enable (PE): If Set, the Endpoint is permitted to generate requests-with-PASID. If Clear, the Endpoint is not permitted to do so. Behavior is undefined if this bit changes value when ATS Enable field in ATS Capability is Set.</p> <p>Processor Graphics does not use this field. Instead, all accesses from advanced contexts are treated as requested-with-PASID, subject to PASID-Enable field in the extended context-entry. Software is expected to Set this field before configuring extended-context entry for Device-2 with PASID Enable field Set. However, for compatibility reasons, this field is implemented as RW.</p>



ATS Extended Capability



The following sections describe the registers in the ATS Extended Capability structure.

ATS Extended Capability Header

Bits	Access	Default	Field
31:20	RO	Xh	Next Capability Offset (NCO). Offset to the next capability; Value 'X' in this field provides the offset for ATS Capability described in later sections.
19:16	RO	1h	Version (V). Capability Version.
15:0	RO	000Fh	Capability ID (CAPID). PASID Extended Capability ID.

ATS Capability Register

Bits	Access	Default	Field
15:6	RO	0h	Reserved.
5	RO	1b	Page Aligned Request (PAR). If Set, indicates the Untranslated Address is always aligned to a 4096 byte boundary. Processor graphics reports value of 1b.
4:0	RO	0h	Invalidate Queue Depth (IQD). The number of Invalidate Requests that the endpoint can accept before putting backpressure on the upstream connection. If 0h, the function can accept 32 Invalidate Requests. Processor Graphics does not use this field, and reports a value of 0h.

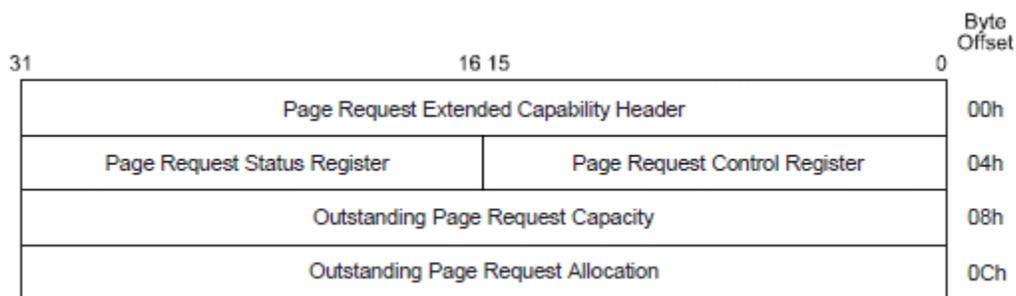
ATS Control Register

Bits	Access	Default	Field
15	R/W	0h	ATS Enable (AE). When Set, the function is enabled to cache translations. Processor graphics ignores this field, as GT uses GTLB as IOTLB, and only pretends to software that it has a Device-TLB. Software is expected to Set this field before configuring extended-context-entry for Device-2 with Page Request Enable field Set. For compatibility, this field is implemented as RW as software can read it to determine ATS enable status.
14:5	RO	0h	Reserved.



Bits	Access	Default	Field
4:0	RW	0h	<p>Smallest Translation Unit (STU). This value indicates to the Endpoint the minimum number of 4096-byte blocks that is indicated in a Translation Completion or Invalidate Request. This is a power of 2 multiple and the number of blocks is 2^{STU}. A value of 0h indicates one block and value of 1F indicates 2³¹ blocks.</p> <p>Processor graphics does not use this field, and reports a value of 0h indicating it uses 4KB as the smallest translation unit (smallest page-size).</p>

Page Request Extended Capability



The following register descriptions define the requirement.

Page Request Extended Capability Header

Bits	Access	Default	Field
31:20	RO	0h	Next Capability Offset (NCO): Offset to the next capability; Value 'X' in this field provides the offset for ATS Capability described in later sections
19:16	RO	1h	Version (V): Capability Version
15:0	RO	0013h	Capability ID (CAPID): PASID Extended Capability ID.



Page Request Control Register

Bits	Access	Default	Field
15:2	RO	0h	Reserved.
1	RO	0	Reset (RST): When the Enable field is clear, or is being cleared in the same register update that sets this field, writing a 1b to this field, clears the associated implementation dependent page request credit counter and pending request state for the associated Page Request Interface. No action is initiated if this field is written to 0b or if this field is written with any value while the PRE field is Set. Read of this field return 0b. Processor graphics does not use this field, and implements it as read-only (0).
0	RW	0h	Page Request Enable (PRE): When Set, indicates that the page request interface on the endpoint is allowed to make page requests. If both this field and the Stopped field in Page Request Status register are Clear, then the page request interface will not issue new page requests, but has outstanding page requests for which page responses is not yet received. When this field transitions from 0 to 1, all the status fields in the Page-Request Status register are cleared. Enabling a page request interface that has not successfully stopped has indeterminate results. Processor graphics ignores this field, as GT uses GTLB as IOTLB, and only pretends to software that it has a Device-TLB. For compatibility, this field is implemented as RW as software can read it to determine Page- Request enable status. Software is expected to Set this field before configuring extended-context-entry for Device-2 with Page Request Enable field Set. Software is expected to respond to all page requests in the page-request queue before Clearing this field.



Page Request Status Register

Bits	Access	Default	Field
15:9	RO	0h	Reserved.
8	RO	0	<p>Stopped (S): When this field is Set, the associated page request interface has stopped issuing additional page requests and that all previously issued Page Requests have completed. When this field is Clear the associate page request interface either has not stopped or has stopped issuing new Page Requests but has outstanding Page Requests. This field is only meaningful if Enable is Clear. If Enable is Set, this field is undefined. When the Enable field is Cleared, after having been previously Set, the interface transitions to the stopping state and Clears this field. After all page requests currently outstanding at the function have received responses, this field is Set and the interface enters the disabled state. If there were no outstanding page requests, this field may be Set immediately when Enable is Cleared. Resetting the interface causes an immediate transition to the disabled state. While in the stopping state, receipt of a Response Failure message results in the immediate transition to the disabled state (Setting this field).</p> <p>Processor Graphics has no direct use of this field. For compatibility reasons, this field is Set when Page-Request Enable (PRE) field in the Page-request Control register transitions from 1 to 0. When PRE transtions from 0 to 1, this field is Cleared.</p>
7:2	RO	0h	Reserved.
1	RW1C	0h	<p>Unexpected Page Request Group Index (UPGRI): When Set, indicates the function received a PRG response message containing a PRG index that has no matching request. A response failure. This field is Set by the Function and cleared when 1b is written to this field.</p> <p>Processor graphics Sets this field when it receives a <i>page_grp_resp_dsc</i> with PRG Index that does not match PRG index in any outstanding <i>page_grp_req_dsc</i>. Such a <i>page_grp_resp_dsc</i> is ignored. When Page- Request Enable (PRE) field in the Pagerequest Control register transtions from 0 to 1, this field is Cleared.</p>
0	RW1C	0h	<p>Response Failure (RF): When Set, indicates the function received a PRG response message indicating a response failure. The function expects no further response from the host (any received are ignored). This field is Set by the Function and cleared when 1b is written to this field.</p> <p>Processor graphics Sets this field when it receives a <i>page_grp_resp_dsc</i> or <i>page_stream_resp_dsc</i> with Response Code of Response Failure (1111b). The advanced context corresponding to the PASID in such response is terminated with error. When Page-Request Enable (PRE) field in the Page request Control register transitions from 0 to 1, this field is Cleared.</p> <p>HW writes 1 to this bit if it gets a failing page response.</p>



Outstanding Page Request Capacity

Bits	Access	Default	Field
31:0	RO	8000h	<p>Outstanding Page Request Capacity (OPRC): This register contains the number of outstanding page request messages the associated Page Request Interface physically supports. This is the upper limit on the number of pages that can be usefully allocated to the Page Request Interface.</p> <p>Processor Graphics device does not use this field.</p>

Outstanding Page Request Allocation

Bits	Access	Default	Field
31:0	RO	0h	<p>Outstanding Page Request Allocation (OPRC): This register contains the number of outstanding page request messages the associated Page Request Interface is allowed to issue (have outstanding at any given instance).</p> <p>Processor Graphics device does not use this field. Software is required to program this field with value $2^{(X+8)}$, where X is the value in Queue Size (QS) field in the Page Request Queue Address register. For compatibility reasons, this field is implemented as RW.</p>



Atomics for Page Table Updates (MSQD)

The following atomics are added to GTI just for page table management and only needed by GAM to perform proper page walks:

The Following Atomics are only applicable in GTI and used for Page Walks.

Privilege and Instruction Access checks are not part of previous GPUs.

R/W => Bit[0]

Extended Access required => Bit[1]

Write Protect Enable => Bit[2]

Intermediate Entry => Bit[3]

Atomic Operation	Opcode	Description	New Destination Value	Applicable	Return Value (Optional)
Atomic_Page_update_0000	1100_0000	Read Access Extended Access bit is disabled Write Protection is disabled Final PTE	Set bit[5] if not set		new_dst
Atomic_Page_update_0001	1100_0001	Write Access Extended Access bit is disabled Write Protection is disabled Final PTE	Set bit[5,6] if not set		new_dst
Atomic_Page_update_0010	1100_0010	Read Access Extended Access bit is enabled Write Protection is disabled Final PTE	Set bit[5,10] if not set		new_dst



Atomic_Page_update_0011	1100_0011	Write Access Extended Access bit is enabled Write Protection is disabled Final PTE	Set bit[5,6,10] if not set		new_dst
Atomic_Page_update_0100	1100_0100	Read Access Extended Access bit is disabled Write Protection is enabled Final PTE	Set bit[5] if not set		new_dst
Atomic_Page_update_0101	1100_0101	Write Access Extended Access bit is disabled Write Protection is enabled Final PTE	Set bit[5,6] if not set		new_dst
Atomic_Page_update_0110	1100_0110	Read Access Extended Access bit is enabled Write Protection is enabled Final PTE	Set bit[5,10] if not set		new_dst
Atomic_Page_update_0111	1100_0111	Write Access Extended Access bit is enabled Write Protection is enabled Final PTE	Set bit[5,6,10] if not set		new_dst



Atomic_Page_update_1000	1100_1000	Read Access Extended Access bit is disabled Write Protection is disabled Intermediate Paging Entry	Set bit[5] if not set		new_dst
Atomic_Page_update_1001	1100_1001	Write Access Extended Access bit is disabled Write Protection is disabled Intermediate Paging Entry	Set bit[5,6] if not set		new_dst
Atomic_Page_update_1010	1100_1010	Read Access Extended Access bit is enabled Write Protection is disabled Intermediate Paging Entry	Set bit[5,10] if not set		new_dst
Atomic_Page_update_1011	1100_1011	Write Access Extended Access bit is enabled Write Protection is disabled Intermediate Paging Entry	Set bit[5,6,10] if not set		new_dst
Atomic_Page_update_1100	1100_1100	Read Access Extended Access bit is disabled Write Protection is enabled Intermediate Paging Entry	Set bit[5] if not set		new_dst



Atomic_Page_update_1101	1100_1101	Write Access Extended Access bit is disabled Write Protection is enabled Intermediate Paging Entry	Set bit[5,6] if not set		new_dst
Atomic_Page_update_1110	1100_1110	Read Access Extended Access bit is enabled Write Protection is enabled Intermediate Paging Entry	Set bit[5,10] if not set		new_dst
Atomic_Page_update_1111	1100_1111	Write Access Extended Access bit is enabled Write Protection is enabled Intermediate Paging Entry	Set bit[5,6,10] if not set		new_dst

Implementation

NOTE: Gen8 dropped the Execution privilege and Supervisor/User flag support. The following atomics are simplified for gen8 but need to be updated for gen9.

Atomic_Page_update_0000:

This paging walk is started on a READ access where the extended access bits in the context is disabled and write protection is disabled. This is the final Page Table Entry.

ALU Decision:

1. If No-Page fault:
 - Is the A-bit (bit5) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.



2. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".

Atomic_Page_update_0001:

This paging walk is started on a WRITE access where the extended access bits in the context is disabled and write protection is disabled. This is the final Page Table Entry.

ALU Decision:

1. If No-Page fault:
 - Is the A-bit (bit5) and D-bit (bit6) set:
 - i. If both set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/D-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".

Atomic_Page_update_0010:

This paging walk is started on a READ access where the extended access bits in the context is enabled and write protection is disabled. This is the final Page Table Entry.

ALU Decision:

1. If No-Page fault:
 - Is the A-bit (bit5) and EA-bit (bit10) set:
 - i. If both set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/EA-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".



Atomic_Page_update_0011:

This paging walk is started on a WRITE access where the extended access bits in the context is enabled and write protection is disabled. This is the final Page Table Entry.

ALU Decision:

1. If No-Page fault:
 - Is the A-bit (bit5) and EA-bit (bit10) and D-bit (bit6) set:
 - i. If all set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/D/EA-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".

Atomic_Page_update_0100:

This paging walk is started on a READ access where the extended access bits in the context is disabled and write protection is enabled. This is the final Page Table Entry.

ALU Decision:

1. If No-Page fault:
 - Is the A-bit (bit5) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".



Atomic_Page_update_0101:

This paging walk is started on a WRITE access where the extended access bits in the context is disabled and write protection is enabled. This is the final Page Table Entry.

ALU Decision:

1. If Page is present and Writes are allowed:
 - Is the A-bit (bit5) and D-bit (bit6) set:
 - i. If both set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/D-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page is present and Writes are not allowed:
 - Is the A-bit (bit5) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
3. If Page is not present:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision:

- If bit[0] of the QW of interest is "0" => Page not present.
- If bit[1] of the QW of interest is "0" => Write permission fault.



Atomic_Page_update_0110:

This paging walk is started on a READ access where the extended access bits in the context is enabled and write protection is enabled. This is the final Page Table Entry.

ALU Decision:

1. If No-Page fault:
 - Is the A-bit (bit5) and EA-bit (bit10) set:
 - i. If both set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/EA-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".



Atomic_Page_update_0111:

This paging walk is started on a WRITE access where the extended access bits in the context is enabled and write protection is enabled. This is the final Page Table Entry.

ALU Decision:

1. If Page is present and Writes are allowed:
 - Is the A-bit (bit5) and EA-bit (bit10) and D-bit (bit6) set:
 - i. If all set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/EA/D-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page is present and Writes are not allowed:
 - Is the A-bit (bit5) and EA-bit (bit10) set:
 - i. If both set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A/EA-bit set, write to memory and return new-dest to GAM and end atomic.
3. If Page is not present:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0" or bit[1] of the QW of interest is "0".



Atomic_Page_update_1000:

This paging walk is started on a READ access where the extended access bits in the context is disabled and write protection is disabled. This is an intermediate page table entry.

ALU Decision:

1. If No-Page fault:
 - Is the A-bit (bit5) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".



Atomic_Page_update_1001:

This paging walk is started on a WRITE access where the extended access bits in the context is disabled and write protection is disabled. This is an intermediate page table entry.

ALU Decision:

1. If No-Page fault & 1GB/2MB Page:
 - Is the A-bit (bit5) and D-bit (bit6) set:
 - i. If both set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/D-bit set, write to memory and return new-dest to GAM and end atomic.
2. If No-Page fault & Not 1GB/2MB Page:
 - Is the A-bit (bit5) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
3. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".

1GB/2MB Decision: It is a 1GB/2MB page if bit[7] of the intermediate walk entry is "1".



Atomic_Page_update_1010:

This paging walk is started on a READ access where the extended access bits in the context is enabled and write protection is disabled. This is an intermediate page table entry.

ALU Decision:

1. If No-Page fault:
 - Is the A-bit (bit5) and EA-bit (bit10) set:
 - i. If both set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/EA-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".



Atomic_Page_update_1011:

This paging walk is started on a WRITE access where the extended access bits in the context is enabled and write protection is disabled. This is an intermediate page table entry.

ALU Decision:

1. If No-Page fault & 1GB/2MB Page:
 - Is the A-bit (bit5) and EA-bit (bit10) and D-bit (bit6) set:
 - i. If all set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/D/EA-bit set, write to memory and return new-dest to GAM and end atomic.
2. If No-Page fault & Not 1GB/2MB Page:
 - Are the A-bit (bit5) and EA-bit (bit10) set:
 - i. If both set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither not set, modify the old-dest with A/EA-bit set, write to memory and return new-dest to GAM and end atomi
3. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".

1GB/2MB Decision: It is a 1GB/2MB page if bit[7] of the intermediate walk entry is "1".



Atomic_Page_update_1100:

This paging walk is started on a READ access where the extended access bits in the context is disabled and write protection is enabled. This is an intermediate page table entry.

ALU Decision:

1. If No-Page fault:
 - Is the A-bit (bit5) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".



Atomic_Page_update_1101:

This paging walk is started on a WRITE access where the extended access bits in the context is disabled and write protection is enabled. This is an intermediate page table entry.

ALU Decision:

1. If Page is present (1) & Writes are allowed (1) & 1GB/2MB Page (1):
 - Is the A-bit (bit5) and D-bit (bit6) set:
 - i. If all set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/D -bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page is present (1) and Writes are not allowed (0) & 1GB/2MB Page (1):
 - Is the A-bit (bit5) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
3. If Page is present (1) and Writes are allowed (1) & 1GB/2MB Page (0):
 - Is the A-bit (bit5) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
4. If Page is present (1) and Writes are not allowed (0) & 1GB/2MB Page (0):
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.
5. If Page is not present:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision:

- If bit[0] of the QW of interest is "0" => Page not present.
- If bit[1] of the QW of interest is "0" => Write permission fault.

1GB/2MB Decision: It is a 1GB/2MB page if bit[7] of the intermediate walk entry is "1".



Atomic_Page_update_1110:

This paging walk is started on a READ access where the extended access bits in the context is enabled and write protection is enabled. This is an intermediate page table entry.

ALU Decision:

1. If No-Page fault:
 - Is the A-bit (bit 5) and EA-bit (bit 10) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A/EA-bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision: It is page fault, if bit[0] of the QW of interest is "0".



Atomic_Page_update_1101:

This paging walk is started on a WRITE access where the extended access bits in the context is disabled and write protection is enabled. This is an intermediate page table entry.

ALU Decision:

1. If Page is present (1) & Writes are allowed (1) & 1GB/2MB Page (1):
 - Is the A-bit (bit5) and EA-bit (bit10) and D-bit (bit6) set:
 - i. If all set, return the PTE to GAM and end-atomic (no writes).
 - ii. If neither one of them set, modify the old-dest with A/D -bit set, write to memory and return new-dest to GAM and end atomic.
2. If Page is present (1) and Writes are not allowed (0) & 1GB/2MB Page (1):
 - Is the A-bit (bit5) and EA-bit (bit10) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A/EA-bit set, write to memory and return new-dest to GAM and end atomic.
3. If Page is present (1) and Writes are allowed (1) & 1GB/2MB Page (0):
 - Is the A-bit (bit5) and EA-bit (bit10) set:
 - i. If set, return the PTE to GAM and end-atomic (no writes).
 - ii. If not set, modify the old-dest with A/EA-bit set, write to memory and return new-dest to GAM and end atomic.
4. If Page is present (1) and Writes are not allowed (0) & 1GB/2MB Page (0):
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.
5. If Page is not present:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault Decision:

- If bit[0] of the QW of interest is "0" => Page not present.
- If bit[1] of the QW of interest is "0" => Write permission fault.

1GB/2MB Decision: It is a 1GB/2MB page if bit[7] of the intermediate walk entry is "1".



Atomic_A_update_000:

Read access from a user context and a non-instruction space.

1. If no-page fault:
 - Is the A-bit (bit5) set:
 - i. If set, just return the PTE to GAM and end-atomic.
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
2. If page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault decision: It is page fault, if bit[0] of the QW of interest is "0", OR if bit[2]=0.

Implementation: The behavior should be exactly same as Atomic A update 010.



Atomic_A_update_001:

Read access from a user context and an instruction space.

1. If no-page fault:
 - Is the A-bit (bit5) set:
 - i. If set, just return the PTE to GAM and end-atomic.
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
2. If page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault decision: It is page fault, if bit[0] of the QW of interest is "0" OR bit[63]=1 OR if bit[2]=0.

Implementation: The behavior should be exactly same as Atomic A update 010.



Atomic_A_update_010:

Read access from a supervisor context and an non-instruction space.

1. If no-page fault:
 - Is the A-bit (bit5) set:
 - i. If set, just return the PTE to GAM and end-atomic.
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
2. If page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault decision: It is page fault, if bit[0] of the QW of interest is "0".

Implementation: Identical to what is described here.



Atomic_A_update_011:

Read access from a supervisor context and an instruction space.

1. If no-page fault:
 - Is the A-bit (bit5) set:
 - i. If set, just return the PTE to GAM and end-atomic.
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
2. If page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault decision: It is page fault, if bit[0] of the QW of interest is "0" OR if bit[63]=1 OR if bit[2]=1.

Implementation: The behavior should be exactly same as Atomic A update 010.



Atomic_A_update_100:

Read access from a supervisor context and an instruction space and can be executed from supervisor or user pages.

1. If no-page fault:
 - Is the A-bit (bit5) set:
 - i. If set, just return the PTE to GAM and end-atomic.
 - ii. If not set, modify the old-dest with A-bit set, write to memory and return new-dest to GAM and end atomic.
2. If page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault decision: It is page fault, if bit[0] of the QW of interest is "0" OR bit[63]=1.

Implementation: The behavior should be exactly same as Atomic A update 010.



Atomic_AD_update_101:

Write access from a user context and a non-instruction space.

1. If no-page fault:
 - Is the A-bit (bit5) set:
 - i. If set, is the D-bit (bit6) set:
 - A. If set, just return the PTE to GAM and end the atomic.
 - B. If not set, modify the old-dest with D-bit set, write to memory and return new-dest to GAM and end atomic.
 - ii. If not set, modify the old-dest with A and D-bit set, write to memory and return the new-dest to GAM and end atomic.
2. If page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well

Page Fault decision: It is page fault, if bit[0] of the QW of interest is "0", OR if bit[2]=0 OR if bit[1]=0.

Implementation: The behavior should be exactly same as Atomic A update 110.



Atomic_AD_update_110:

Write access from a supervisor context and an non-instruction space.

1. If no-page fault:
 - Is the A-bit (bit5) set:
 - i. If set, is the D-bit (bit6) set:
 - A. If set, just return the PTE to GAM and end the atomic.
 - B. If not set, modify the old-dest with D-bit set, write to memory and return new-dest to GAM and end atomic
 - ii. If not set, modify the old-dest with A and D-bit set, write to memory and return the new-dest to GAM and end atomic.
2. If page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault decision: It is page fault, if bit[0] of the QW of interest is "0" OR bit[1]=0.

Implementation: Identical to what is described here.



Atomic_AD_update_111:

Write access from a supervisor context and a non-instruction space and RO is don't care.

1. If no-page fault:
 - Is the A-bit (bit5) set:
 - i. If set, is the D-bit (bit6) set:
 - A. If set, just return the PTE to GAM and end the atomic.
 - B. If not set, modify the old-dest with D-bit set, write to memory and return new-dest to GAM and end atomic.
 - ii. If not set, modify the old-dest with A and D-bit set, write to memory and return the new-dest to GAM and end atomic.
2. If page fault:
 - Return old-dest to GAM which will lead to GAM detecting the fault as well.

Page Fault decision: It is page fault, if bit[0] of the QW of interest is "0" OR bit[63]=1.

Implementation: The behavior should be to ignore bit[63] in the above proposed mechanism. The behavior should be exactly same as Atomic A update 110.



Atomic Operations between GPU and IA

IA cores are capable of doing atomic operations on any memory space defined as part of their page tables, MTRRs, and PAT. The core detects the memory type after applying all the checks, and if the end target is within WB space, it uses the optimized MESI protocol (i.e. RFO, WB) to complete the atomic operation. If the memory space is UC/WC/WT, it uses the bus lock to honor the atomic requirements.

GPUs are only capable of doing atomics via optimized MESI protocols; they do not have a mechanism to do bus locking. This restricts atomic operations to WB space if they happened to be between GPU and IA cores. We cannot guarantee the atomicity for UC/WC/WT.

There are multiple ways how GPU can handle atomics to non-WB space.

1. **Ignore the Memory Type:** GPU ignores the memory type for the atomic operation and performs it via RFO/WBMTol as if the space is WB.
If IA is relying on the LOCK for the same atomic, LOCK keeps the GPU off the bus for integrated solutions. And if GPU has the ownership of the line, a LOCKed read from IA still evicts the line from GT even if the IA has the line as UC/WT/WC in its memory space.
2. **Report as an error and fail the cycle:** GPU detects the mismatch and handles the cycle as error (i.e. write has no affect and read returns garbage) and reports the error as catastrophic to SW. App can be terminated by SW.
3. **Perform Bus Lock:** Similar to IA cores, GPU can support bus locks around atomic operations to UC/WT/WC spaces. However the initial implementations of shared atomic implementations do not have this option in GPU hardware.

Option#2 is the main mode where GPU is not expecting atomics to UC/WT/WC space and any such accesses are faulted as HW cannot guarantee the atomicity of the operation with the current implementation.